

Line Integration For Rendering Heterogenous Emissive Volumes

Florian Simon, Johannes Hanika, Tobias Zirr, Carsten Dachsbacher



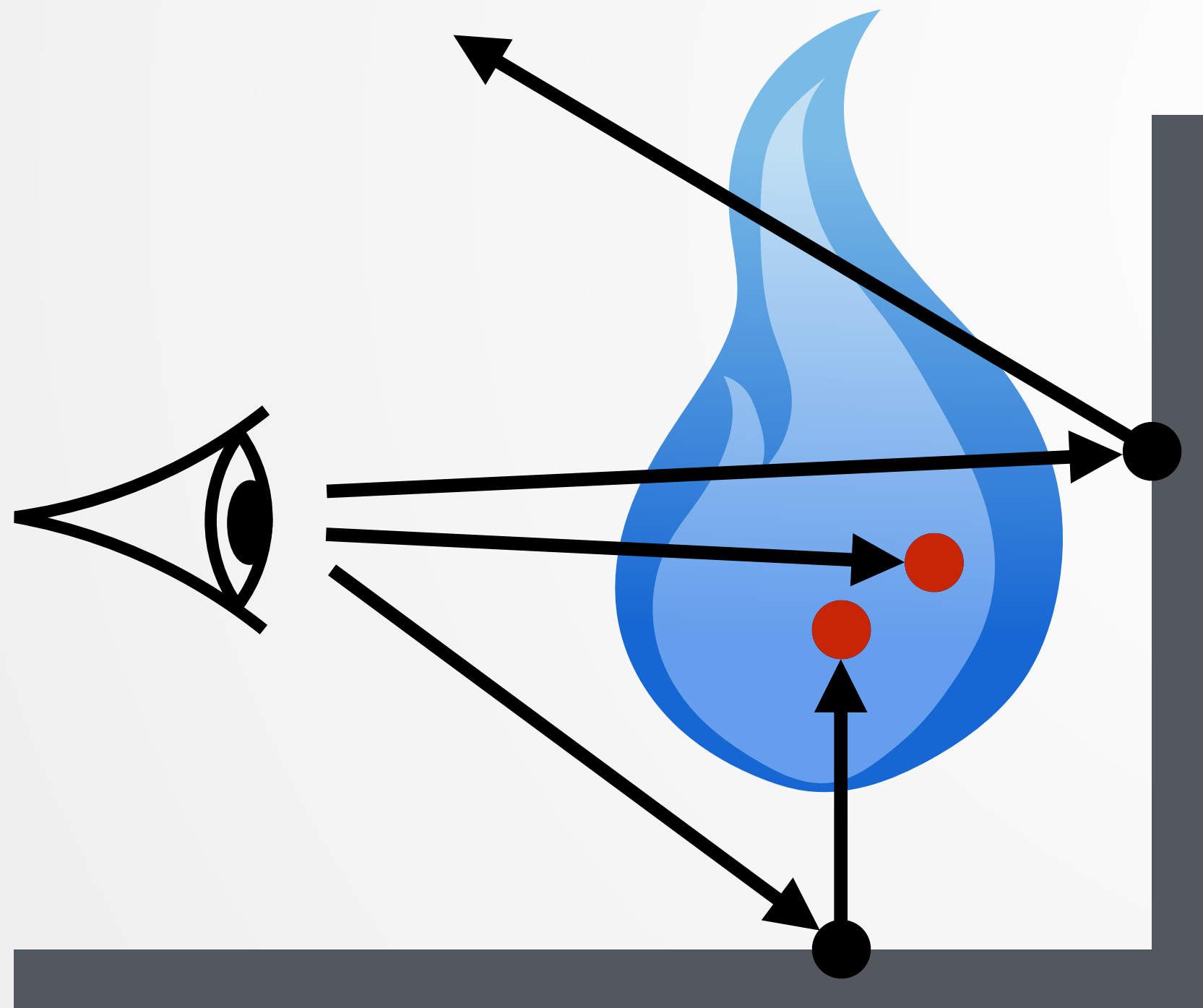






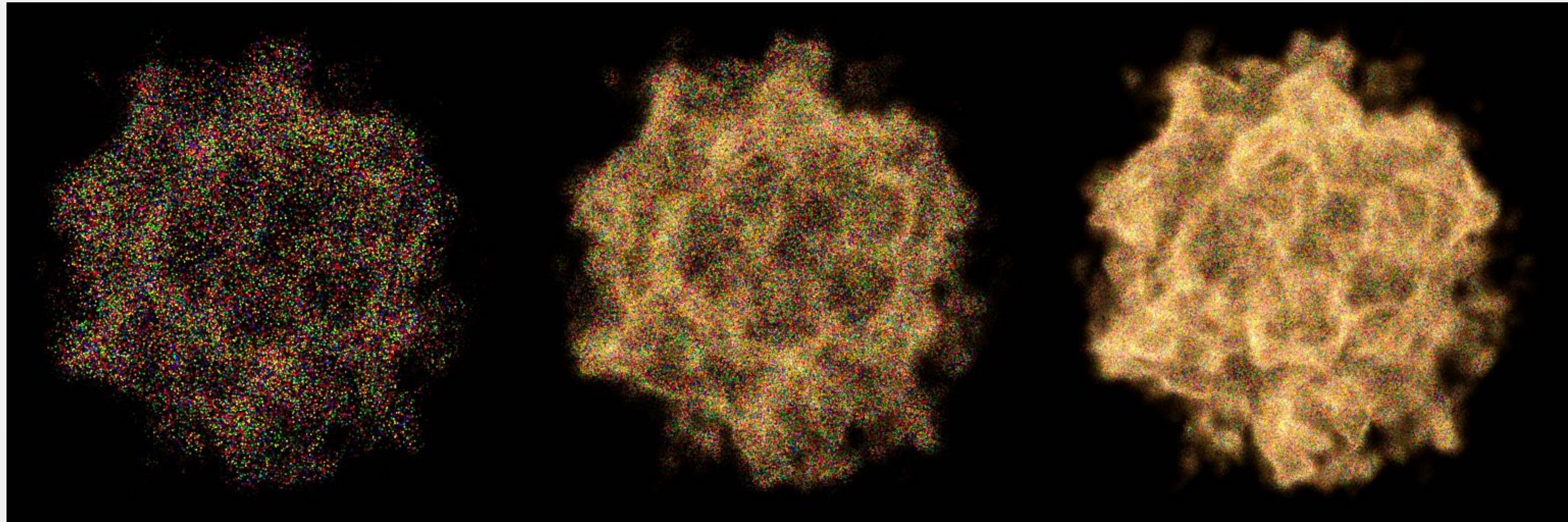
The Idea

- Path tracing evaluates volumetric emission only at points



The Idea

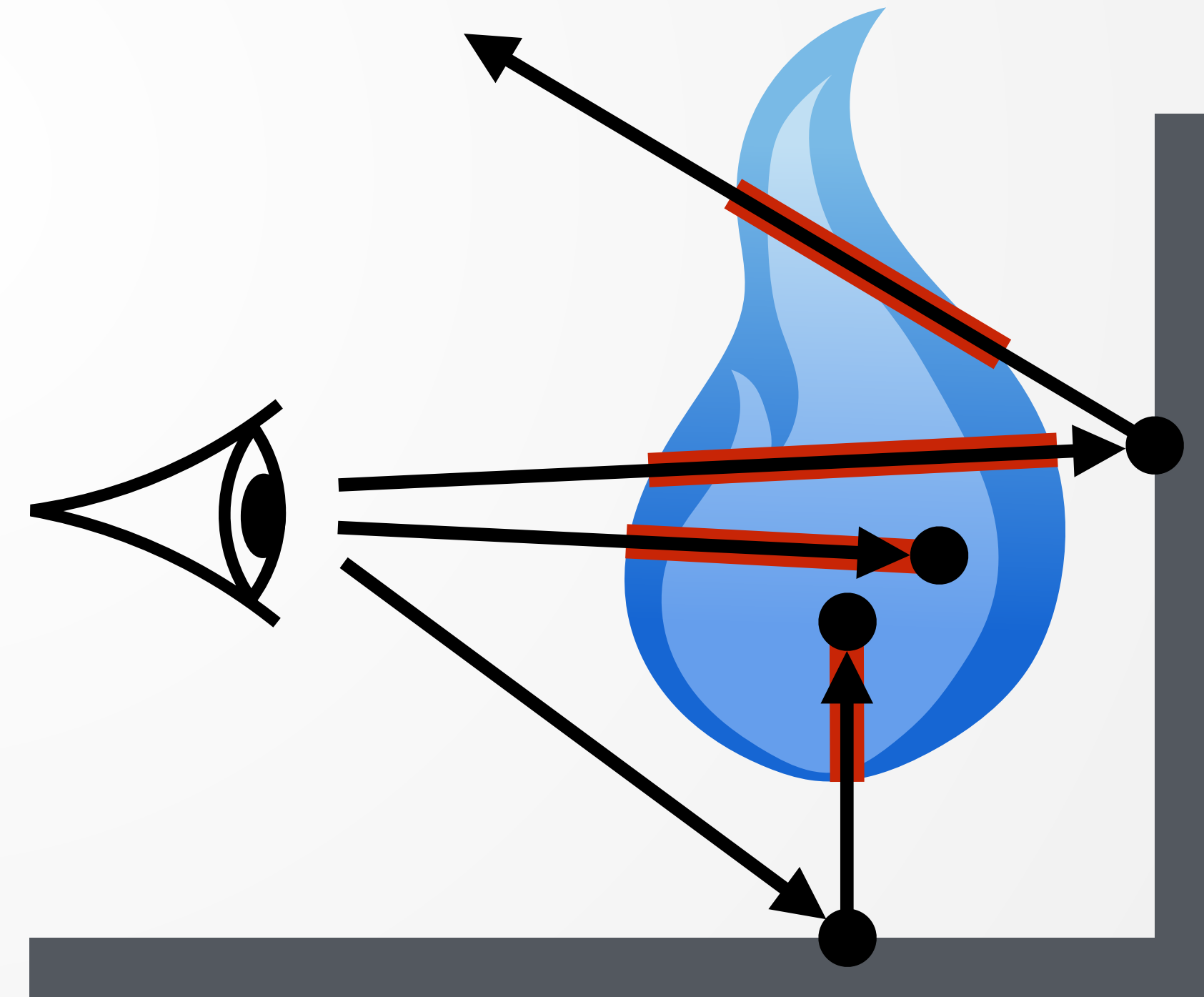
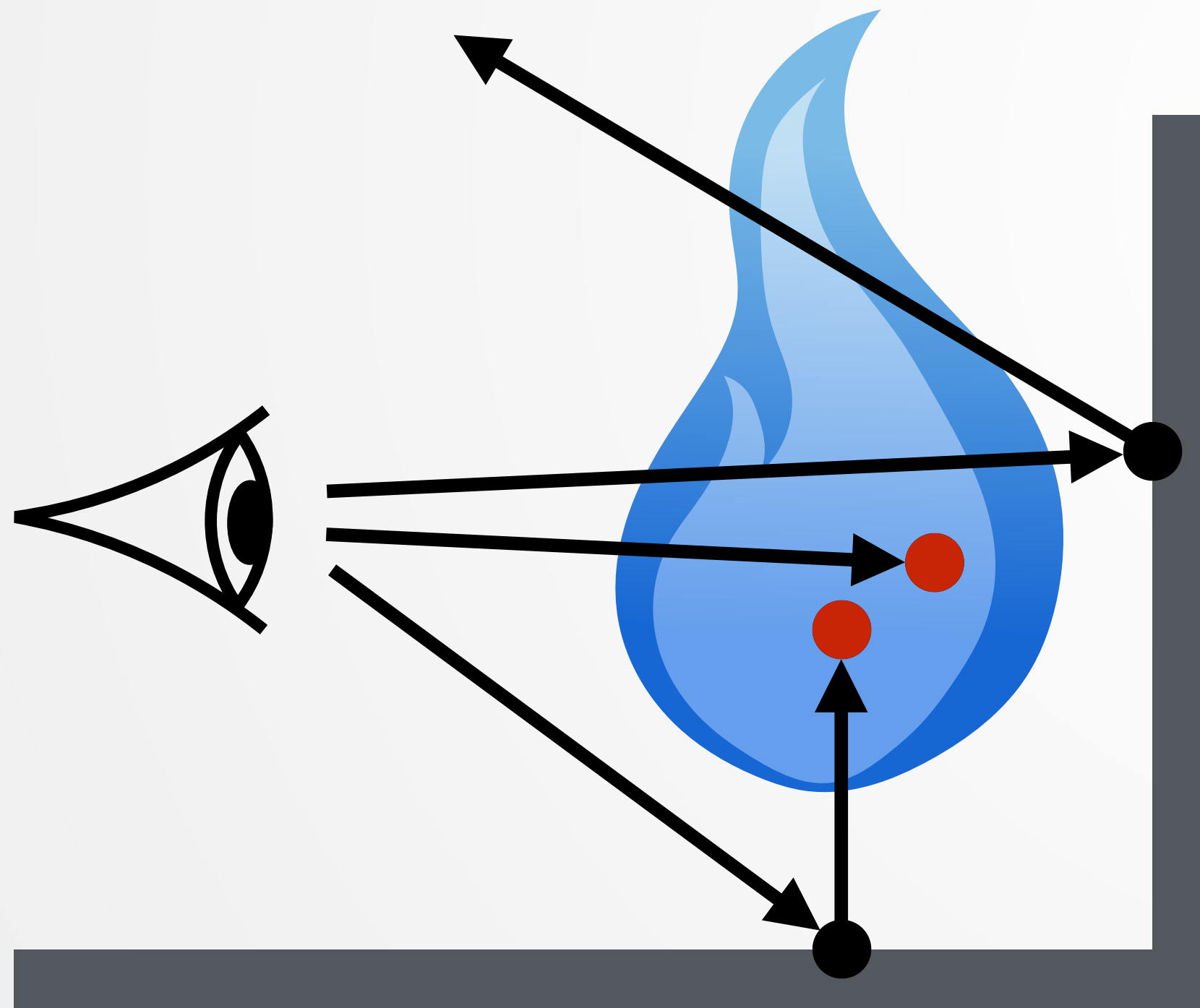
- Path tracing evaluates volumetric emission only at points



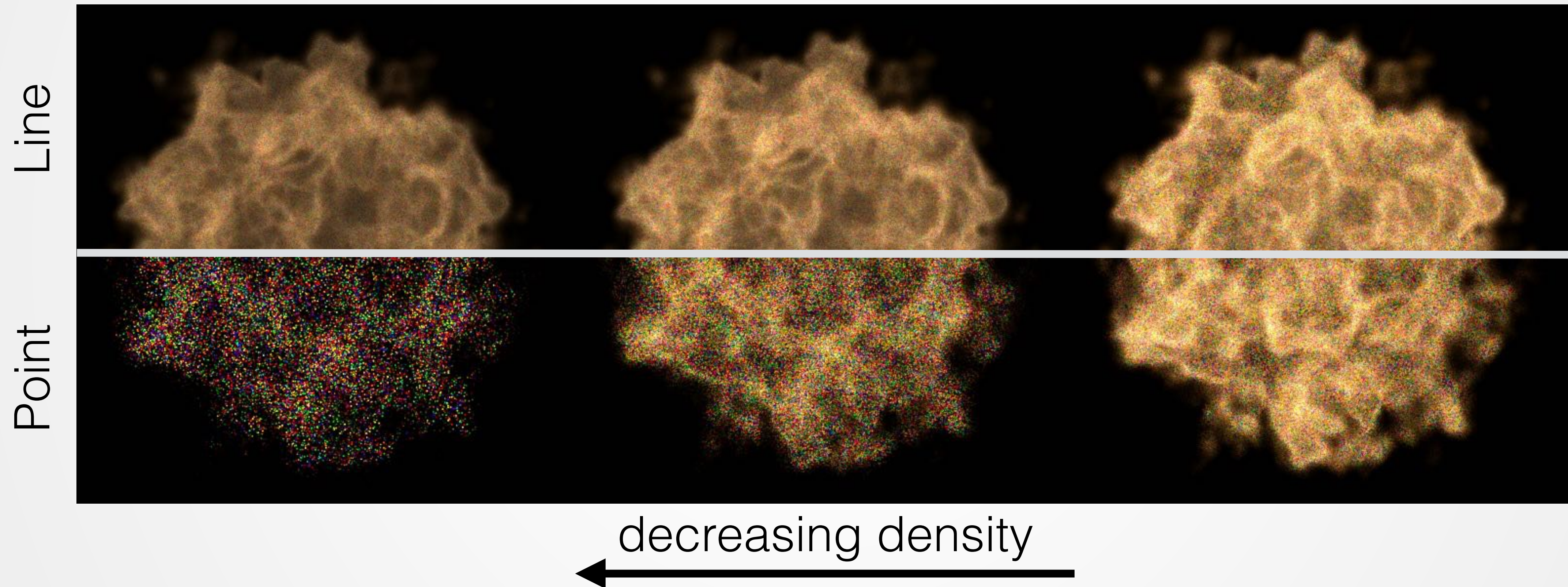
← decreasing density

The Idea

- Path tracing evaluates volumetric emission only at points
- Line Integration extends this to emission of segments

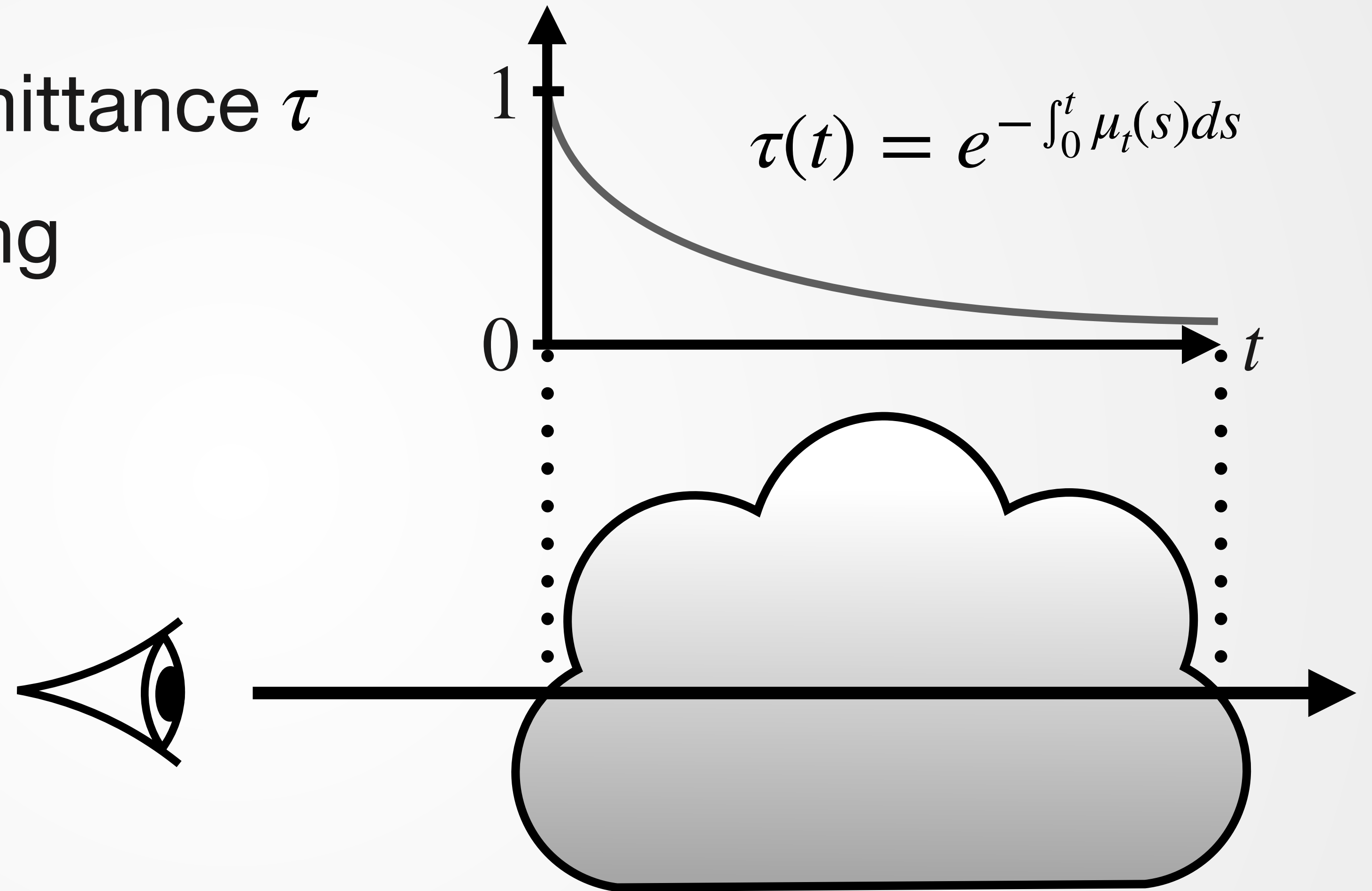


Line Integration



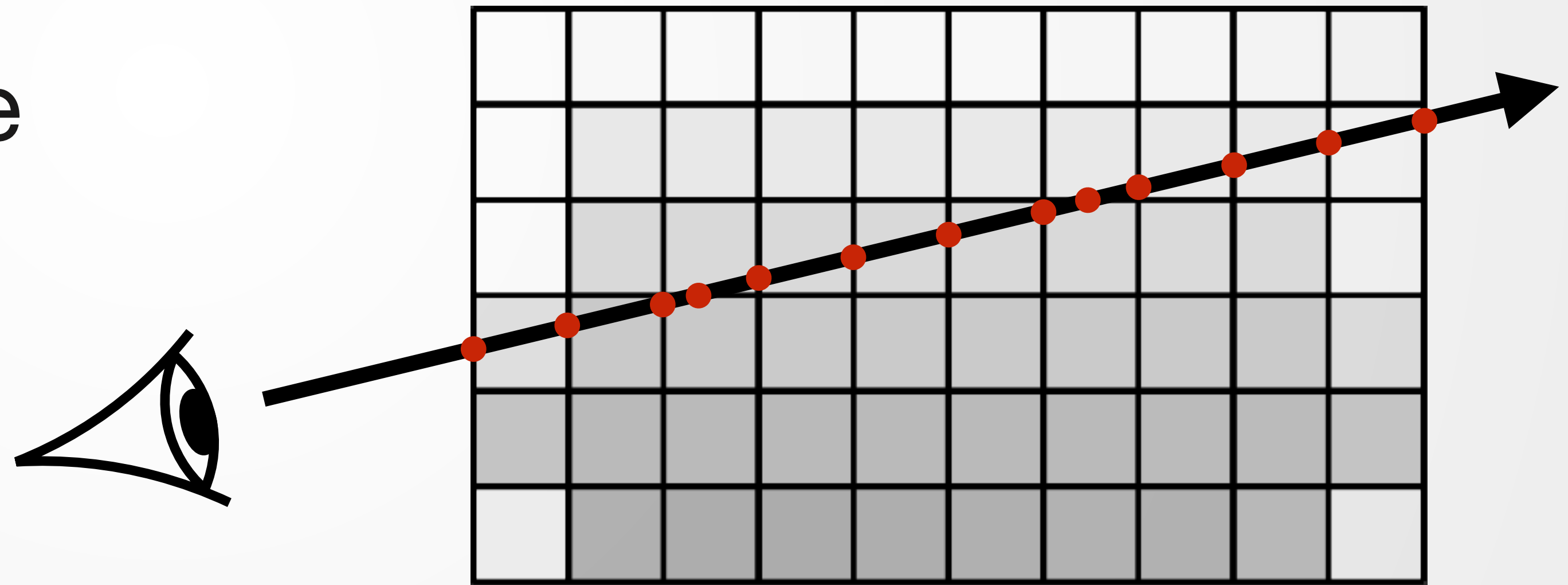
Free Path Sampling

- Proportional to transmittance τ
- Delta/Residual Tracking
 - Szirmay-Kalos et al. 2011
 - Kutz et al. 2017
- Regular Tracking



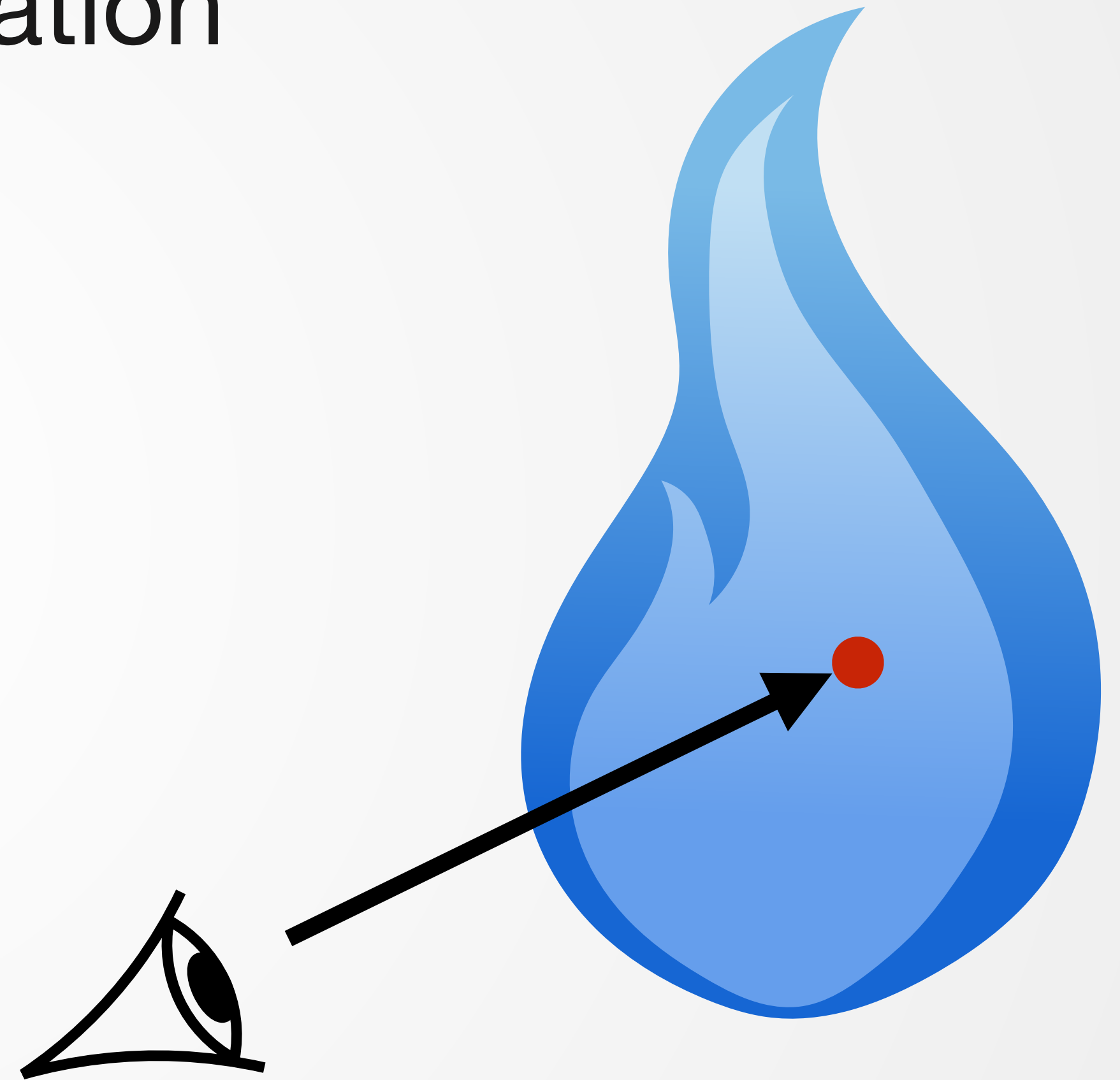
Regular Tracking

- Piecewise constant volume
- Step from voxel to voxel
- Integrate transmittance
- Stop when transmittance below random threshold



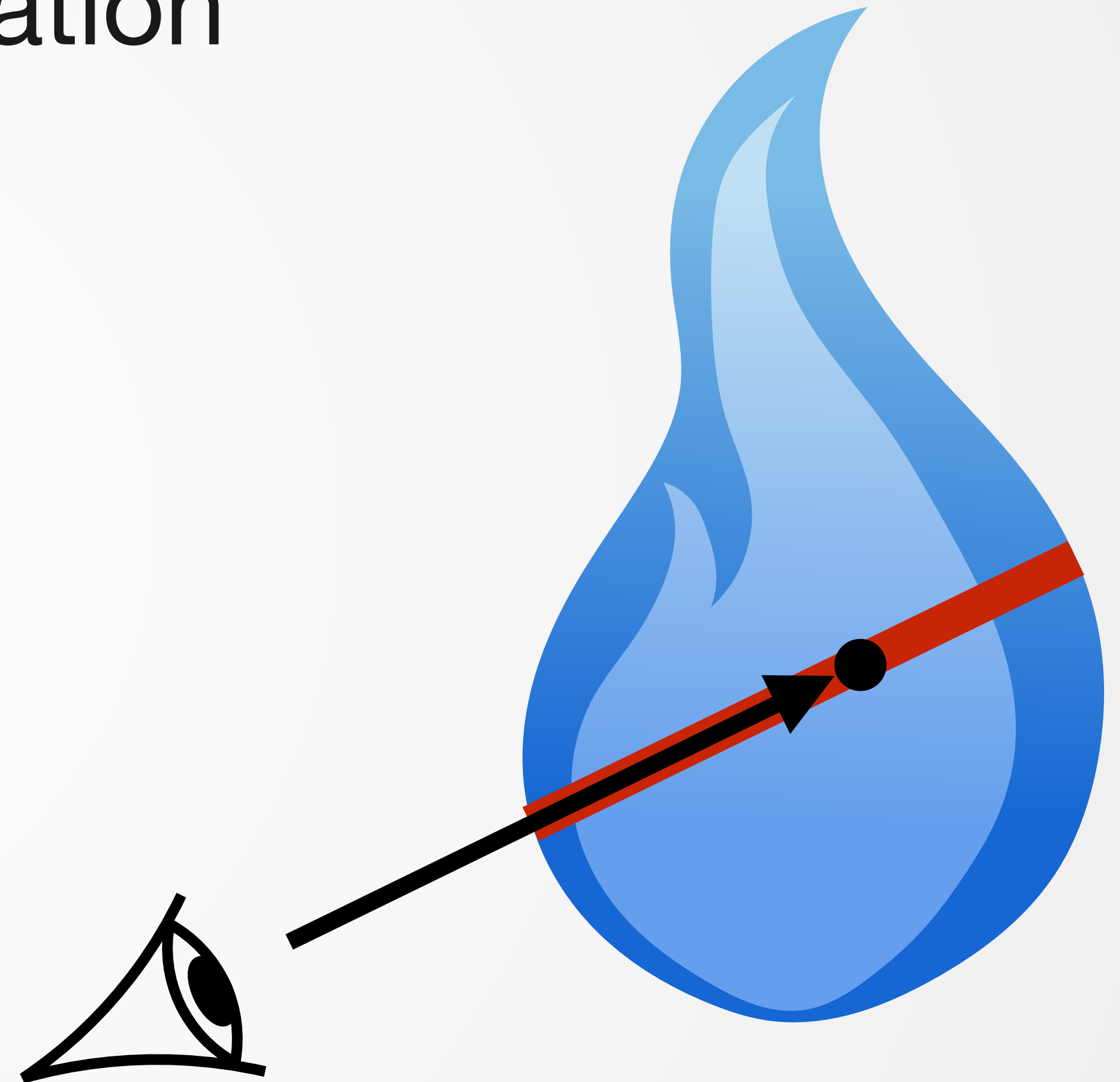
Handling Emission

- At scattering events = point integration



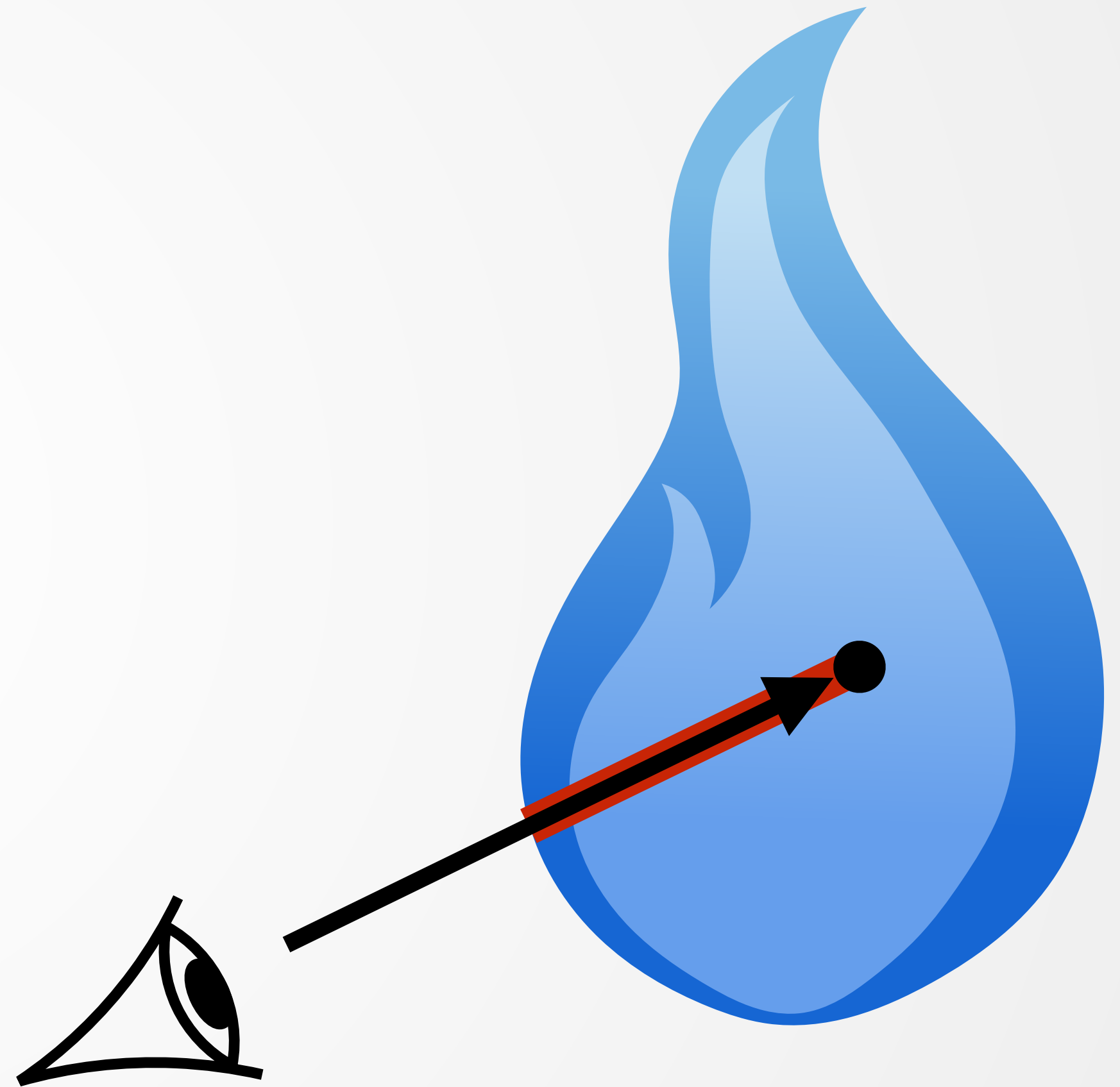
Handling Emission

- At scattering events = point integration
- Alternative:
 - Deterministic integration of emission
 - Inefficient for dense volumes
 - MIS with next event estimation?
(more on that later)



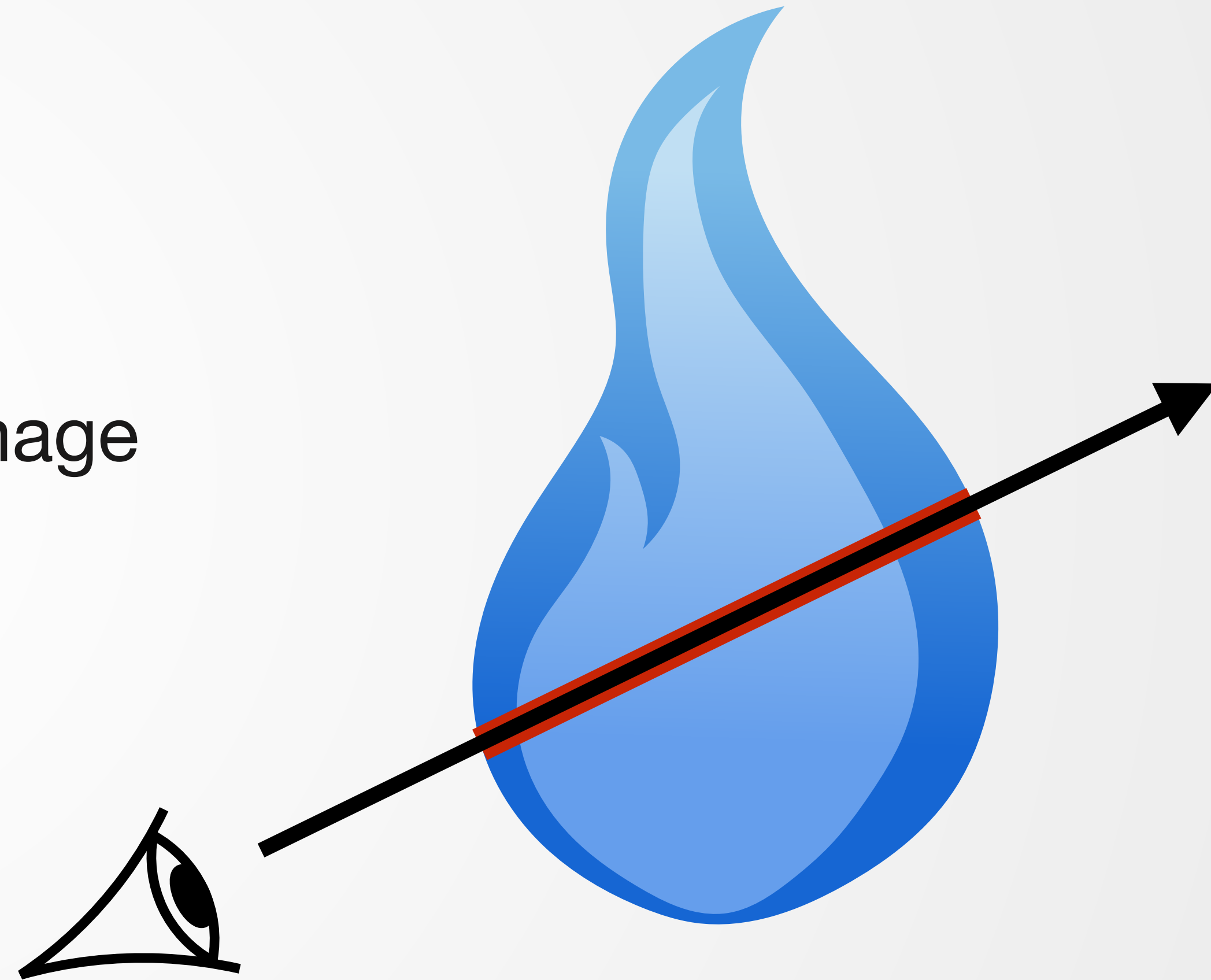
Line Integration

- Integrate emission only up to scattering event
- Advantages:



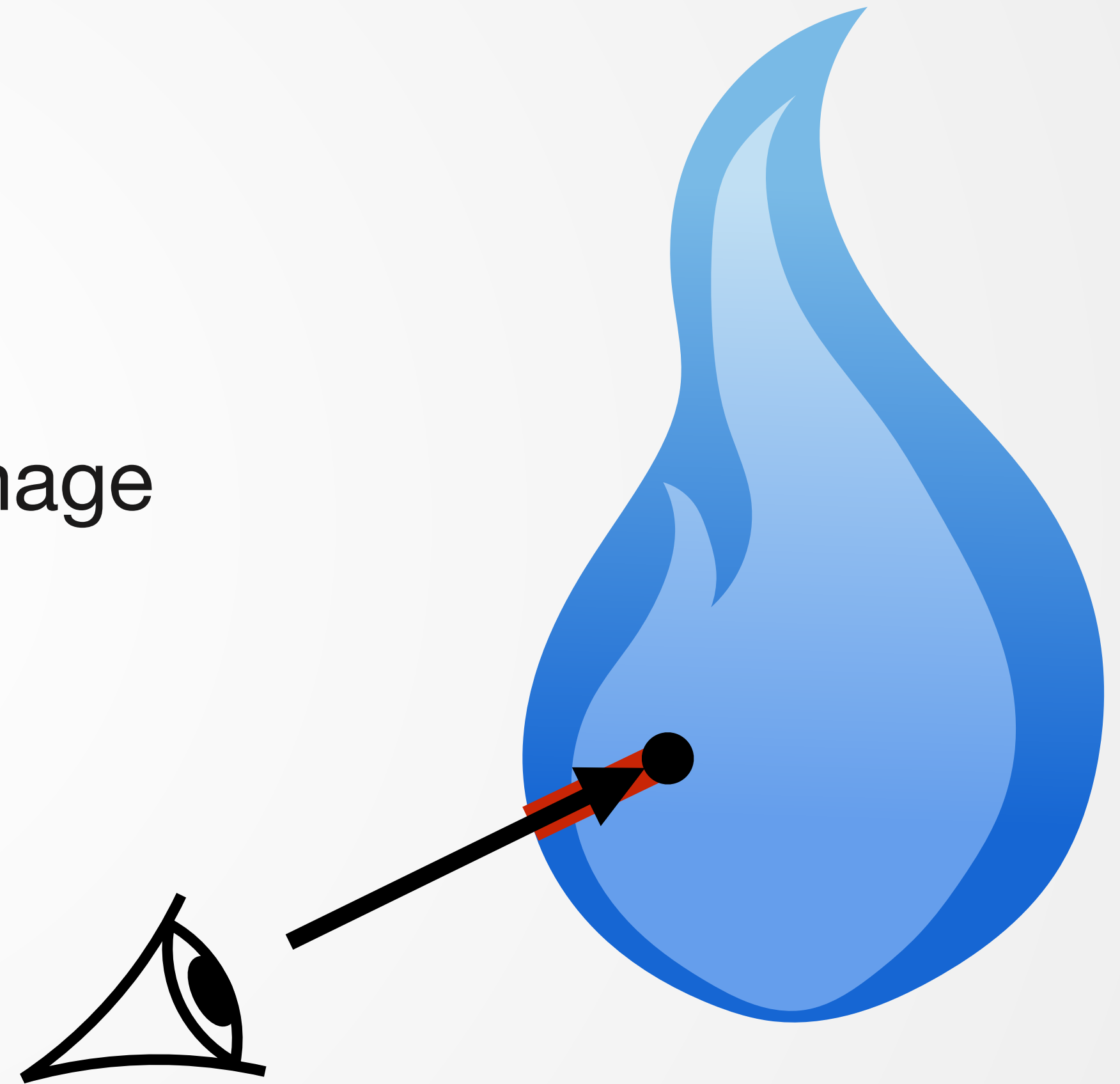
Line Integration

- Integrate emission only up to scattering event
- Advantage:
 - No-collision paths also contribute to the image



Line Integration

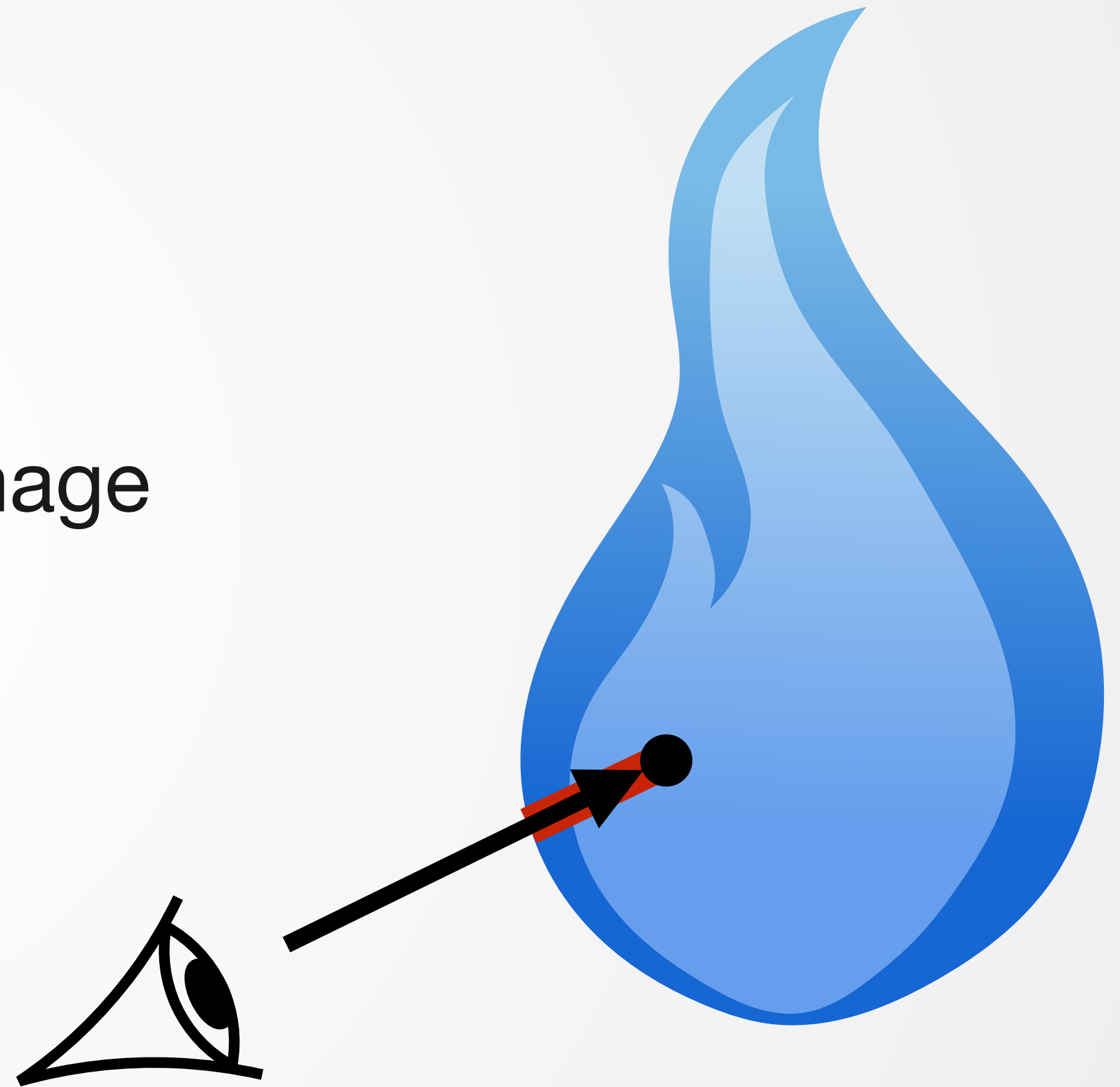
- Integrate emission only up to scattering event
- Advantage:
 - No-collision paths also contribute to the image
 - Early out in dense volumes



Line Integration

- Integrate emission only up to scattering event
- Advantage:
 - No-collision paths also contribute to the image
 - Early out in dense volumes

How?

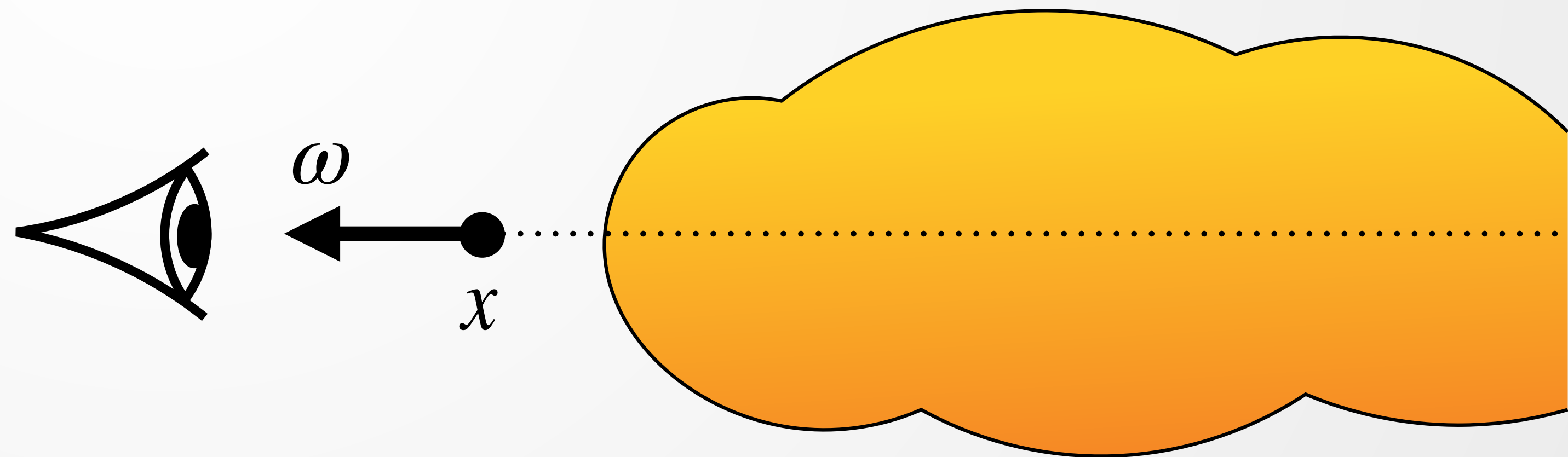


Volumetric Emission

- Radiance at x in direction ω due to direct volumetric emission:

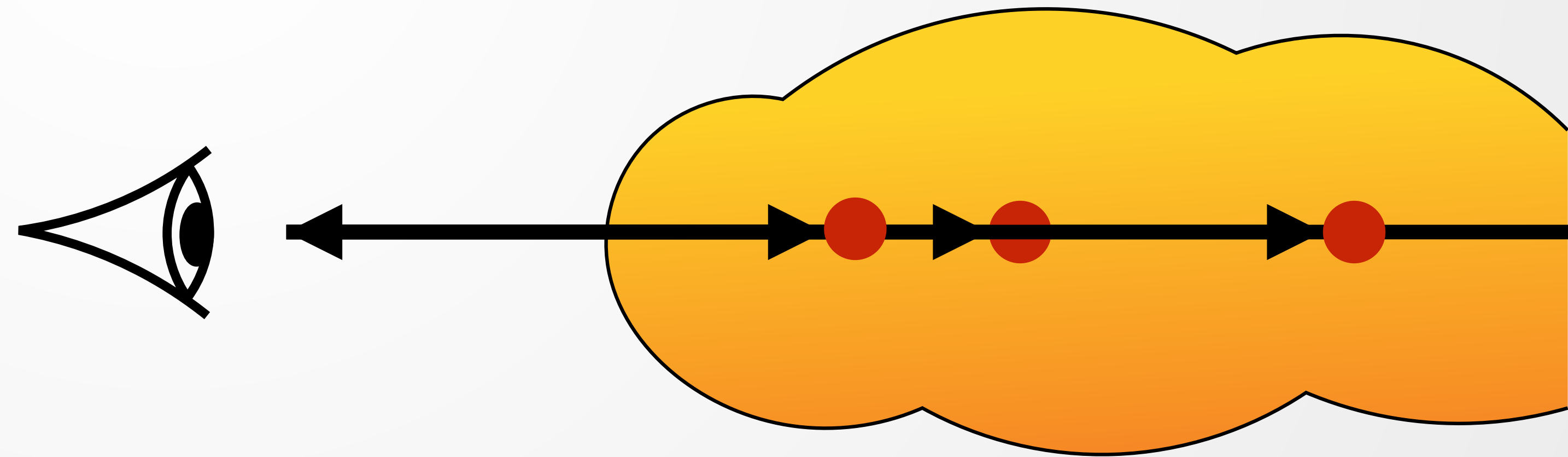
$$L(x, \omega) = \int_0^\infty \tau(x - \omega t) L_e(x - \omega t) dt$$

$$= \int_0^\infty \tau(t) L_e(t) dt$$



Point Integration

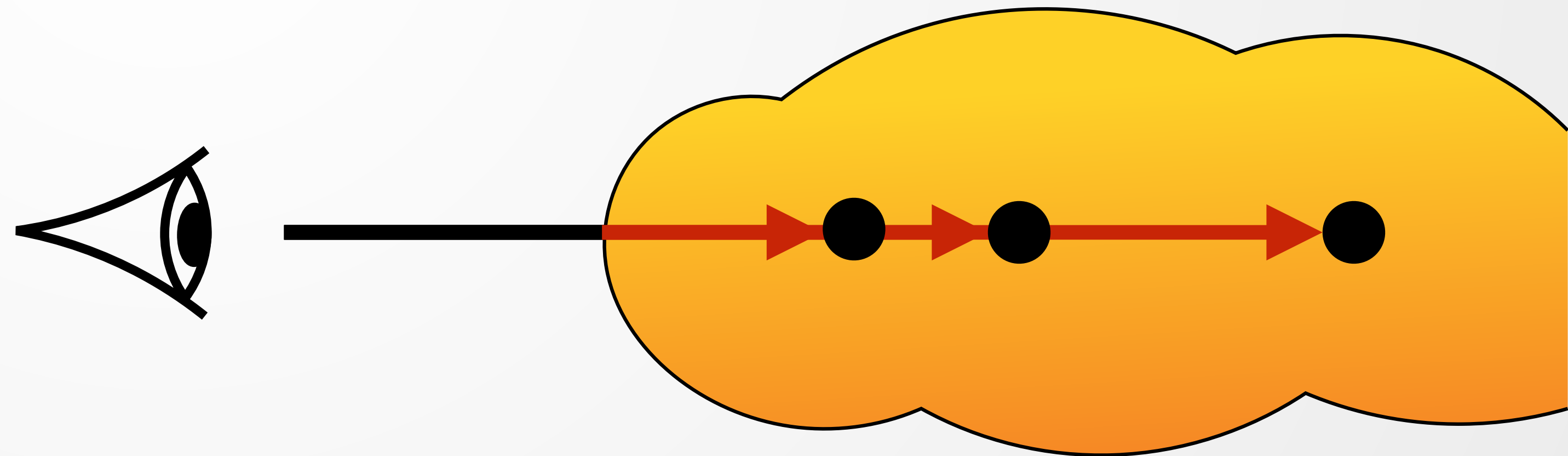
$$\int_0^\infty \tau(t) L_e(t) dt \approx \frac{1}{N} \sum_{i=1}^N \frac{\tau(t_i) L_e(t_i)}{p(t_i)}$$



Line Integration

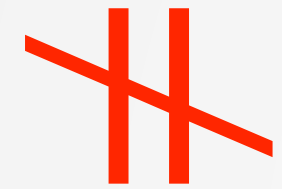
$$\int_0^\infty \tau(t) L_e(t) dt \approx \frac{1}{N} \sum_{i=1}^N \frac{\tau(t_i) L_e(t_i)}{p(t_i)}$$

$$\int_0^\infty \int_0^t \tau(s) L_e(s) ds dt \approx \frac{1}{N} \sum_{i=1}^N \frac{\int_0^{t_i} \tau(s) L_e(s) ds}{p(t_i)}$$

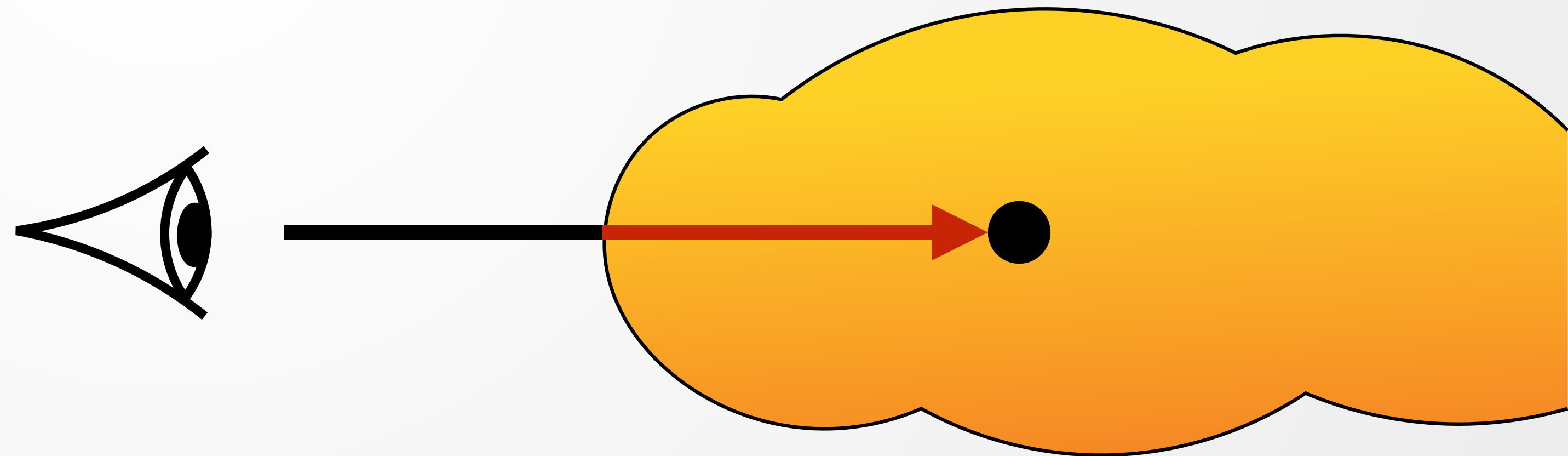


Line Integration

$$\int_0^\infty \tau(t) L_e(t) dt \approx \frac{1}{N} \sum_{i=1}^N \frac{\tau(t_i) L_e(t_i)}{p(t_i)}$$

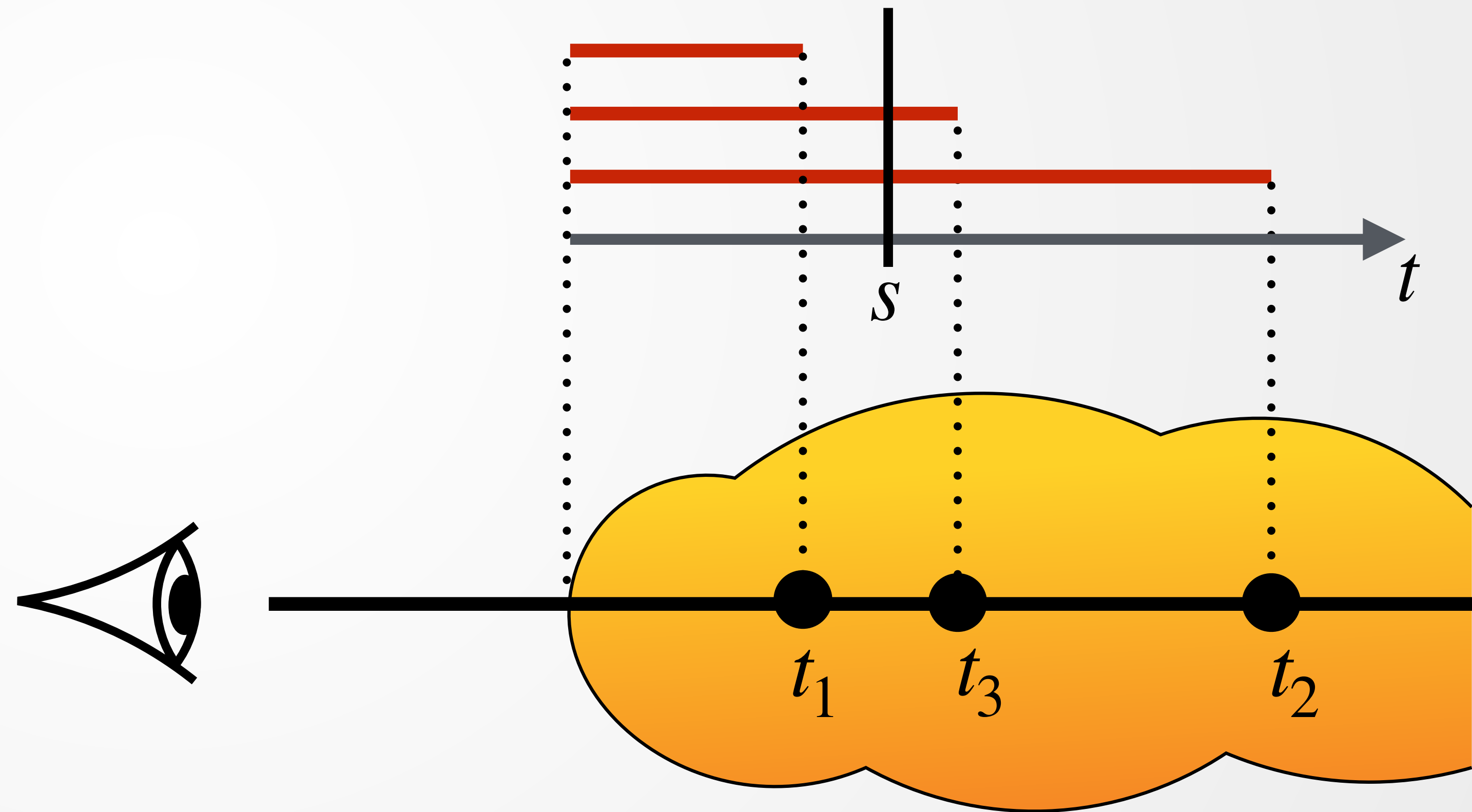


$$\int_0^\infty \int_0^t \tau(s) L_e(s) ds dt \approx \frac{1}{N} \sum_{i=1}^N \frac{\int_0^{t_i} \tau(s) L_e(s) ds}{p(t_i)}$$



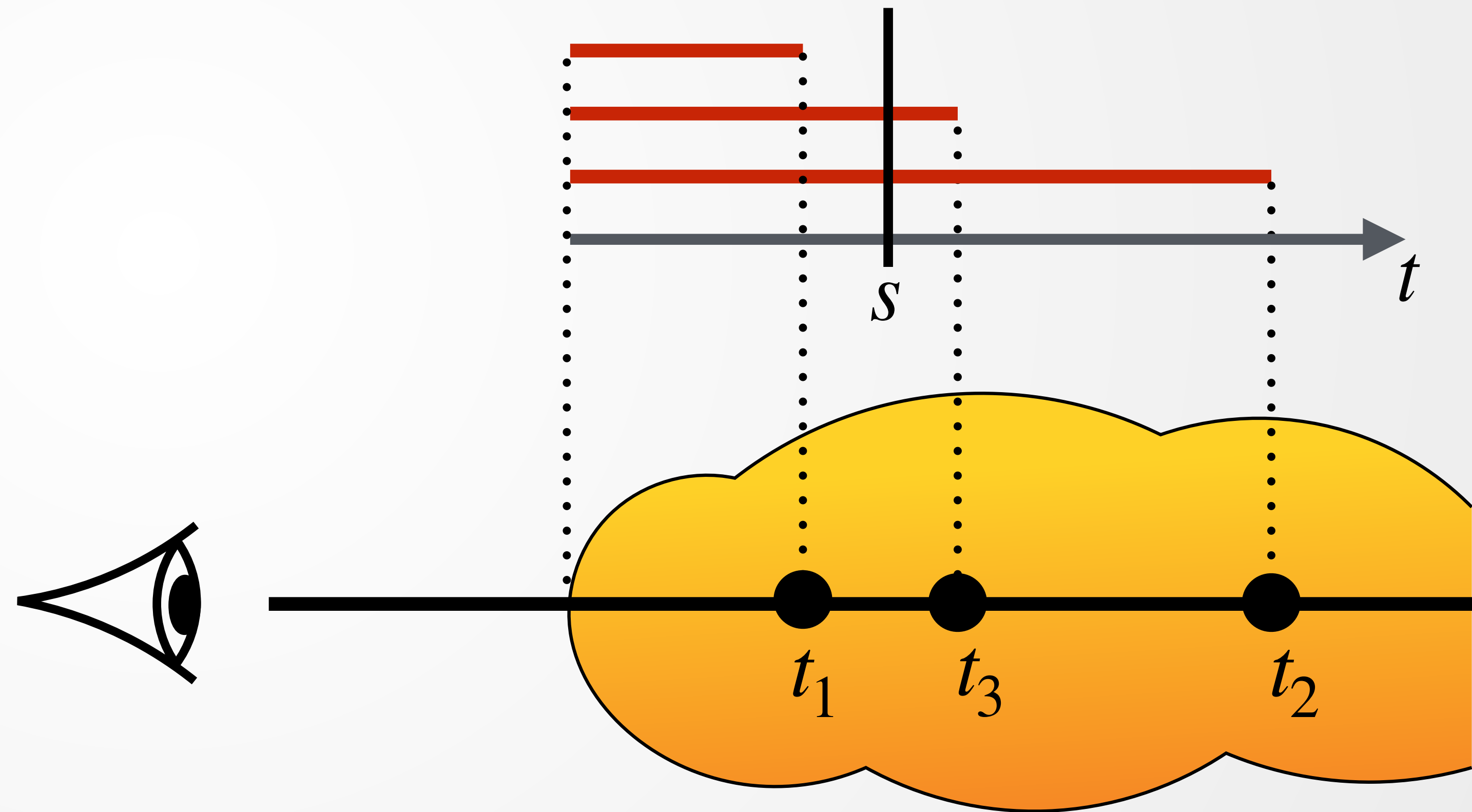
Line Integration

$$\int_0^\infty \tau(t) L_e(t) dt \neq \int_0^\infty \int_0^t \tau(s) L_e(s) ds dt$$



Line Integration

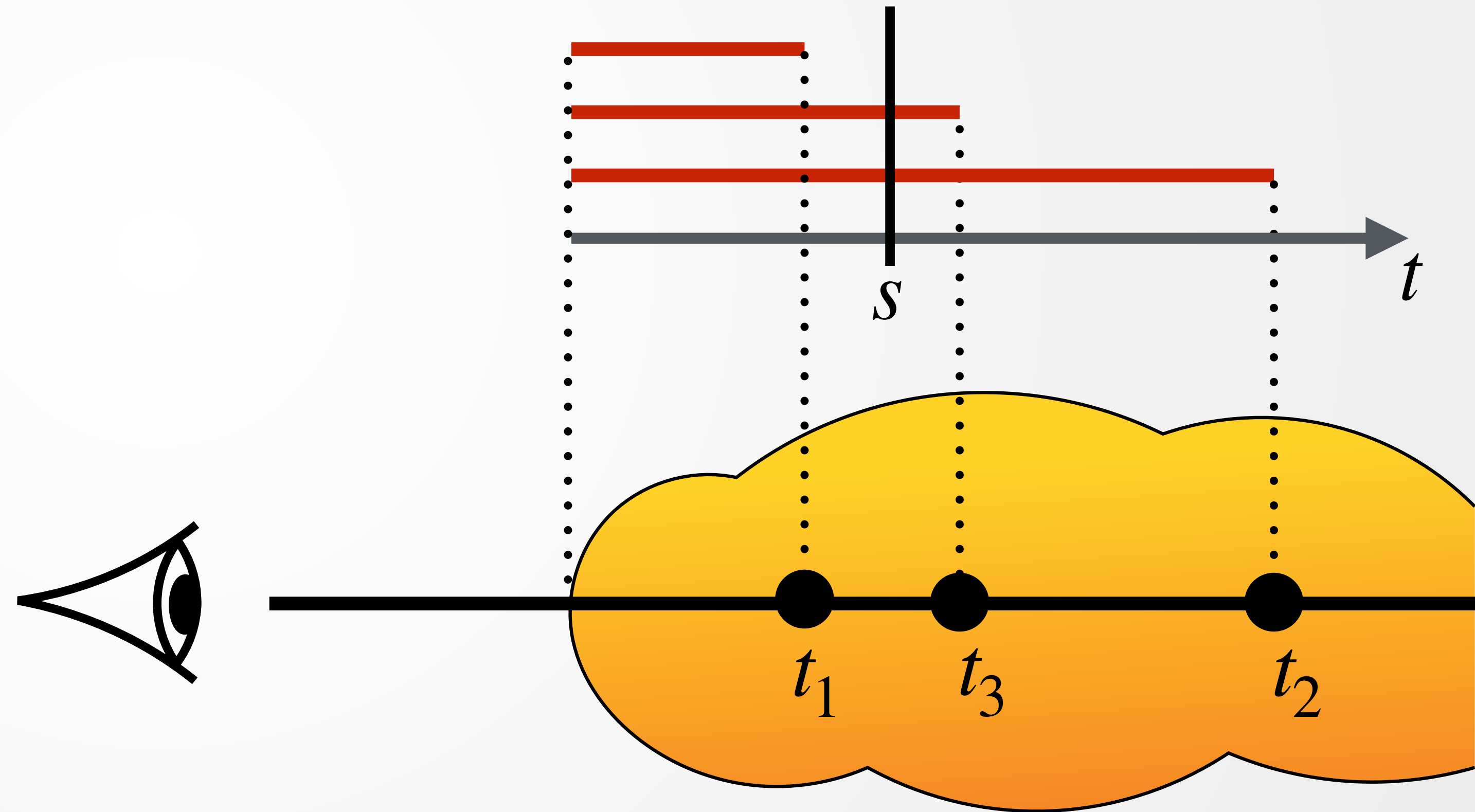
$$\int_0^\infty \tau(t) L_e(t) dt \stackrel{!}{=} \int_0^\infty \int_0^t w_t(s) \tau(s) L_e(s) ds dt$$



Line Integration

$$\int_0^\infty \tau(t) L_e(t) dt \stackrel{!}{=} \int_0^\infty \int_0^t w_t(s) \tau(s) L_e(s) ds dt$$

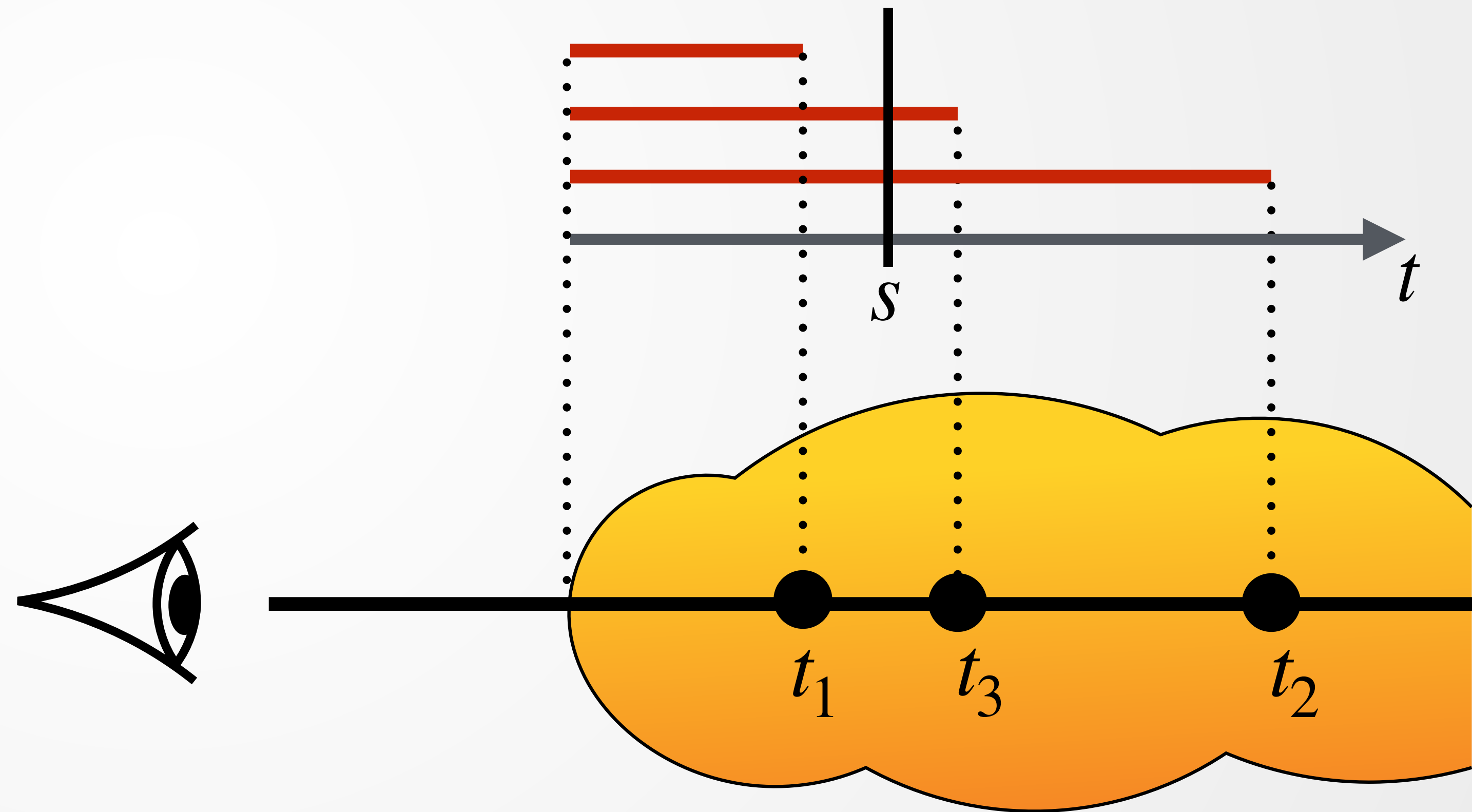
- $w_t(s) = 0$ for all $s > t$



Line Integration

$$\int_0^\infty \tau(t) L_e(t) dt \stackrel{!}{=} \int_0^\infty \int_0^\infty w_t(s) \tau(s) L_e(s) ds dt$$

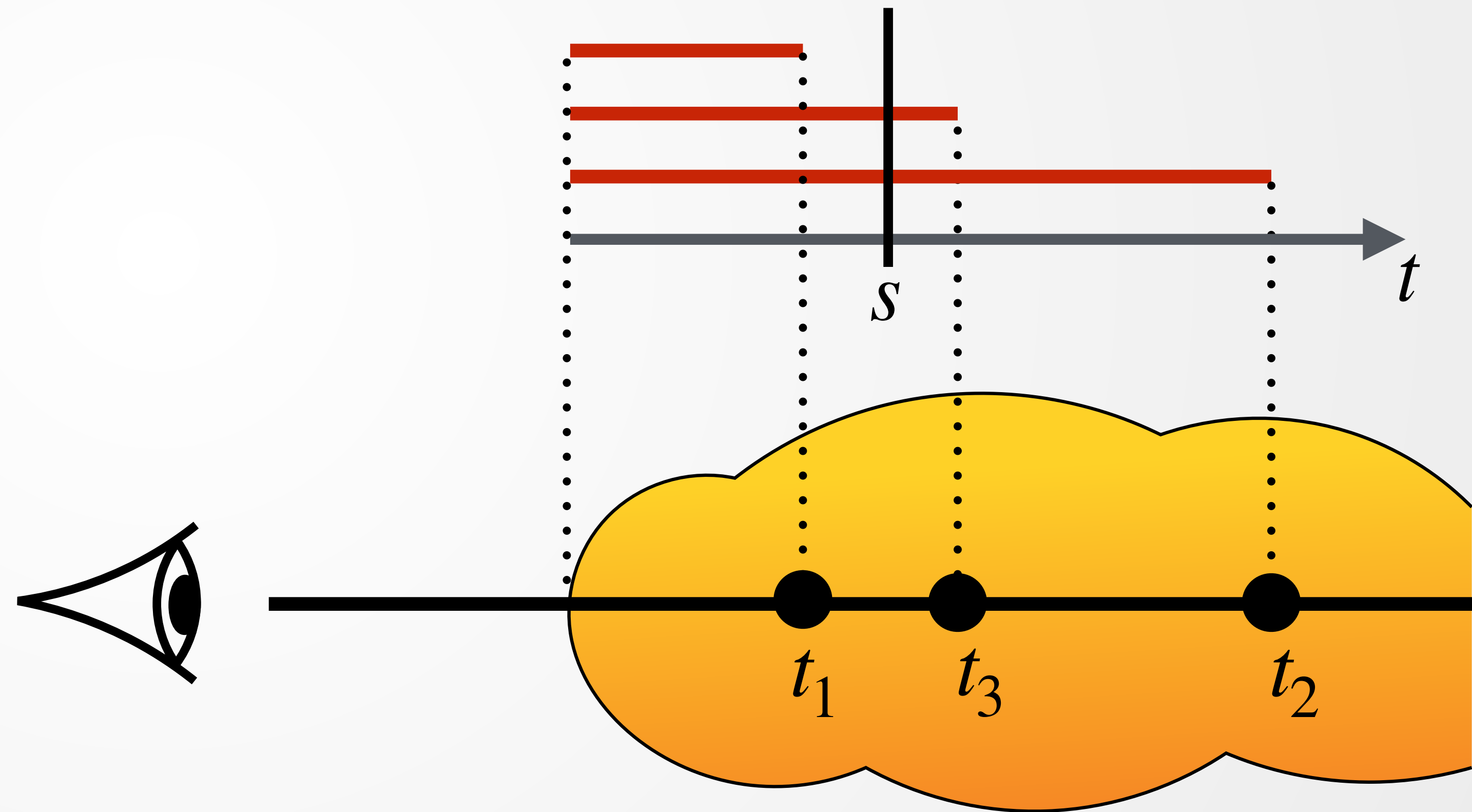
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Line Integration

$$\int_0^\infty \tau(t) L_e(t) dt \stackrel{!}{=} \int_0^\infty \int_0^\infty w_t(s) \tau(s) L_e(s) dt ds$$

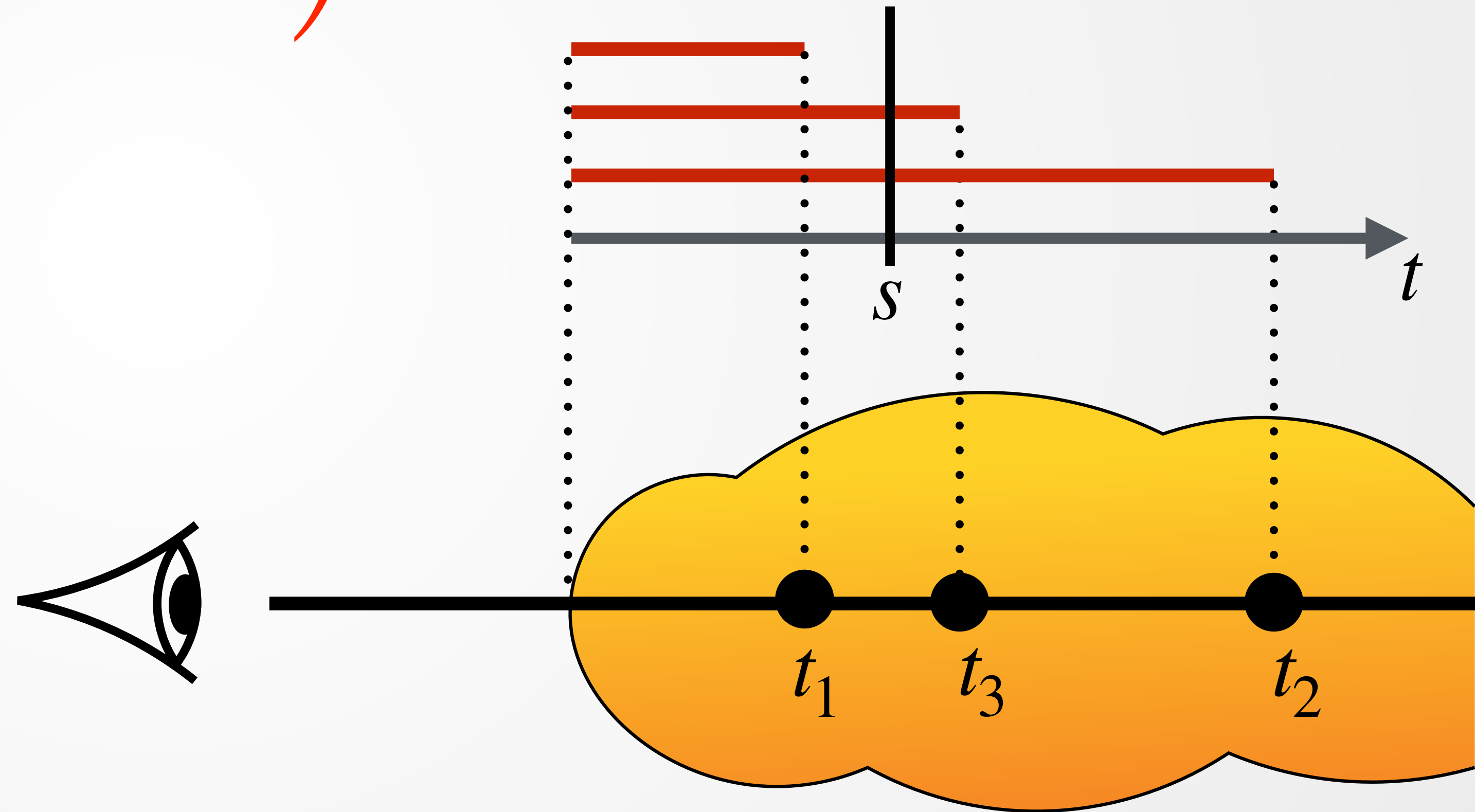
- $w_t(s) = 0$ for all $s > t$



Line Integration

$$\int_0^\infty \tau(t) L_e(t) dt \stackrel{!}{=} \int_0^\infty \left(\int_0^\infty w_t(s) dt \right) \tau(s) L_e(s) ds$$

- $w_t(s) = 0$ for all $s > t$

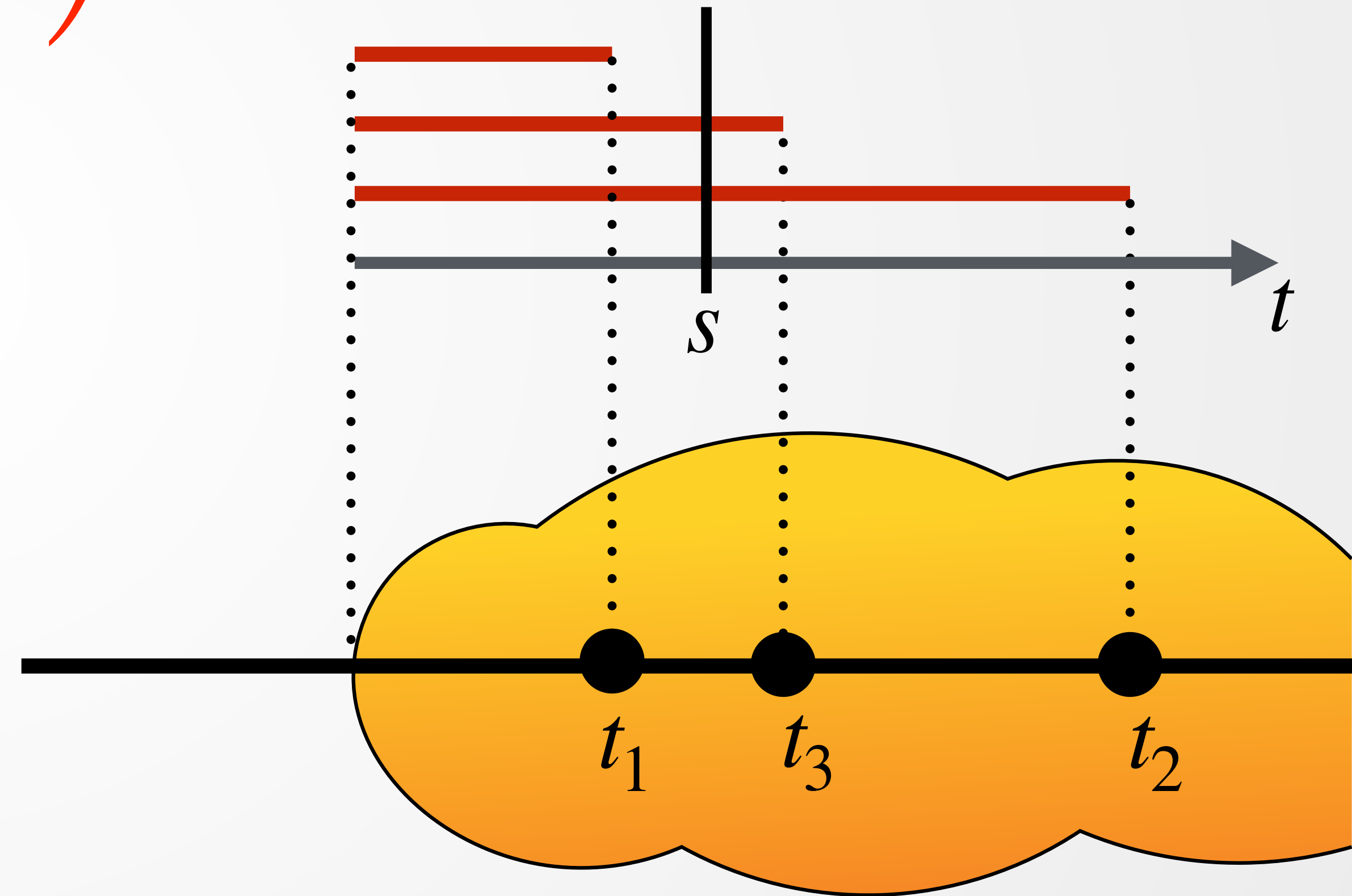
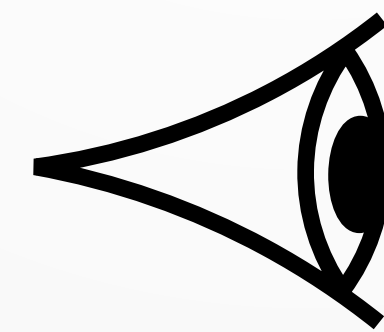


Line Integration

$$\int_0^\infty \tau(t) L_e(t) dt \stackrel{!}{=} \int_0^\infty \left(\int_0^\infty w_t(s) dt \right) \tau(s) L_e(s) ds$$

- $w_t(s) = 0$ for all $s > t$

- $\int_0^\infty w_t(s) dt = 1$ for all s

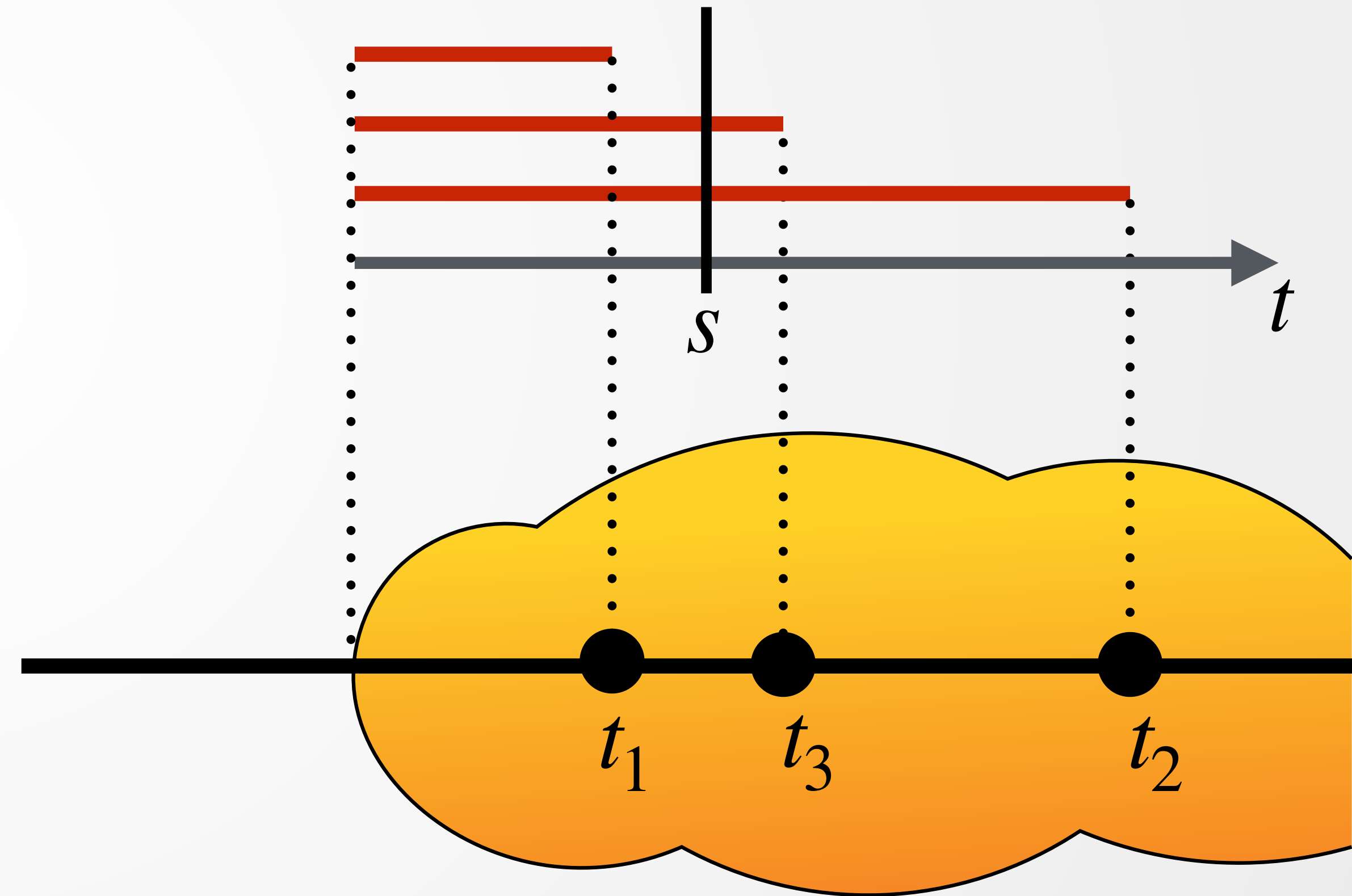
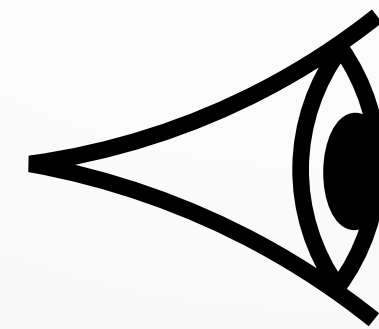


Line Integration

$$\int_0^\infty \tau(t) L_e(t) dt = \int_0^\infty \tau(s) L_e(s) ds$$

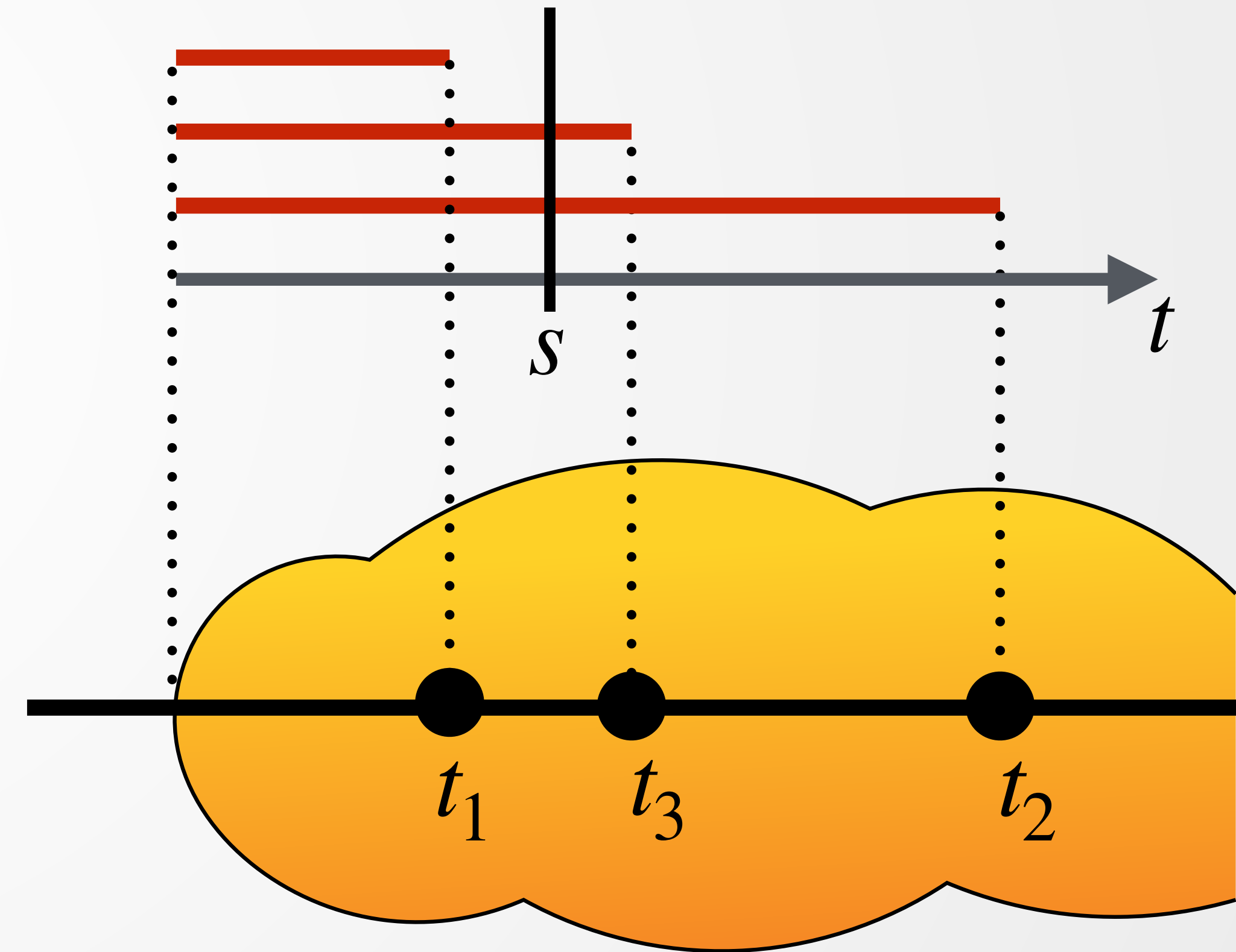
- $w_t(s) = 0$ for all $s > t$

- $\int_0^\infty w_t(s) dt = 1$ for all s



Weight Function

- Intuition:
 - $\Pr(t \geq s) = \tau(s)$
 - $w_t(s) \propto 1/\tau(s)$



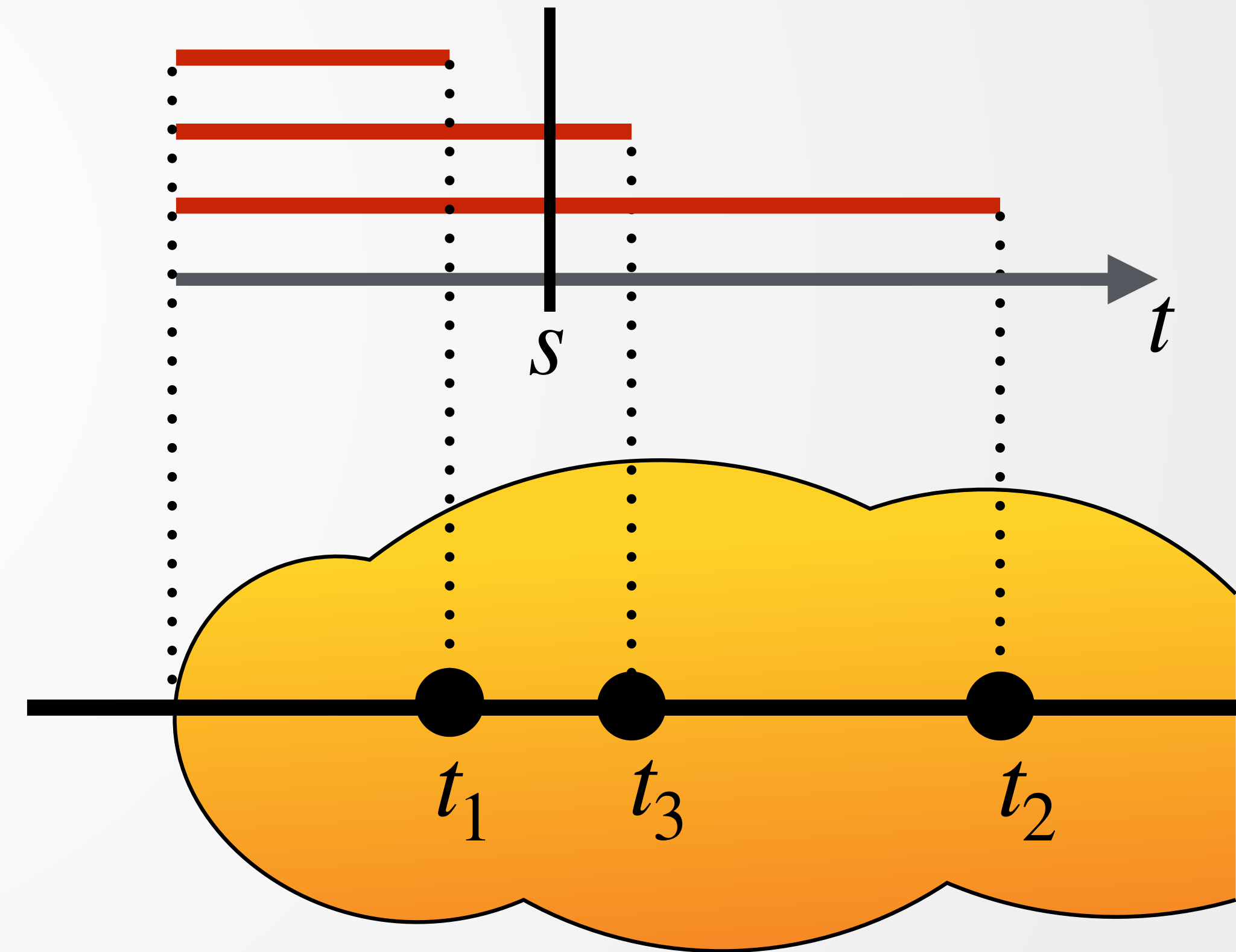
Weight Function

- Intuition:

- $\Pr(t \geq s) = \tau(s)$
- $w_t(s) \propto 1/\tau(s)$

- Weight function:

$$w_t(s) = \begin{cases} \frac{\mu_t(t)\tau(t)}{\tau(s)}, & \text{if } s \leq t \\ 0, & \text{otherwise} \end{cases}$$



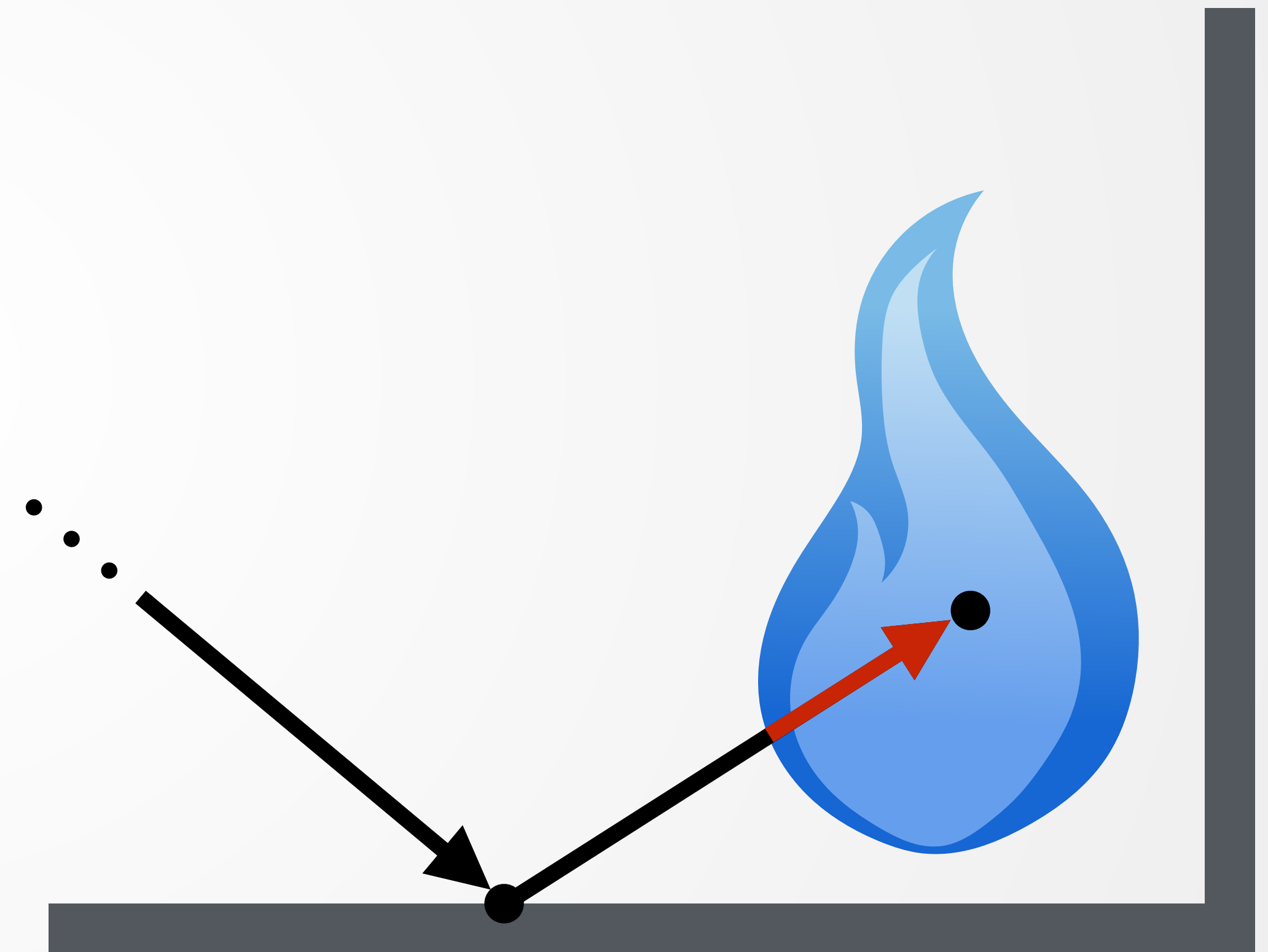
Next Event Estimator

- Crucial for efficient path tracing
- Sample light vertex directly on a light source
- Importance sampling volumes: Villemain and Hery 2013
- Combined with forward sampling (e.g. BSDF) using MIS



Next Event Estimation

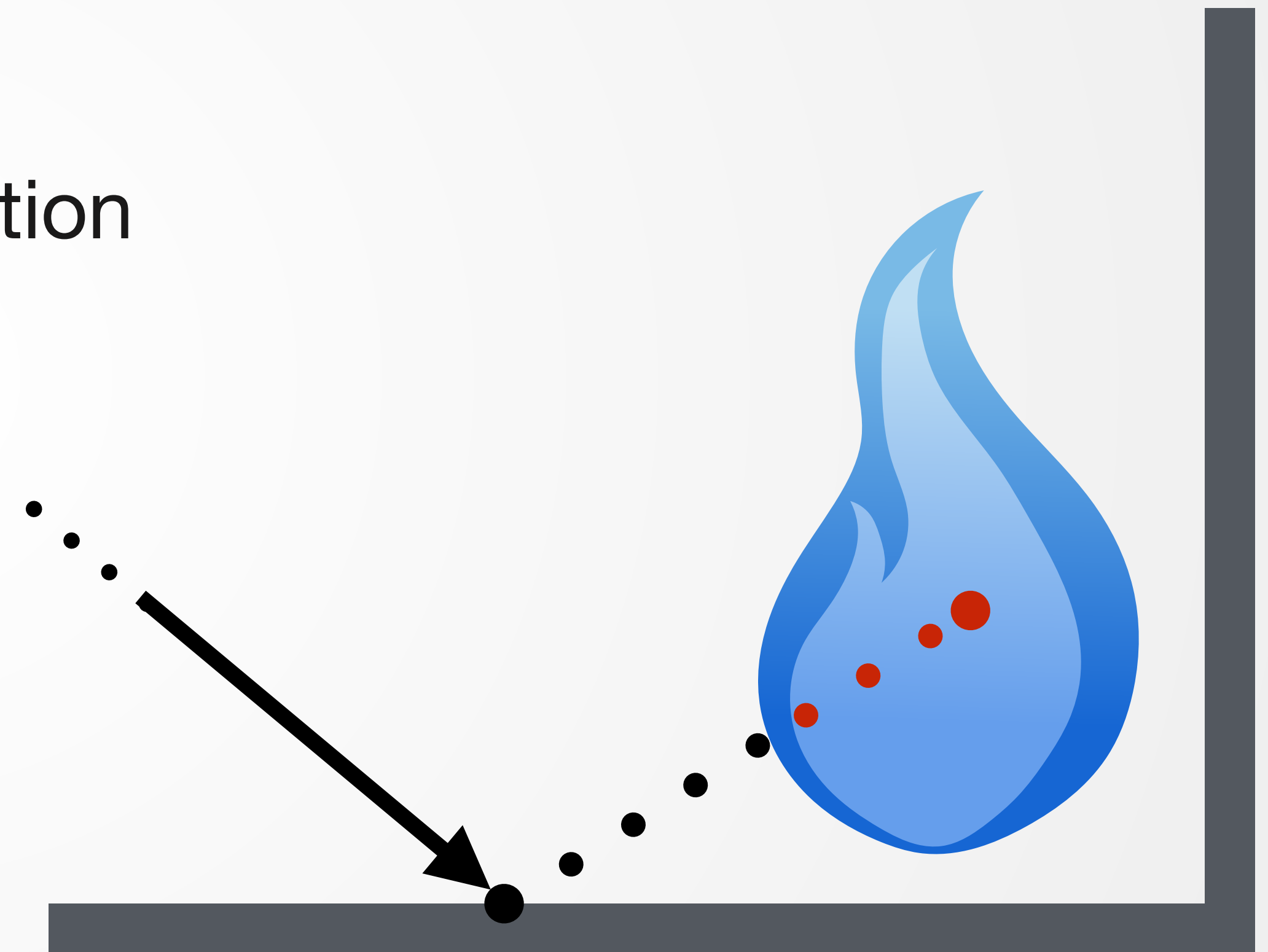
- Scattering events inside the volume



forward sampling

Next Event Estimation

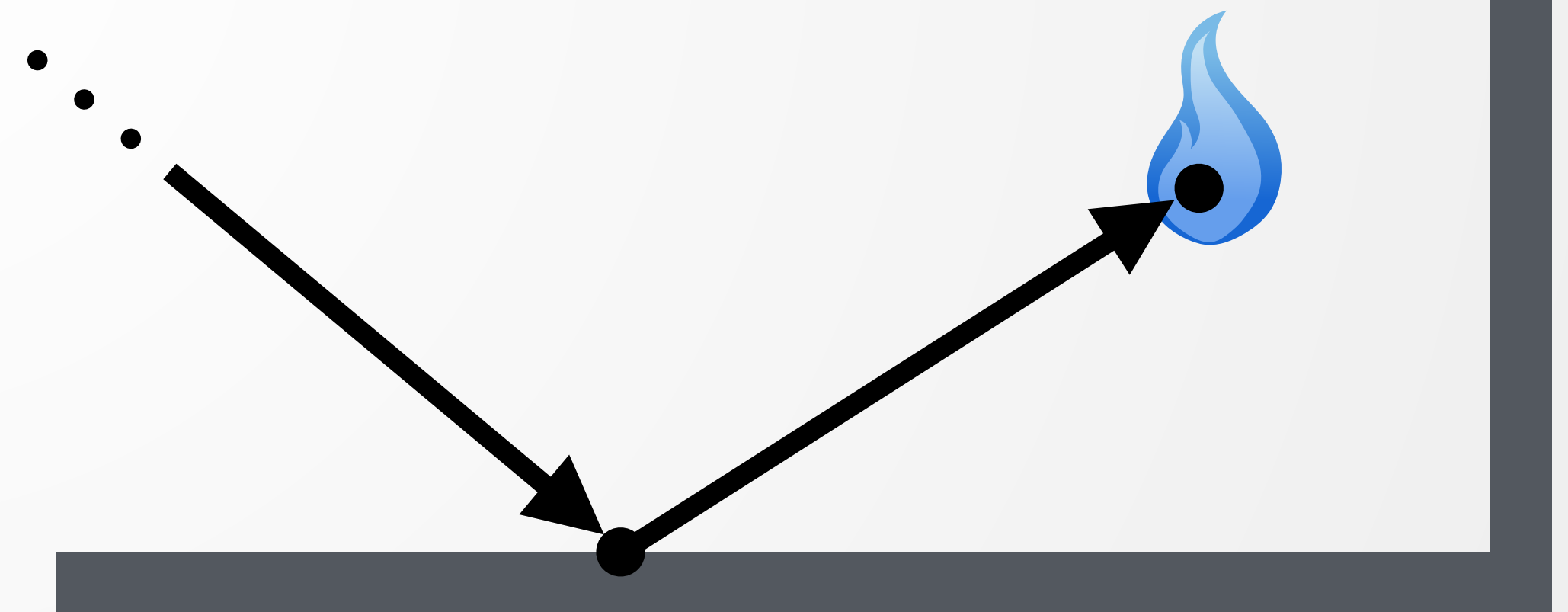
- Scattering events inside the volume
- Can also be sampled with NEE
 - Line integration with same weight function



next event estimation

Next Event Estimation

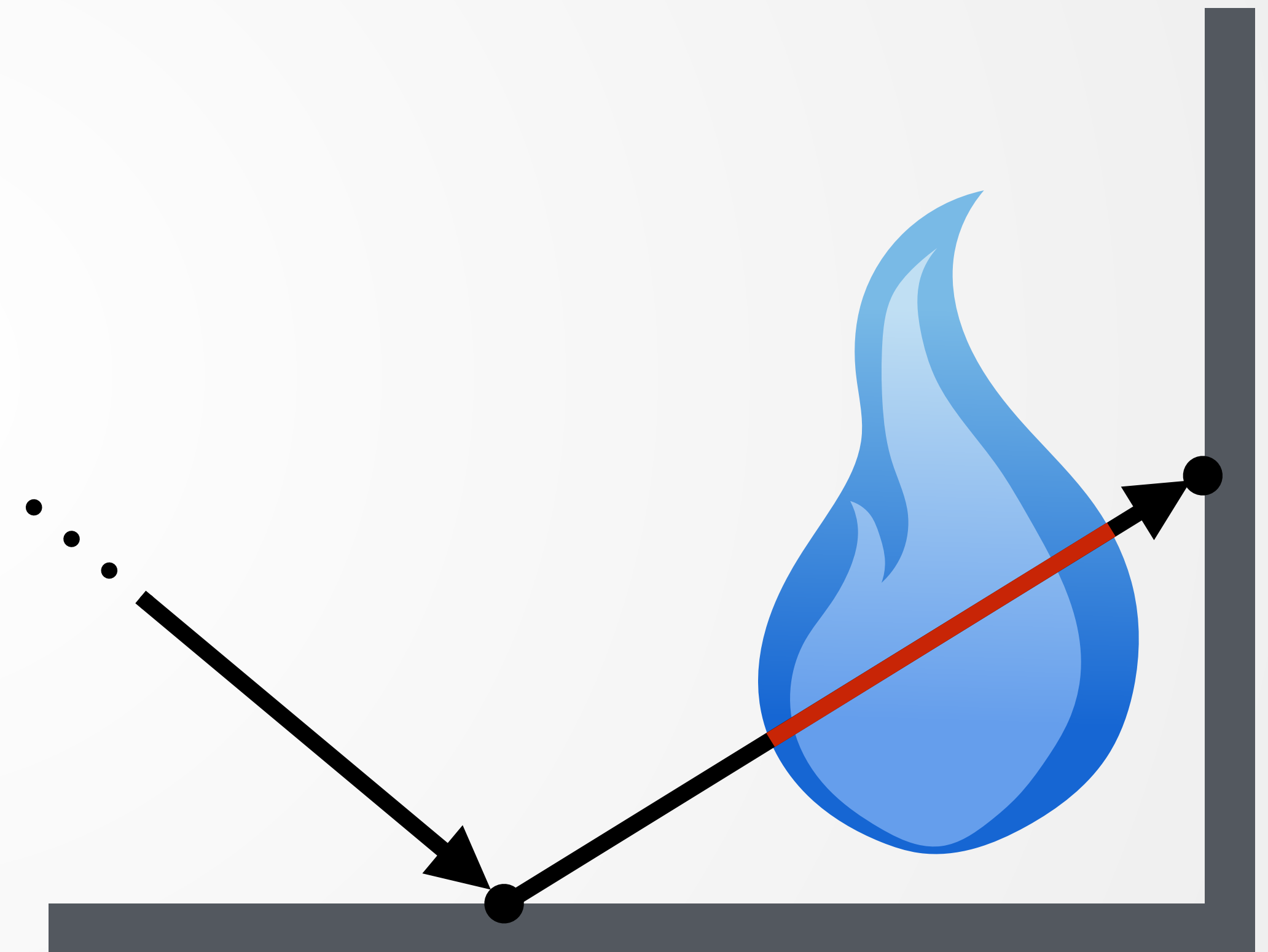
- Scattering events inside the volume
- Can also be sampled with NEE
 - Line integration with same weight function
- MIS is important for unlikely forward paths



forward sampling

Next Event Estimation

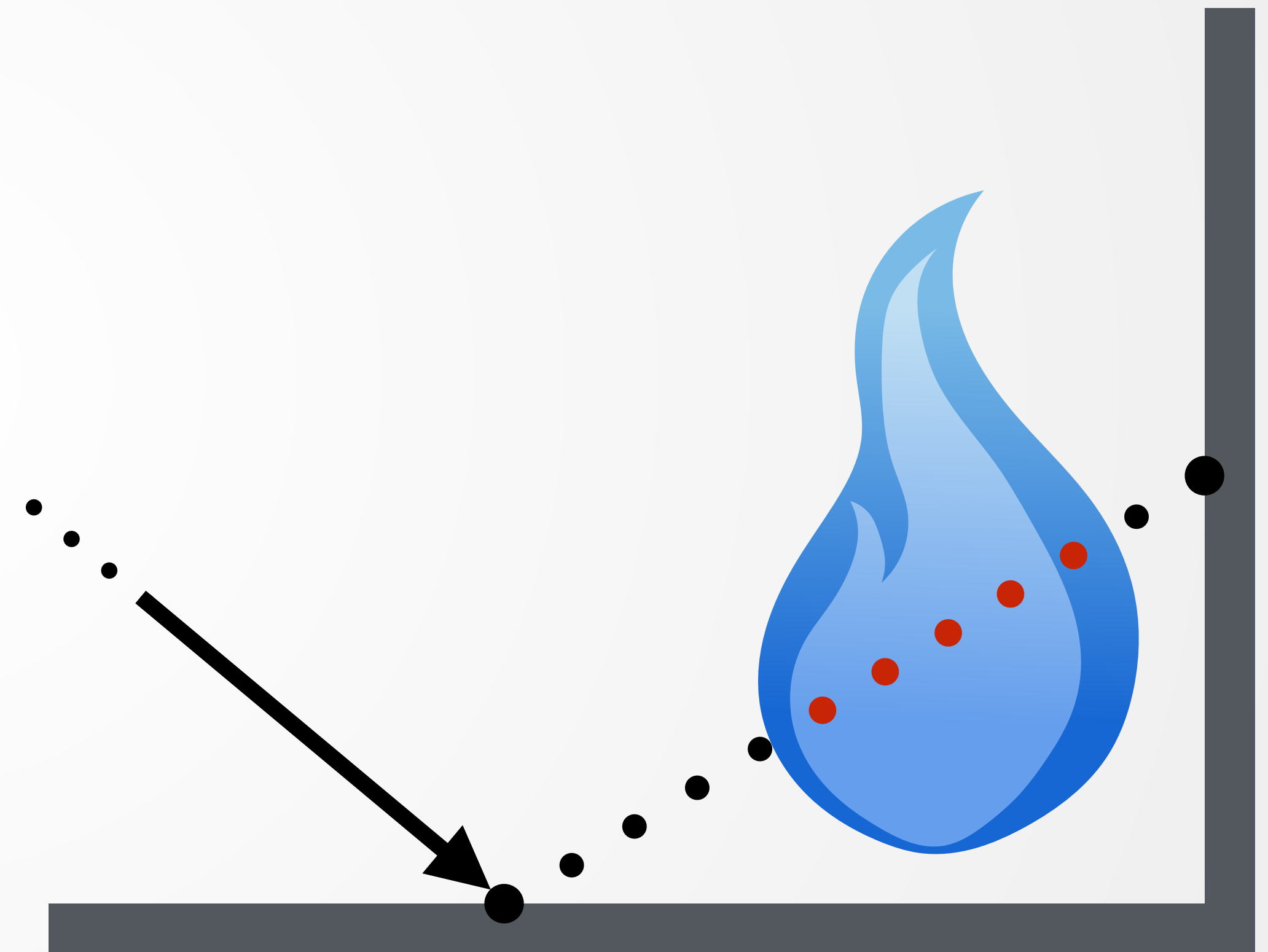
- No-collision paths contribute due to line integration



forward sampling

Next Event Estimation

- No-collision paths contribute due to line integration
- But cannot be created by NEE

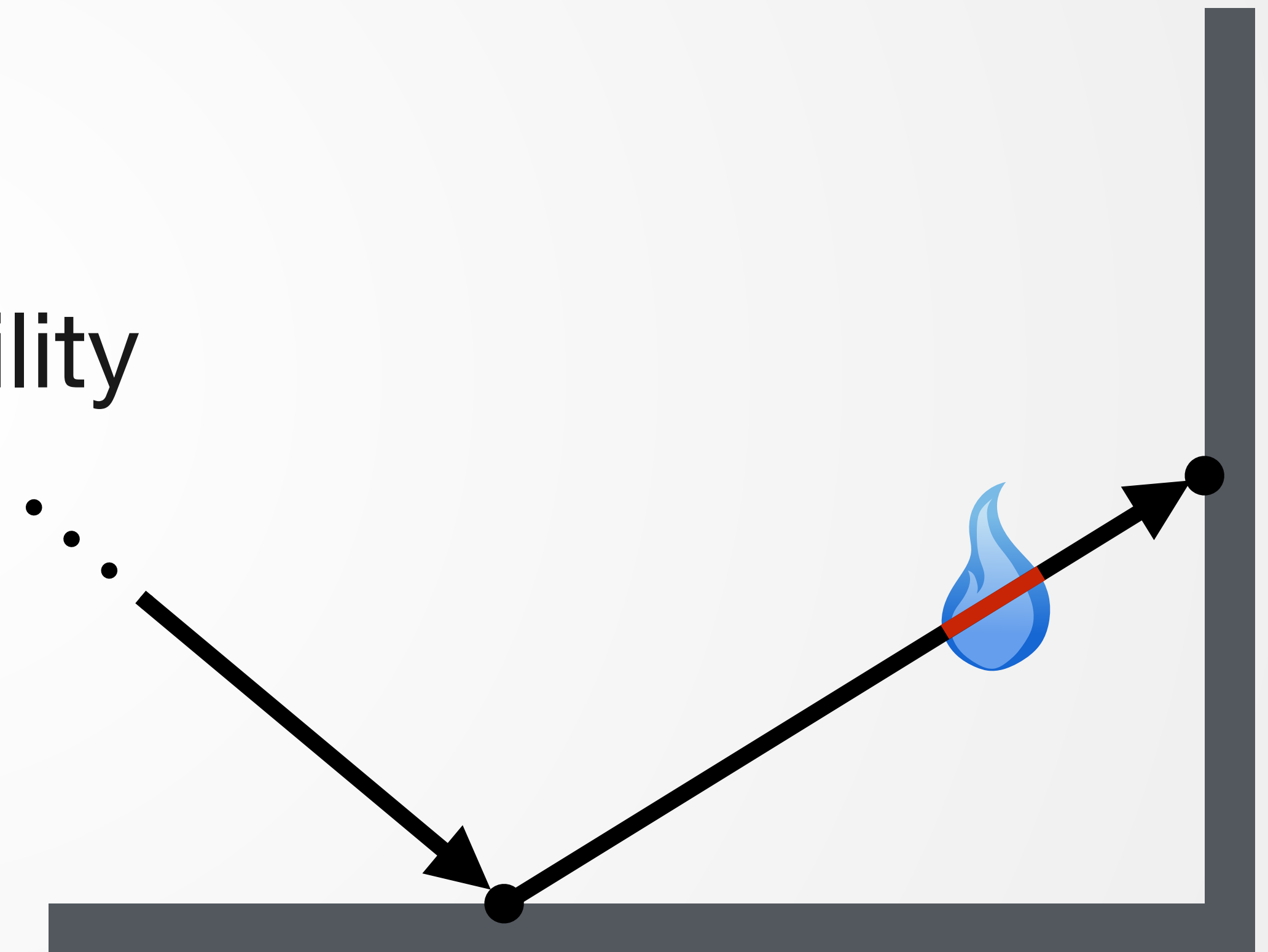


next event estimation



Next Event Estimation

- No-collision paths contribute due to line integration
- But cannot be created by NEE
- Full contribution of low probability paths

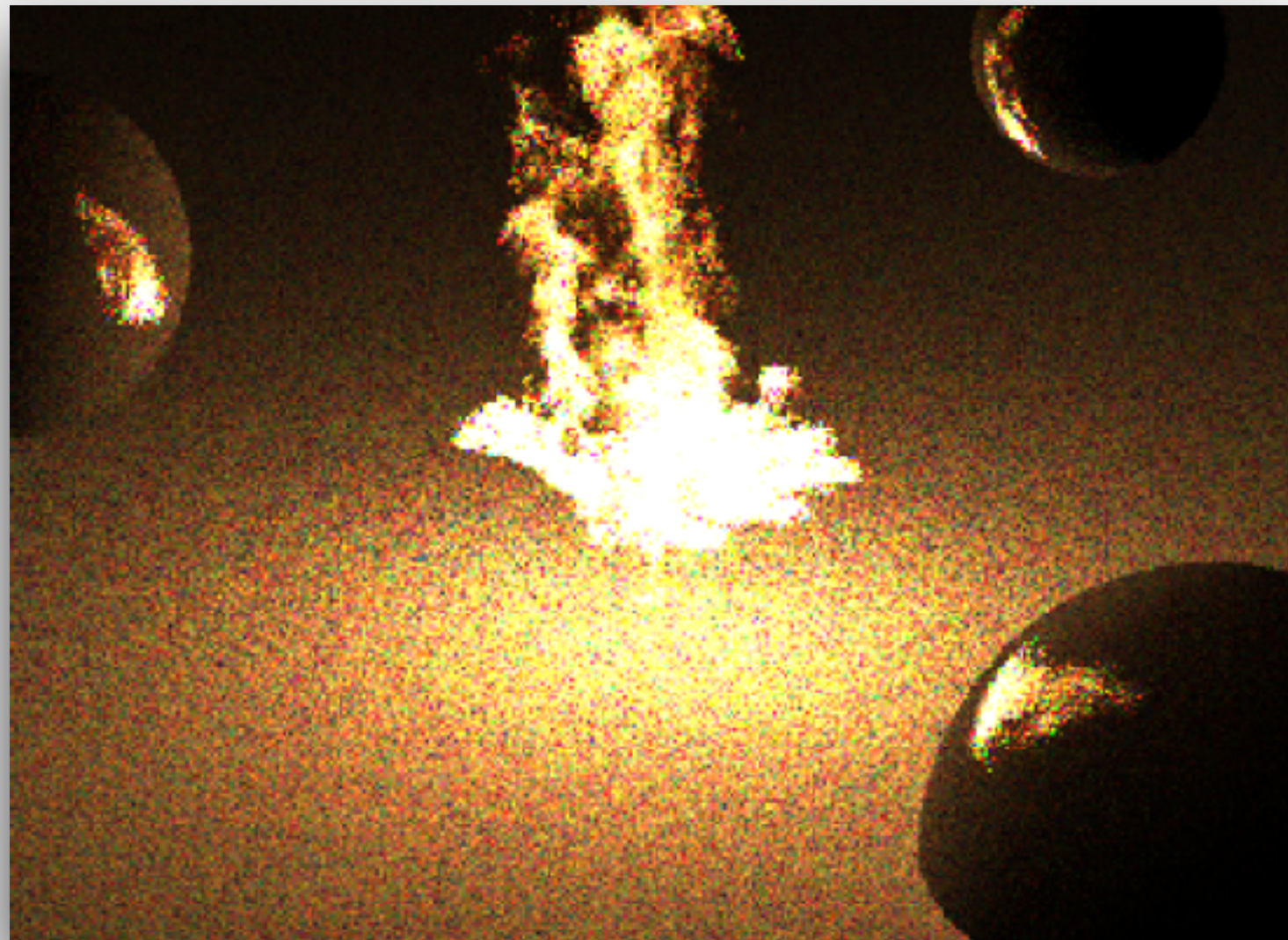


forward sampling

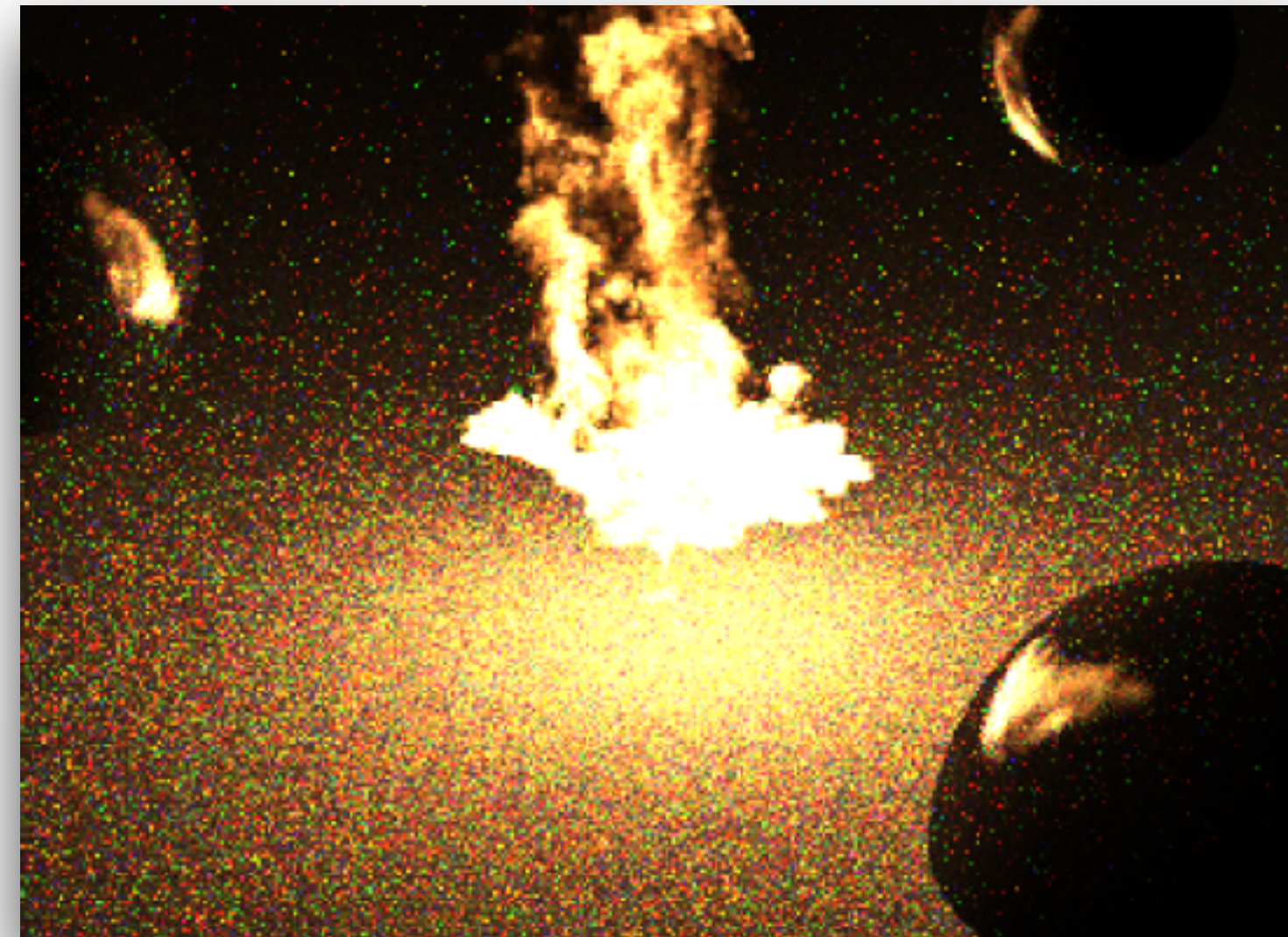
Next Event Estimation

- Line integration does not work well with NEE

Point + NEE



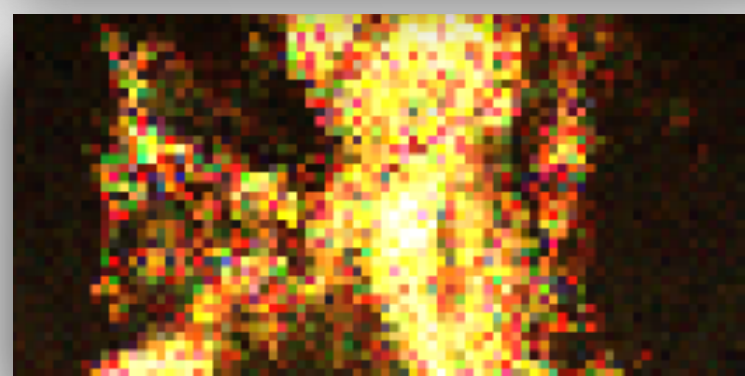
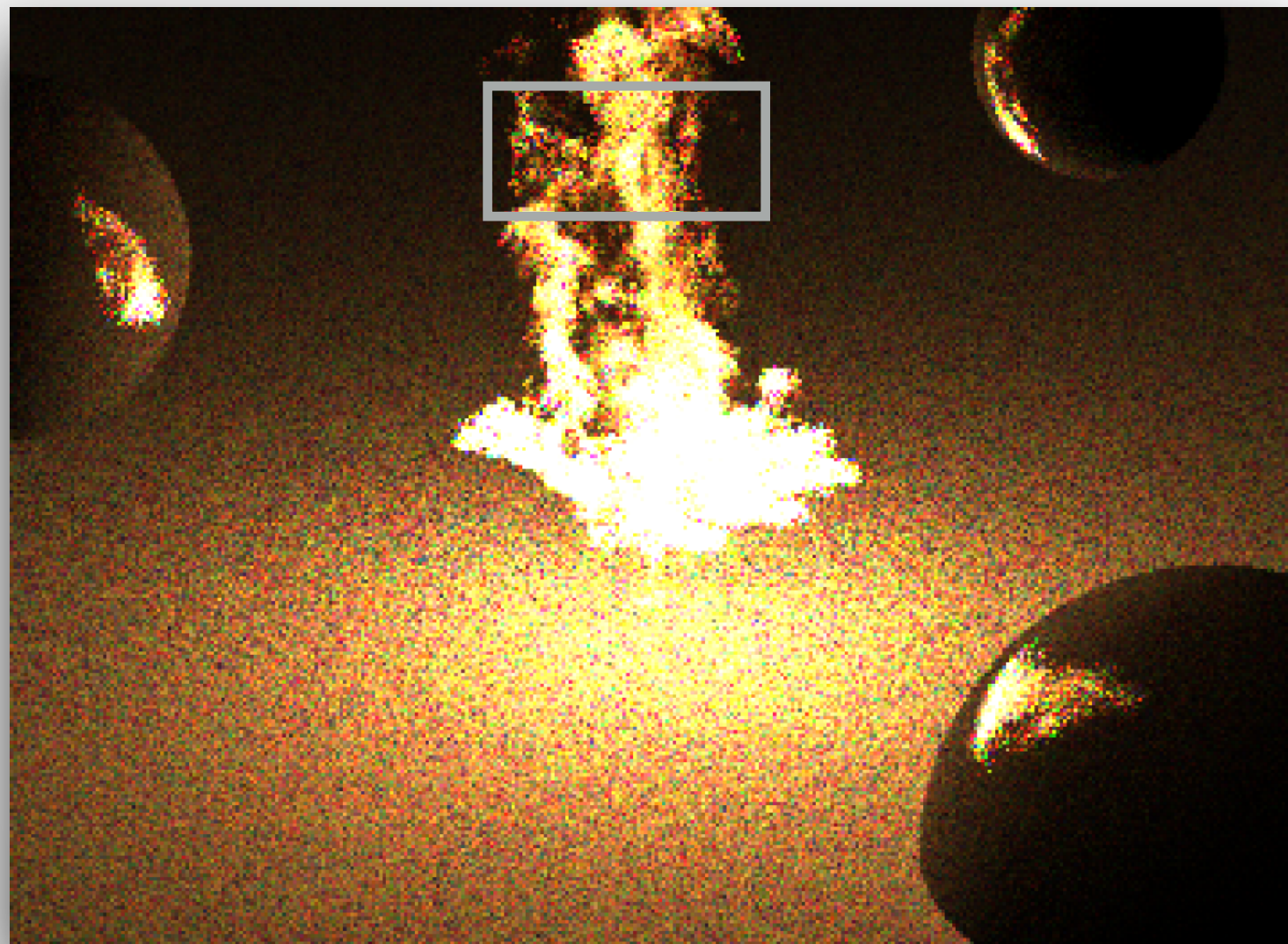
Line + NEE



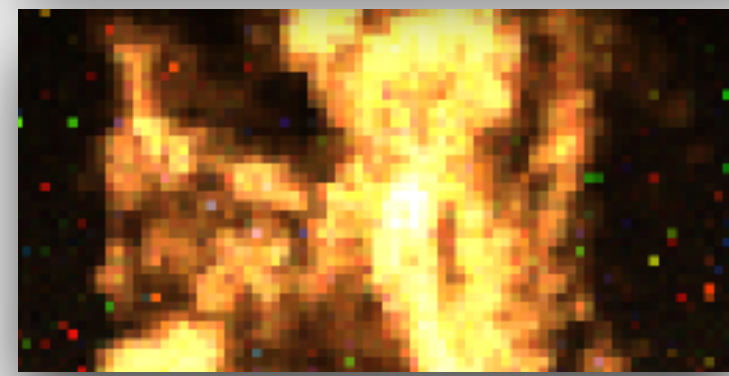
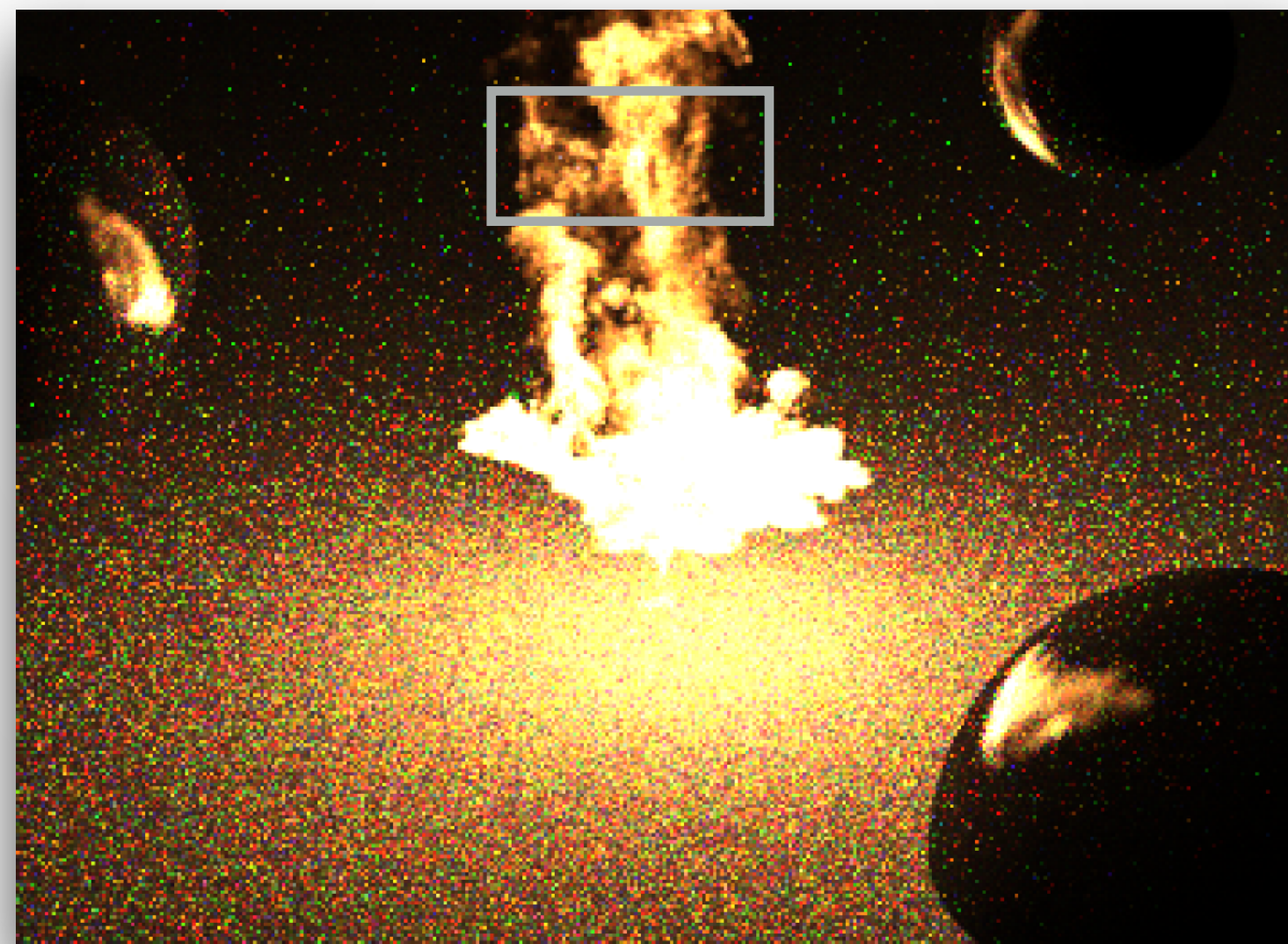
Next Event Estimation

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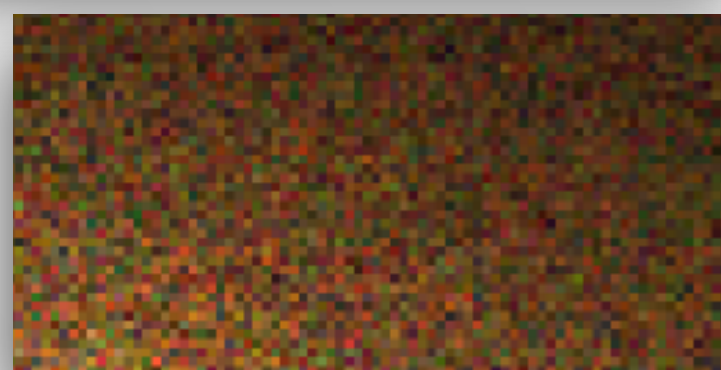
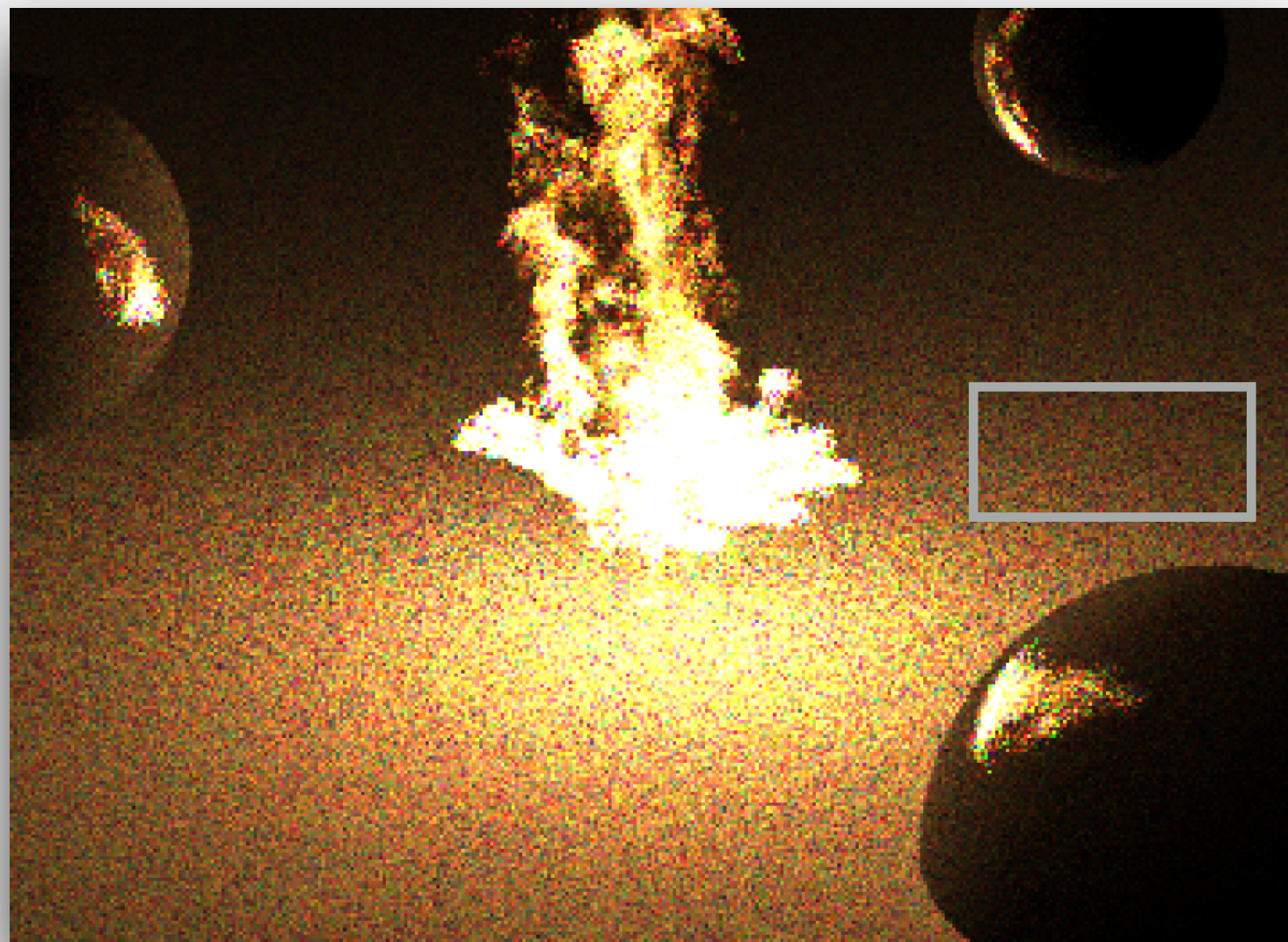
Line + NEE



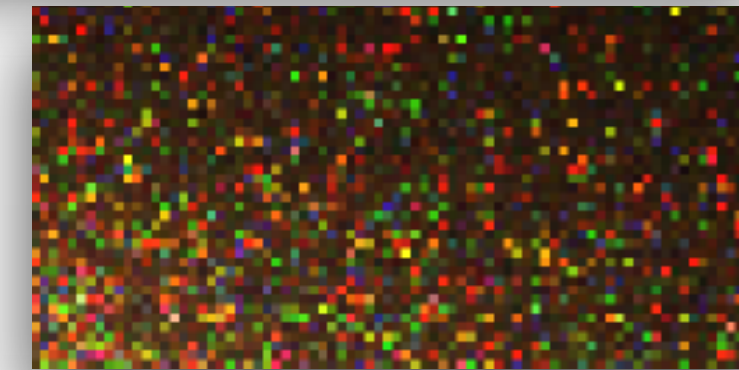
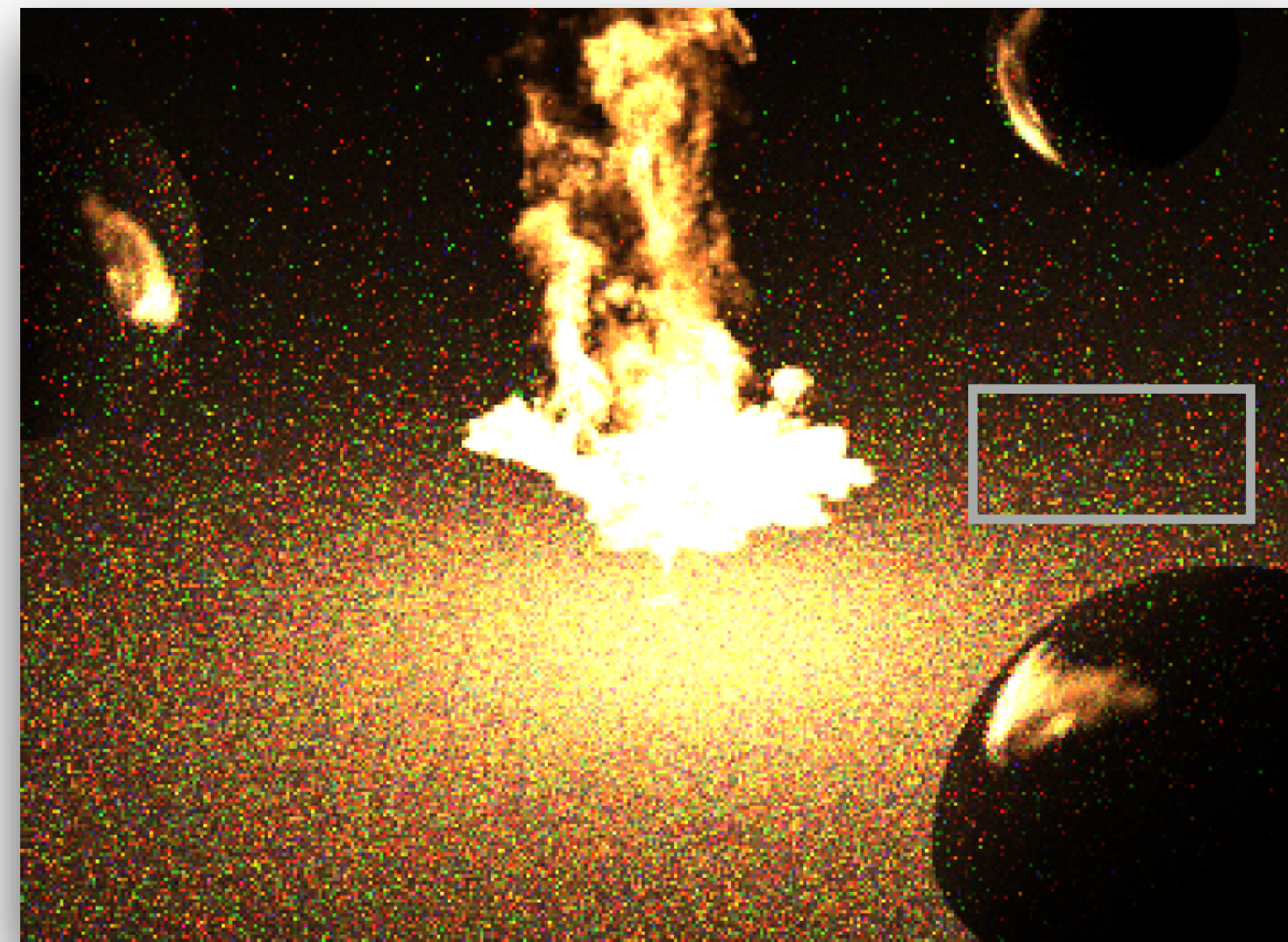
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Line + NEE

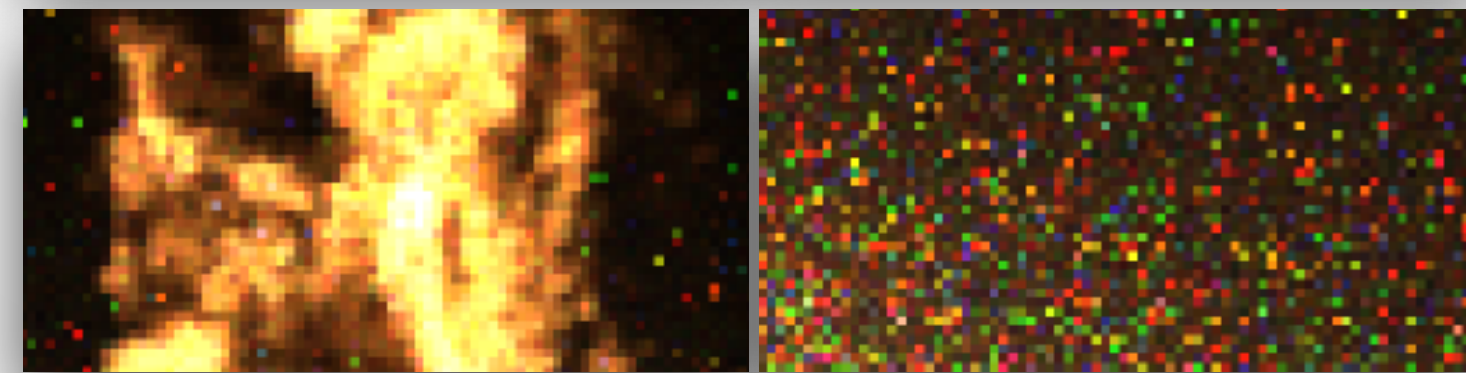
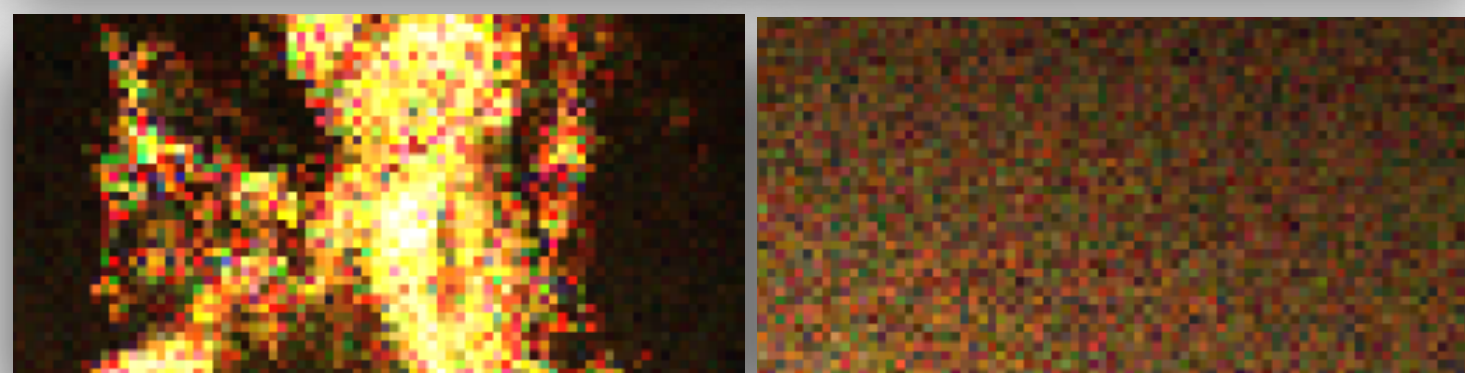
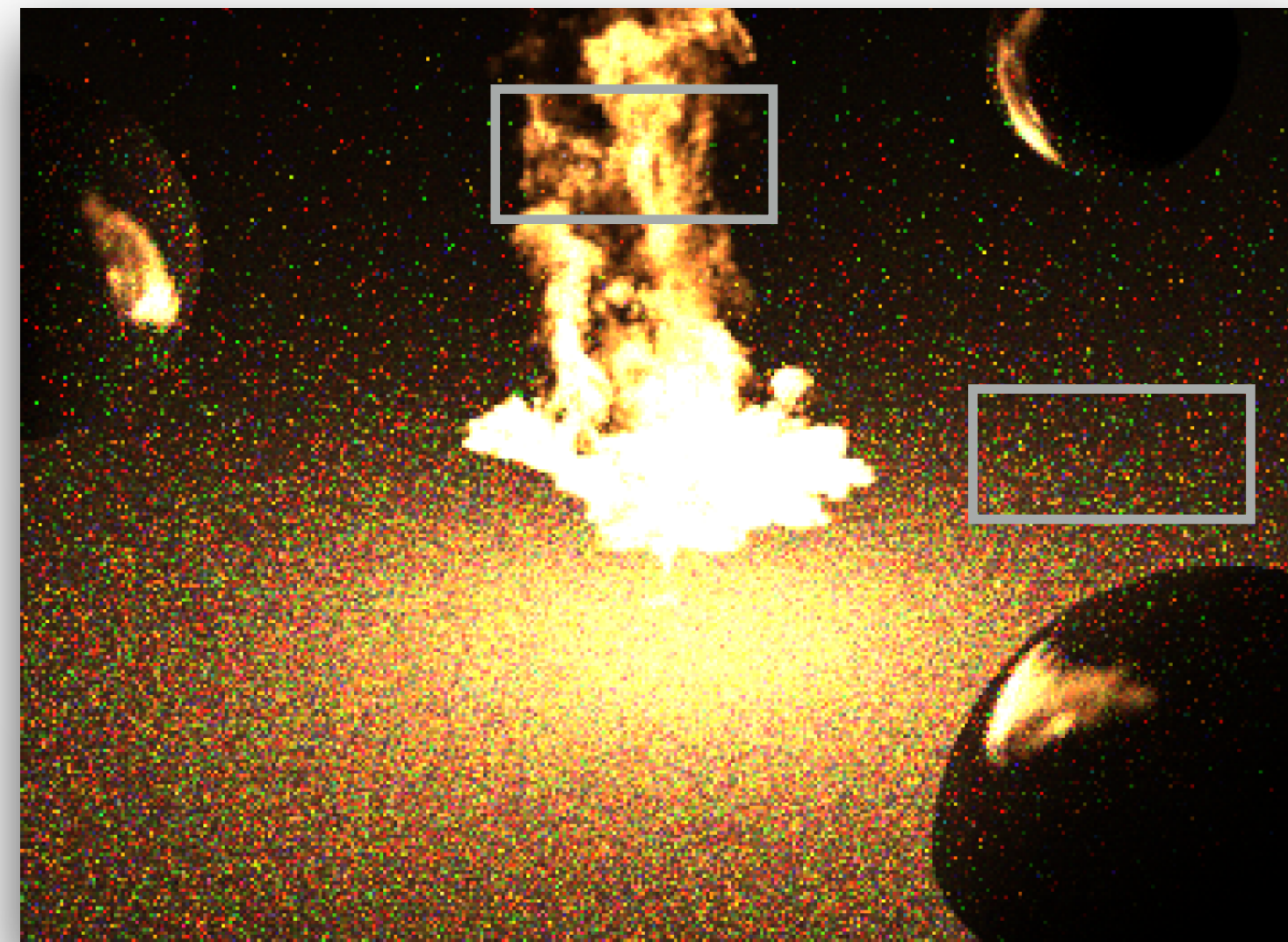
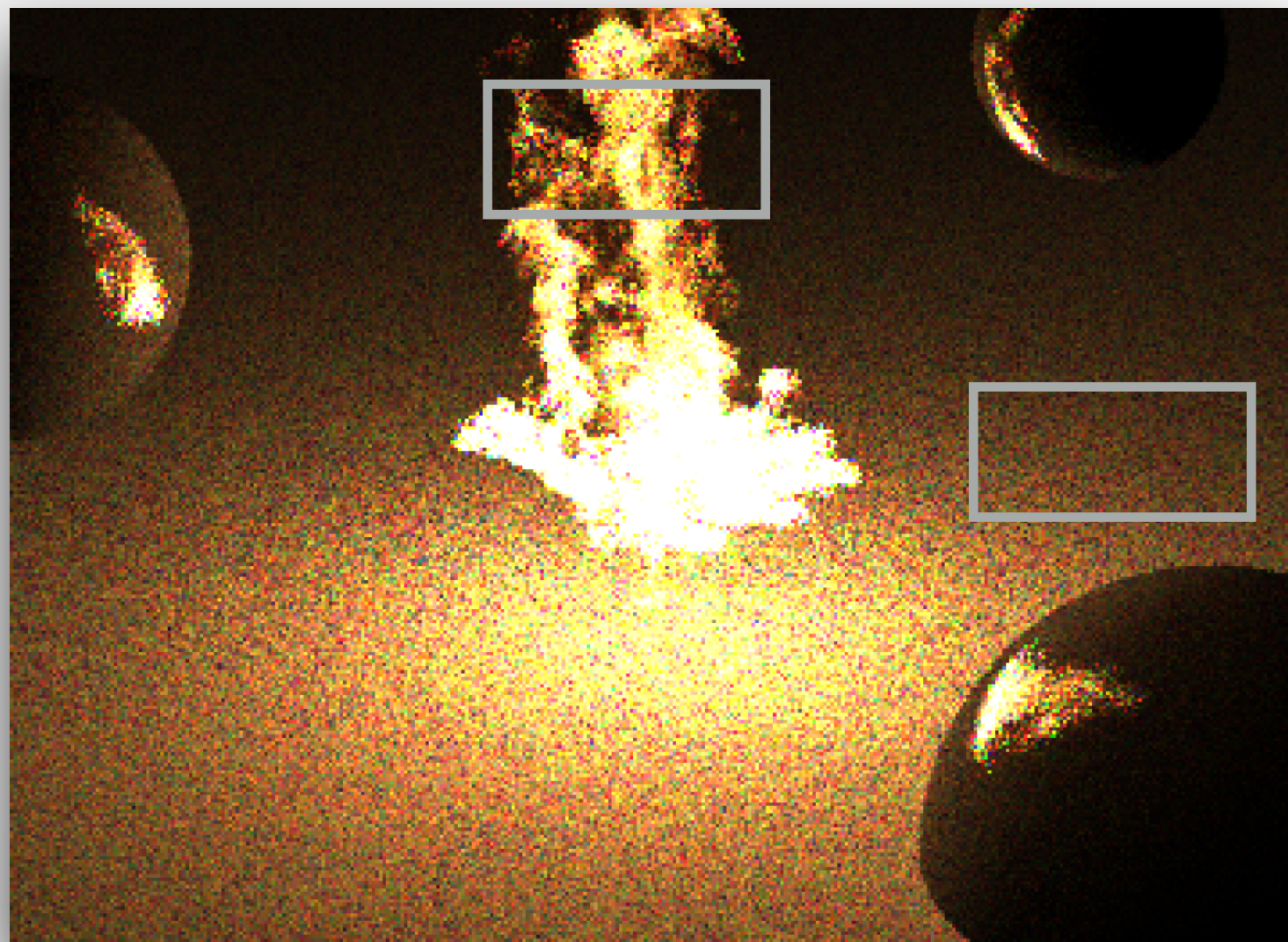


Next Event Estimation

- Line integration does not work well with NEE
- Idea: modify NEE to be able to create no-collision paths

Point + NEE

Line + NEE



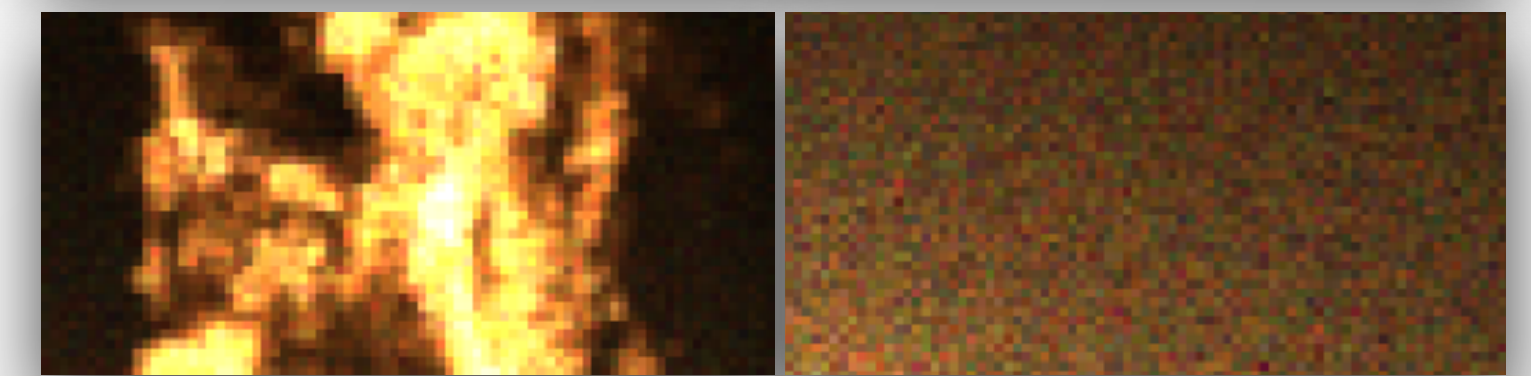
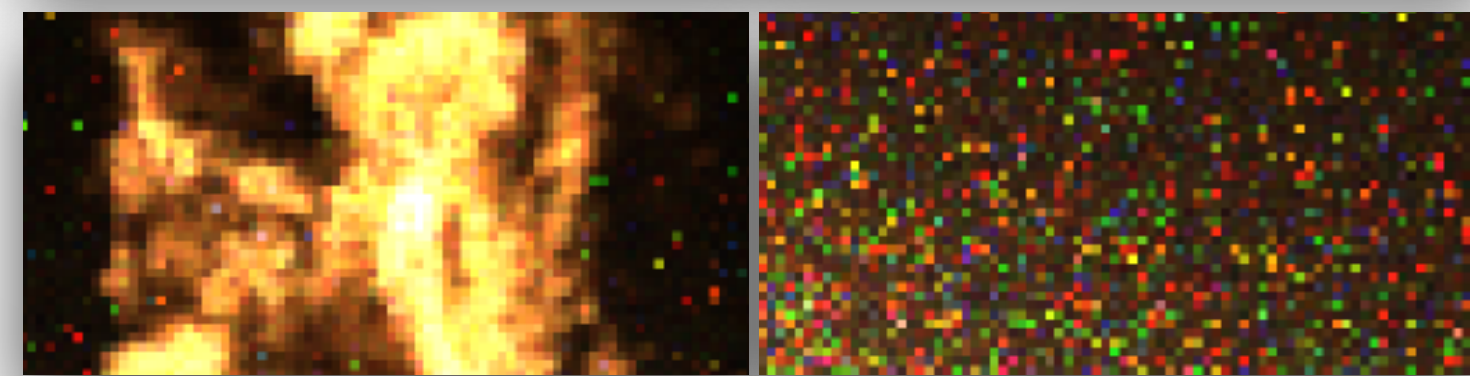
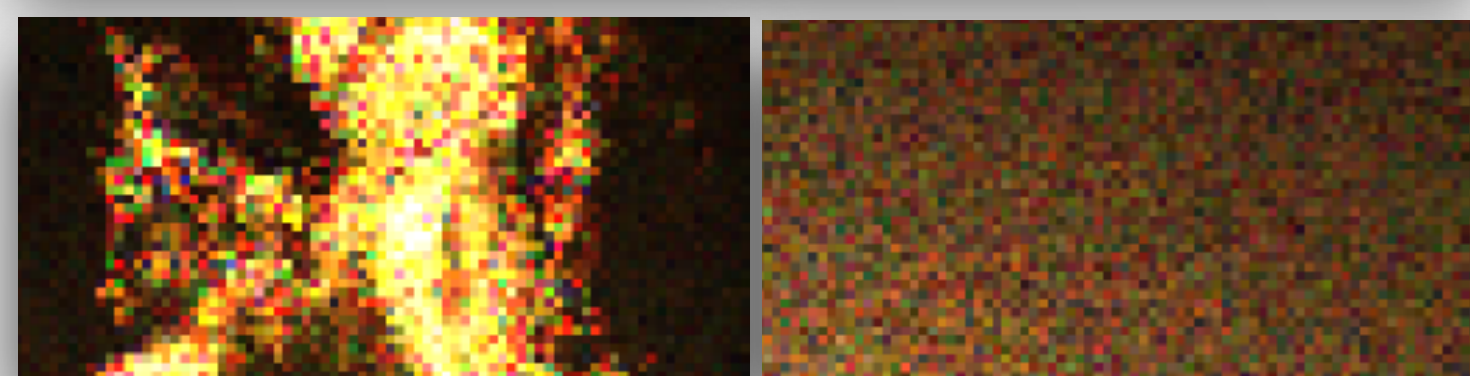
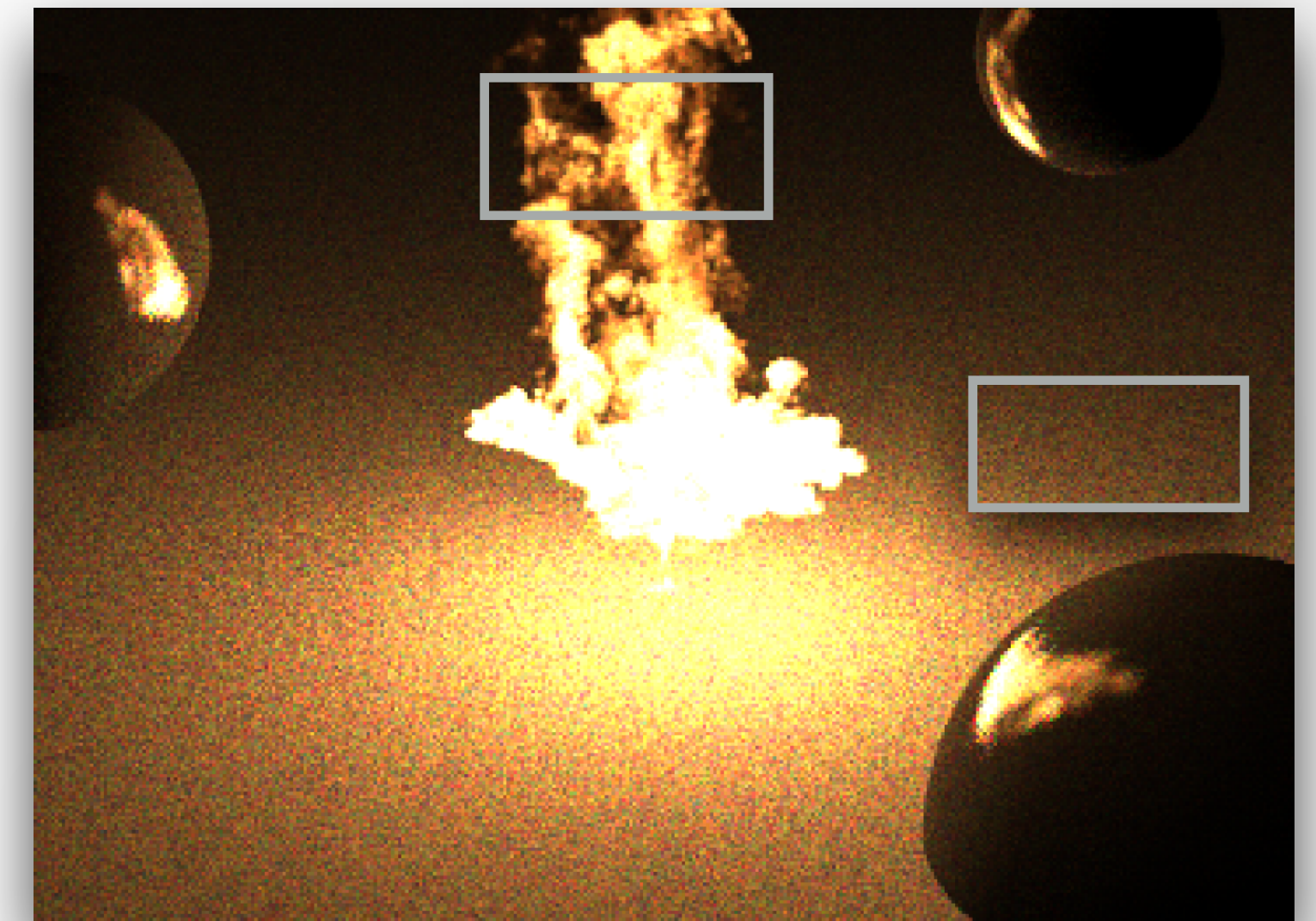
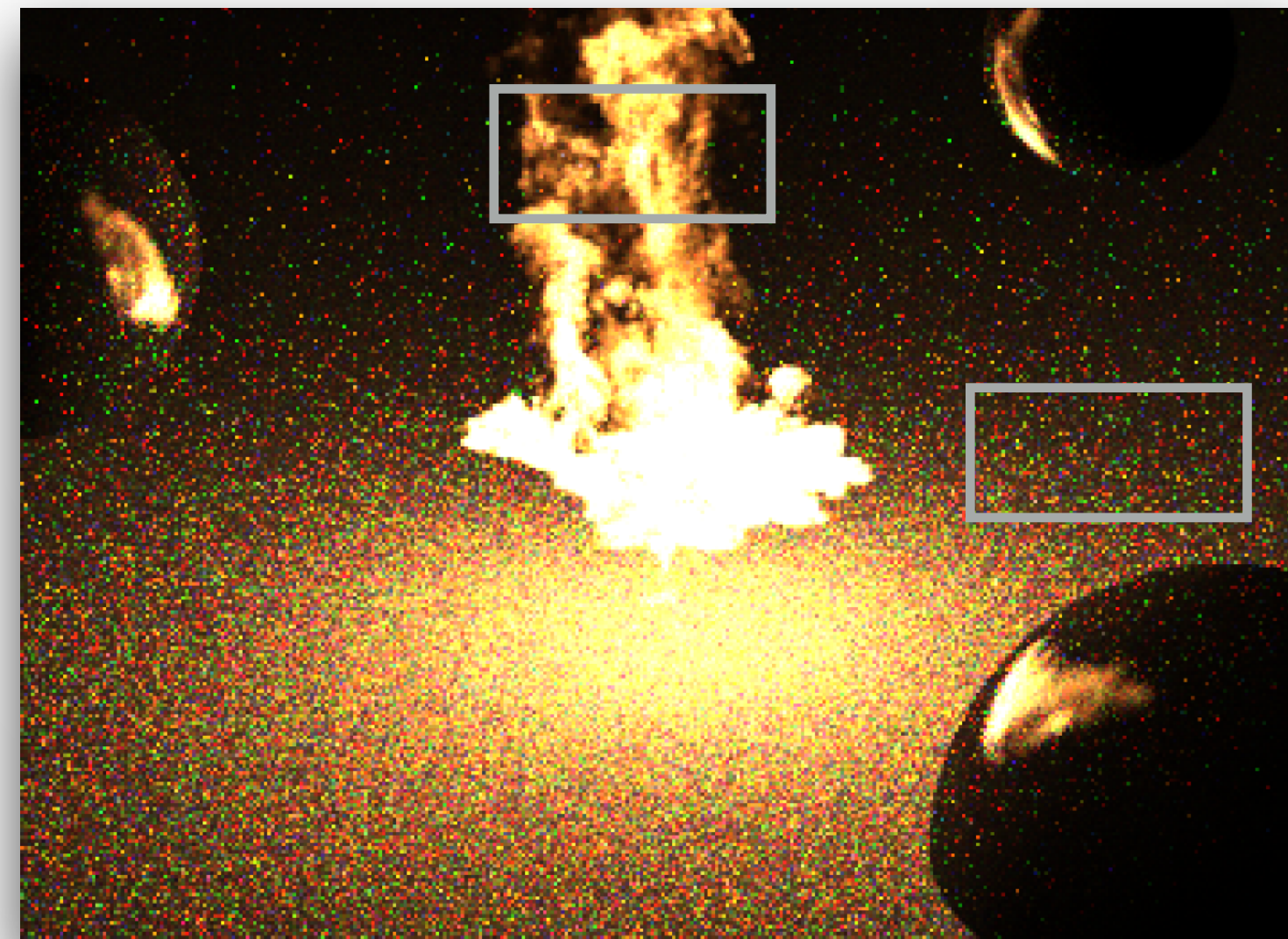
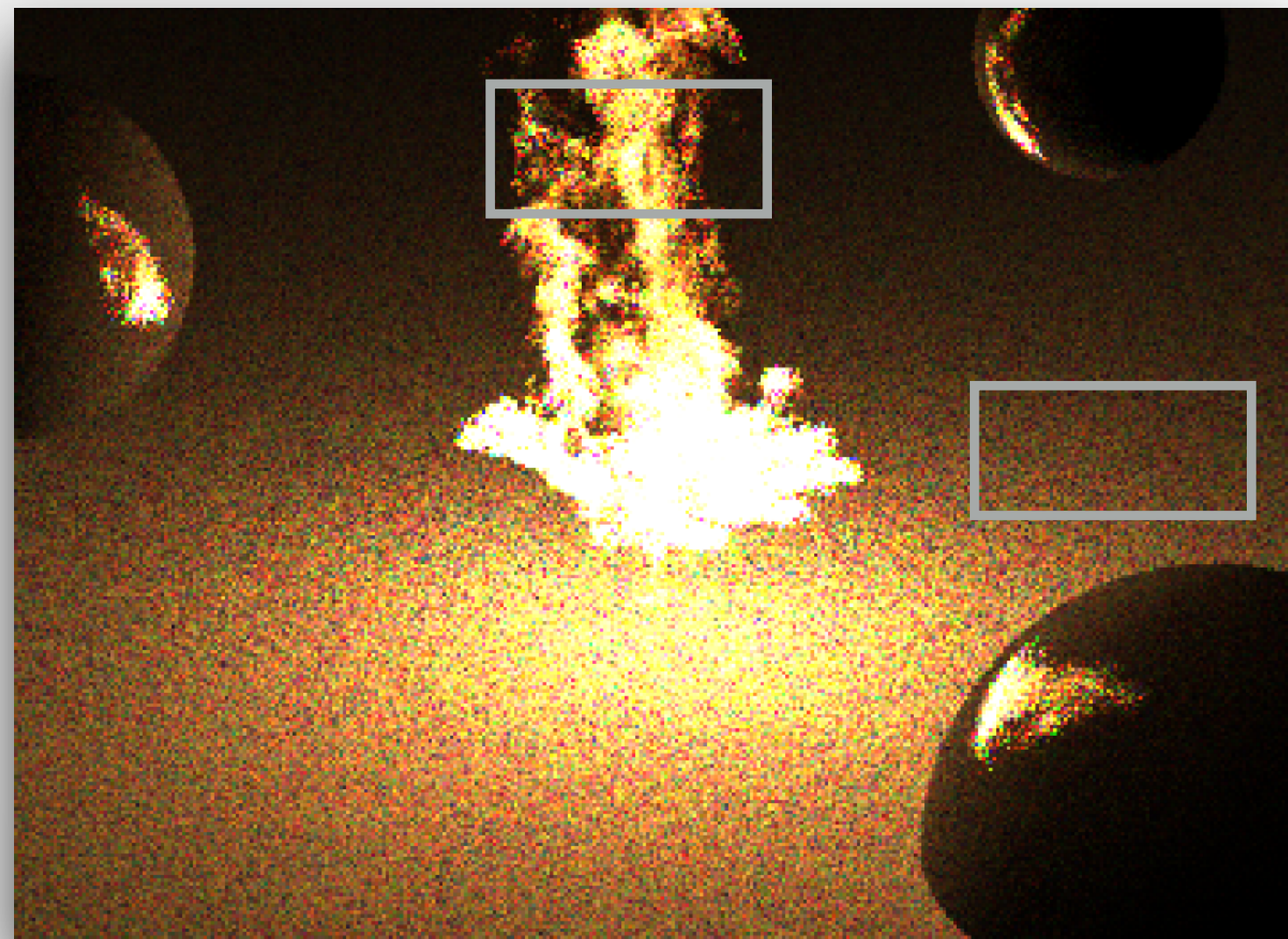
Next Event Estimation

- Line integration does not work well with NEE
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Point + NEE

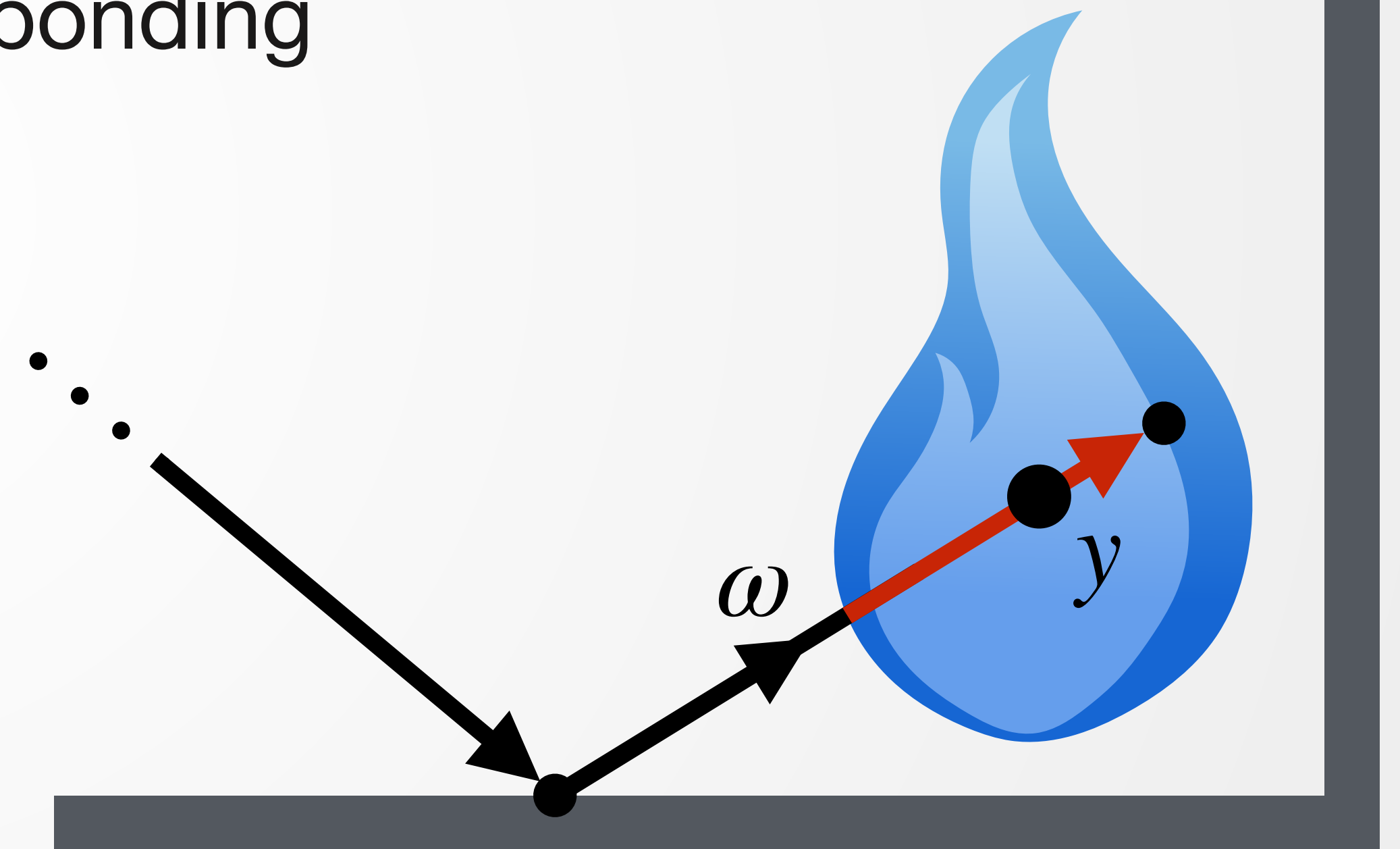
Line + NEE

Line + FNEE



Forward Next Event Estimation

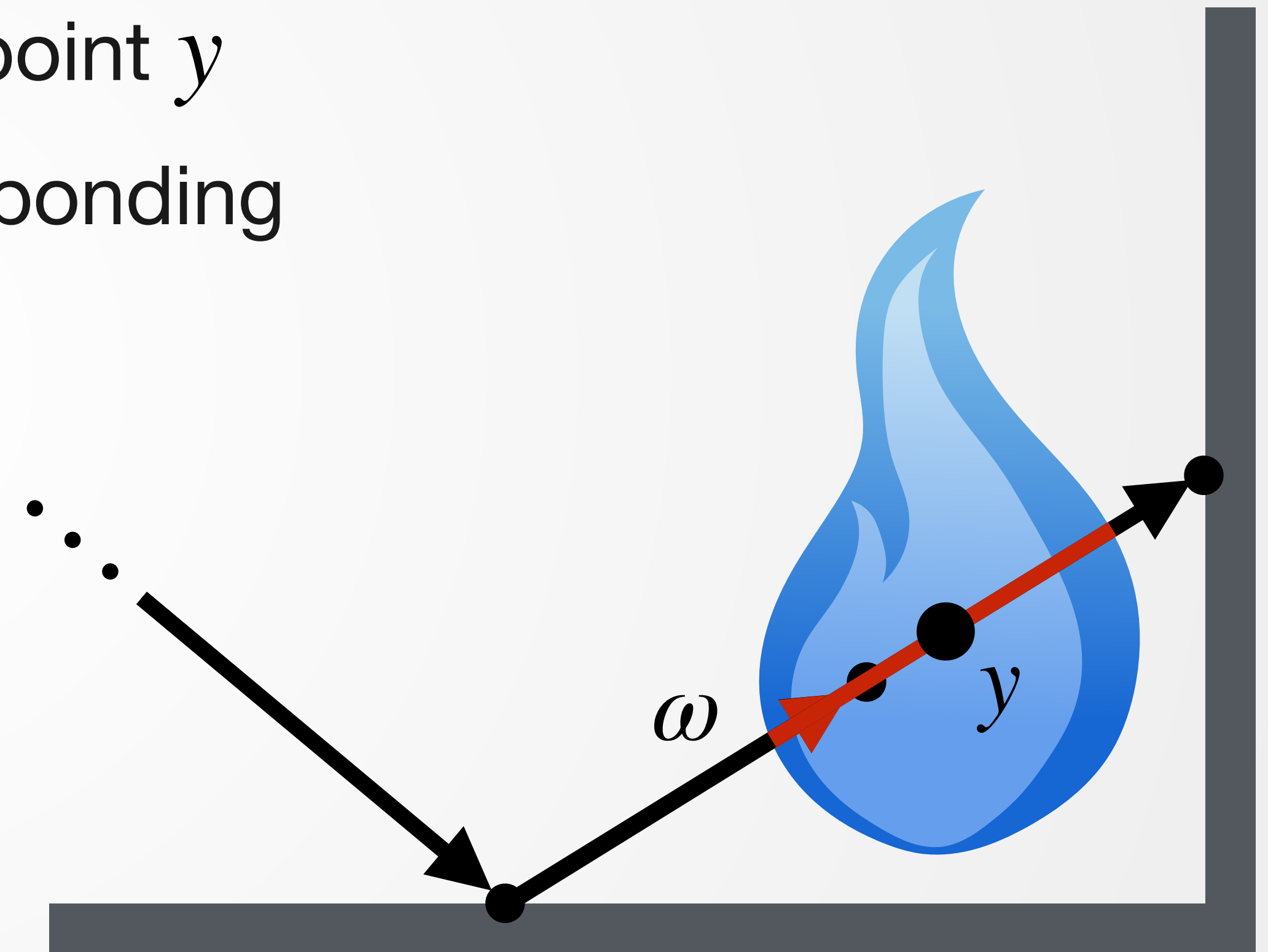
- Combine forward and NEE sampling by
 - first: importance sampling of an emissive point y
 - then: transmittance sampling in the corresponding direction ω
- Advantages



forward next event estimation

Forward Next Event Estimation

- Combine forward and NEE sampling by
 - first: importance sampling of an emissive point y
 - then: transmittance sampling in the corresponding direction ω
- Advantages
 - Allows no-collision paths
 - Shorter segments in dense volumes



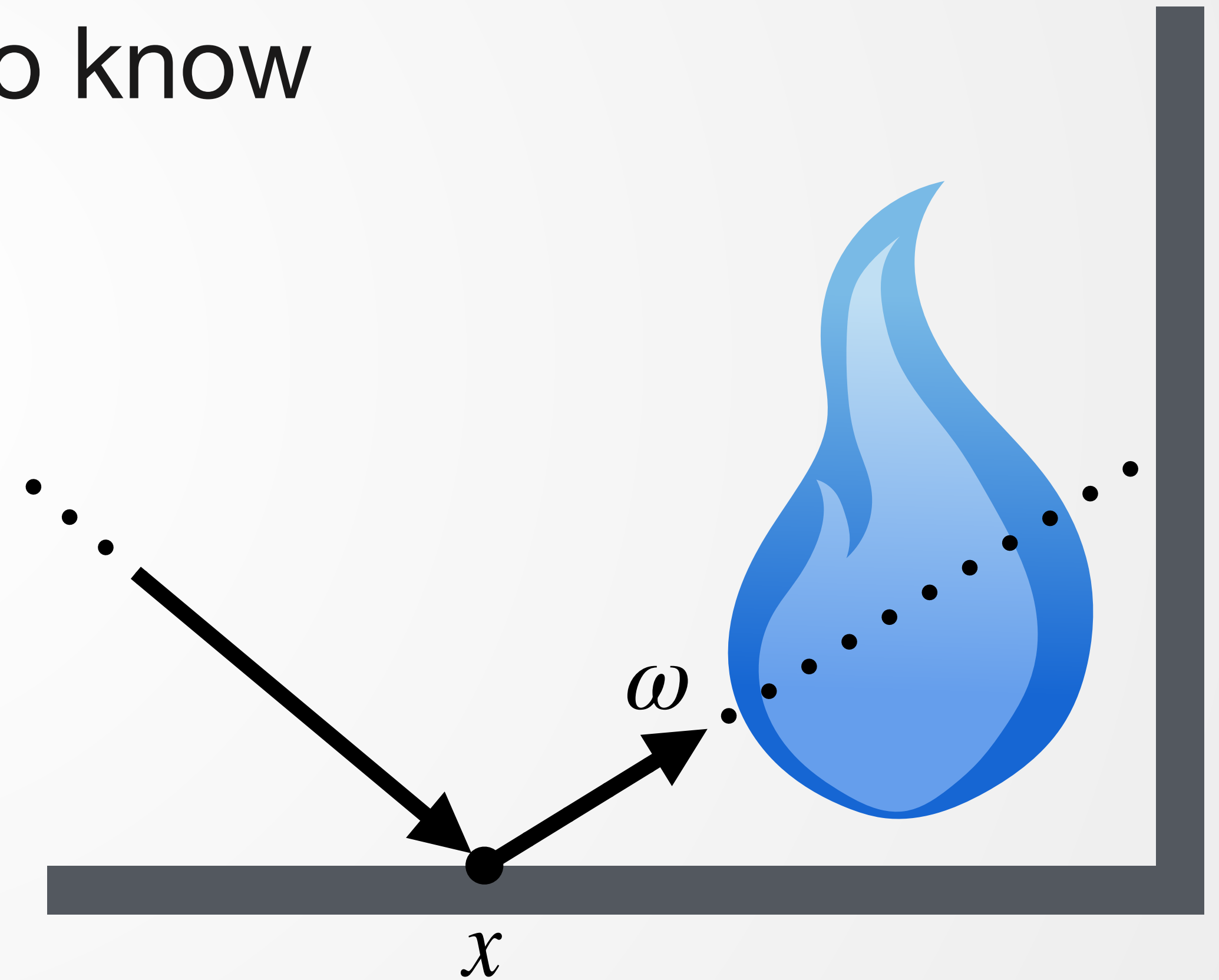
forward next event estimation

Forward Next Event Estimation

- Problem: Multiple points correspond to the same direction
- For the final path PDF we need to know

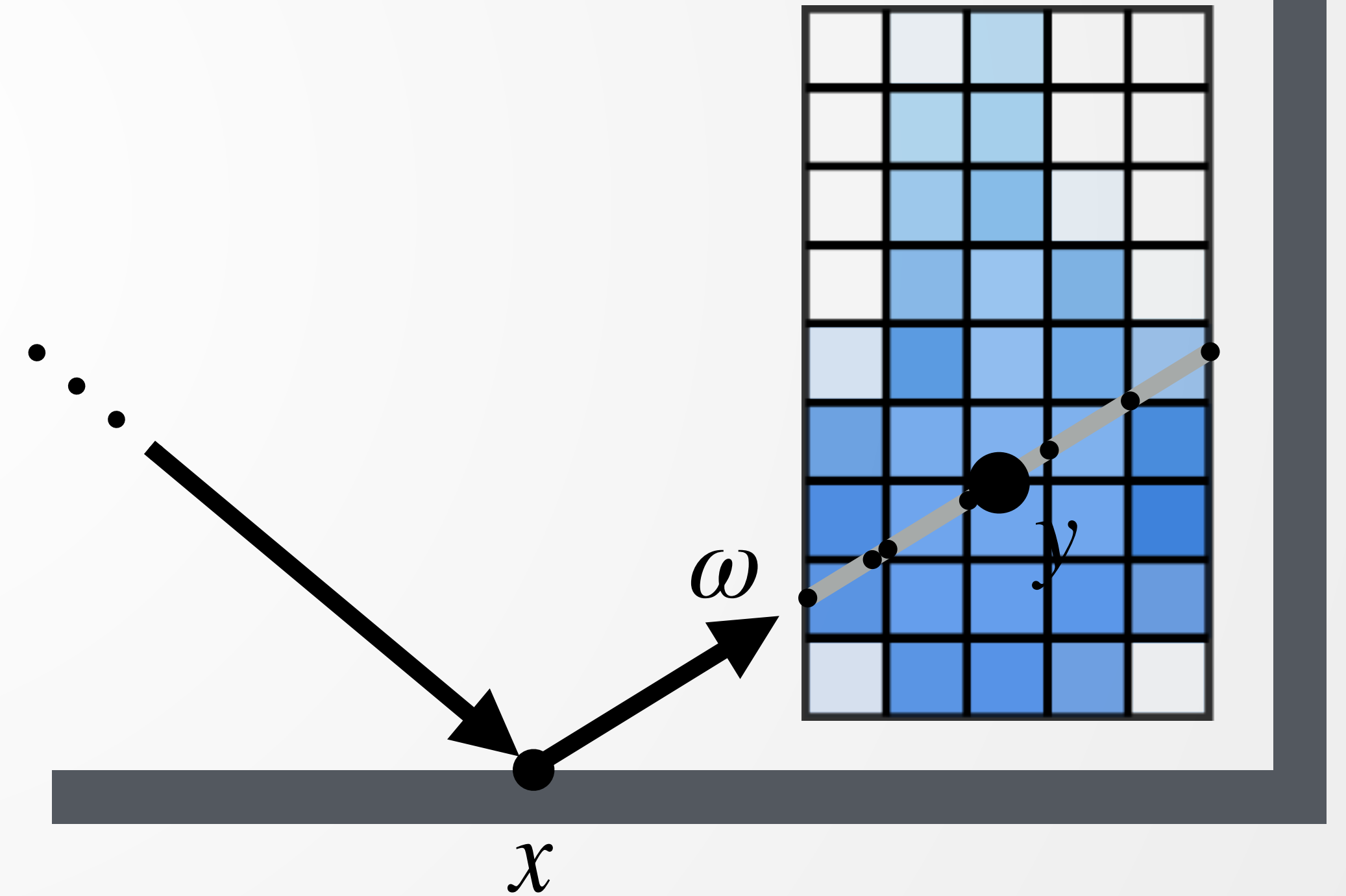
$$p_{\sigma}(\omega) = \int_0^{\infty} p_V(x + \omega t) t^2 dt$$

- Too expensive to evaluate all the time



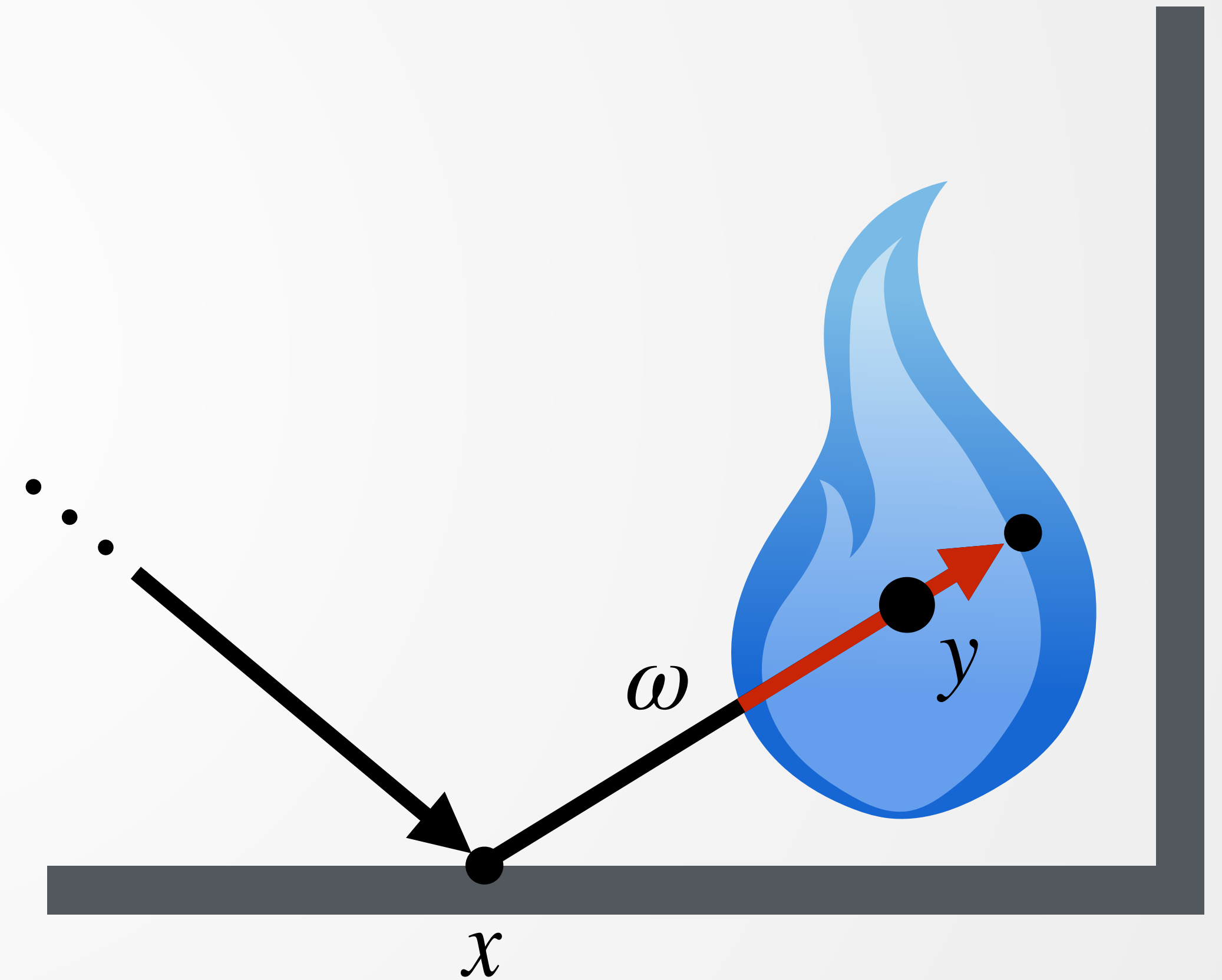
Forward Next Event Estimation

- Solution: Low resolution volume for
 - Initial point sampling
 - PDF integration



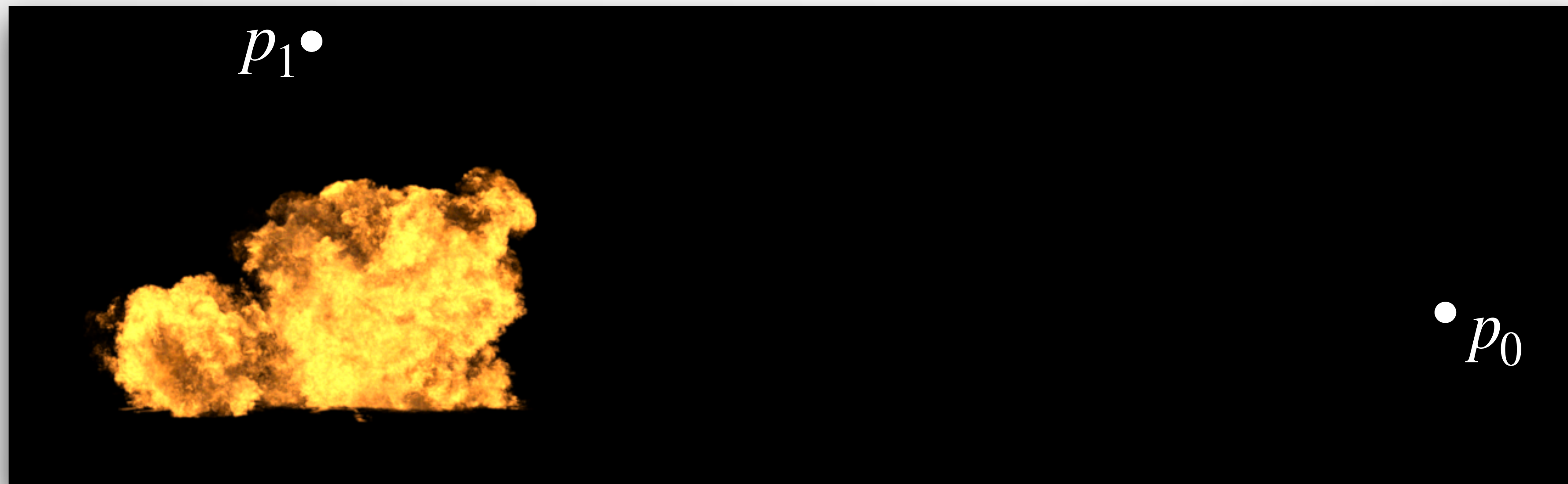
Forward Next Event Estimation

- Solution: Low resolution volume for
 - Initial point sampling
 - PDF integration
- On original resolution
 - Free path sampling
 - Line integration



FNEE Test

- Irradiance computed for two points
- RMSE comparison of
 - NEE with point integration
 - FNEE with line integration for 4096^3 , 512^3 , 64^3

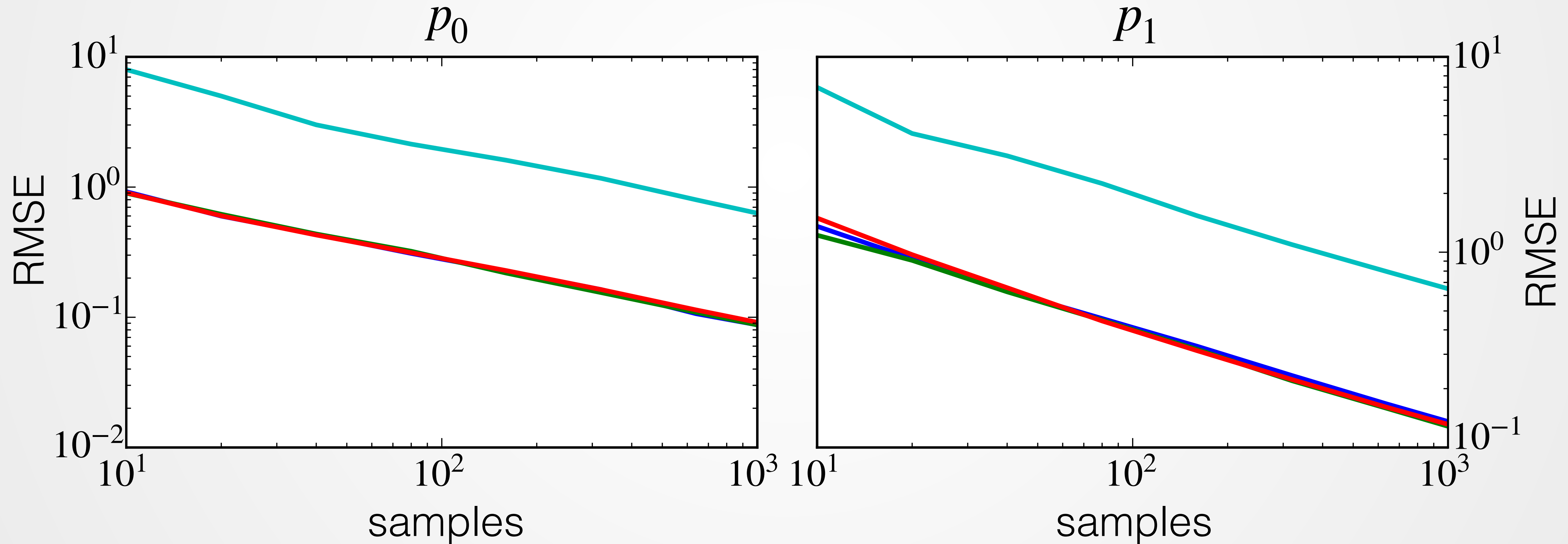


FNEE Test

- NEE
- FNEE 4096^3
- FNEE 512^3
- FNEE 64^3



- Equal-sample RMSE

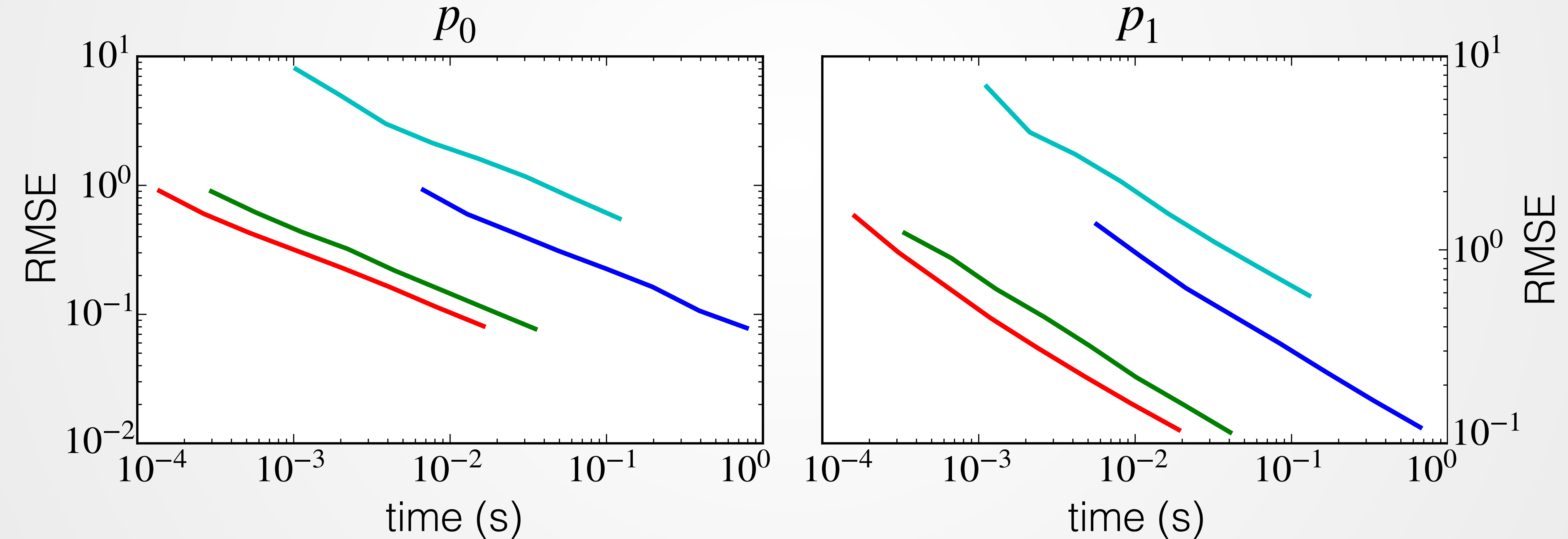


FNEE Test

- NEE
- FNEE 4096^3
- FNEE 512^3
- FNEE 64^3



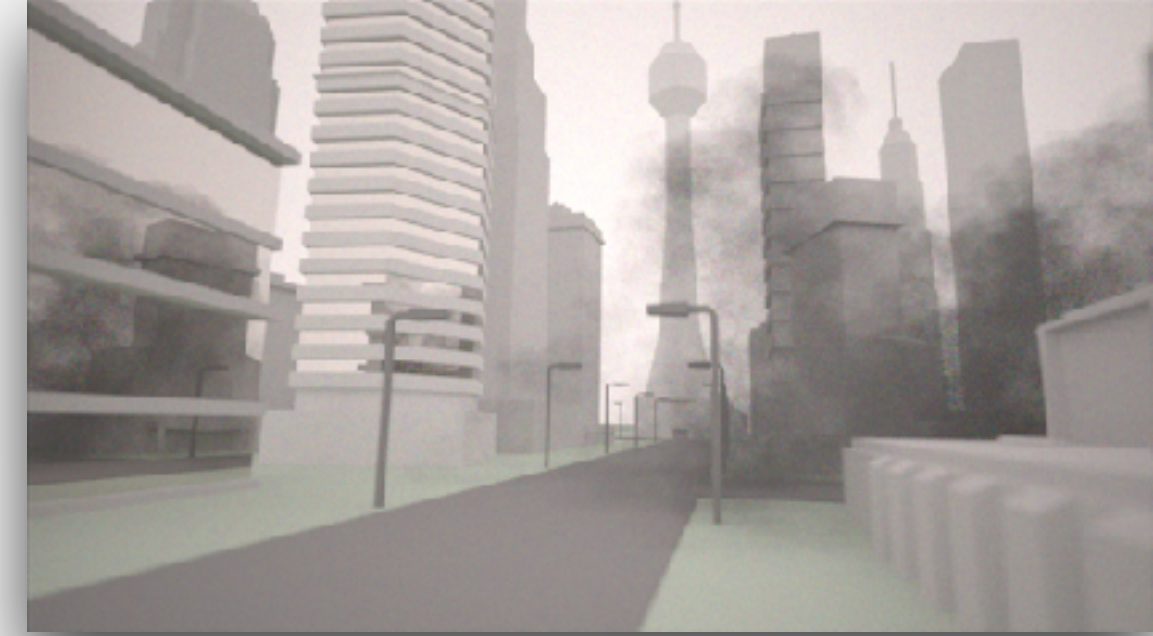
- Equal-time RMSE



Results

Results

- Explosion (thin) - equal time - 10min



Density



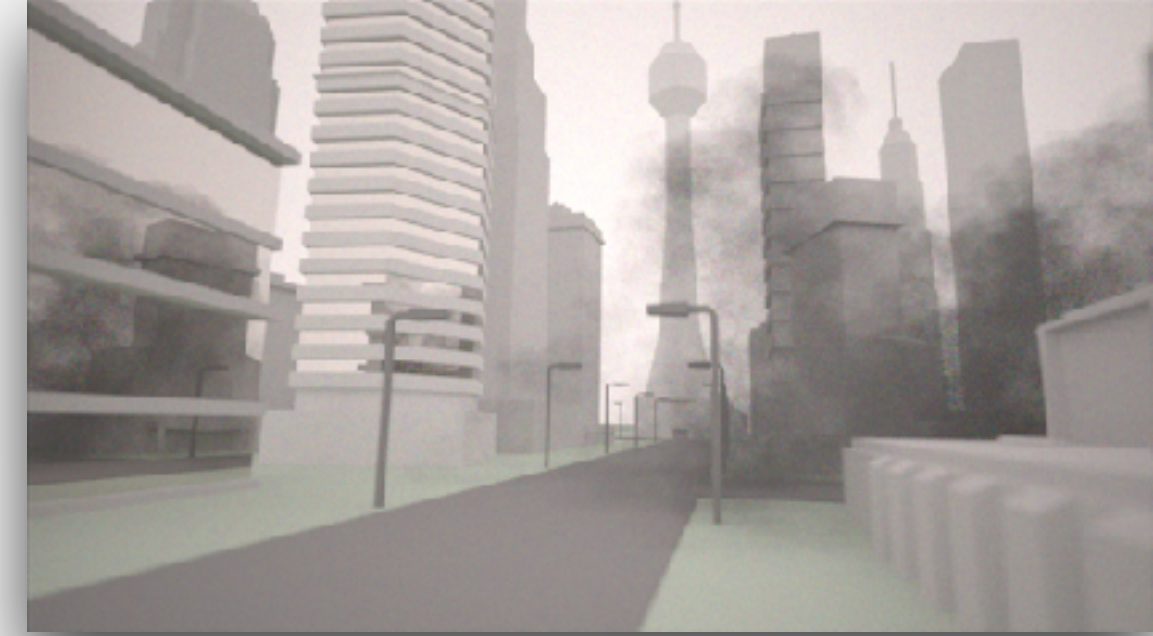
FNEE - RMSE 0.748 - 48spp



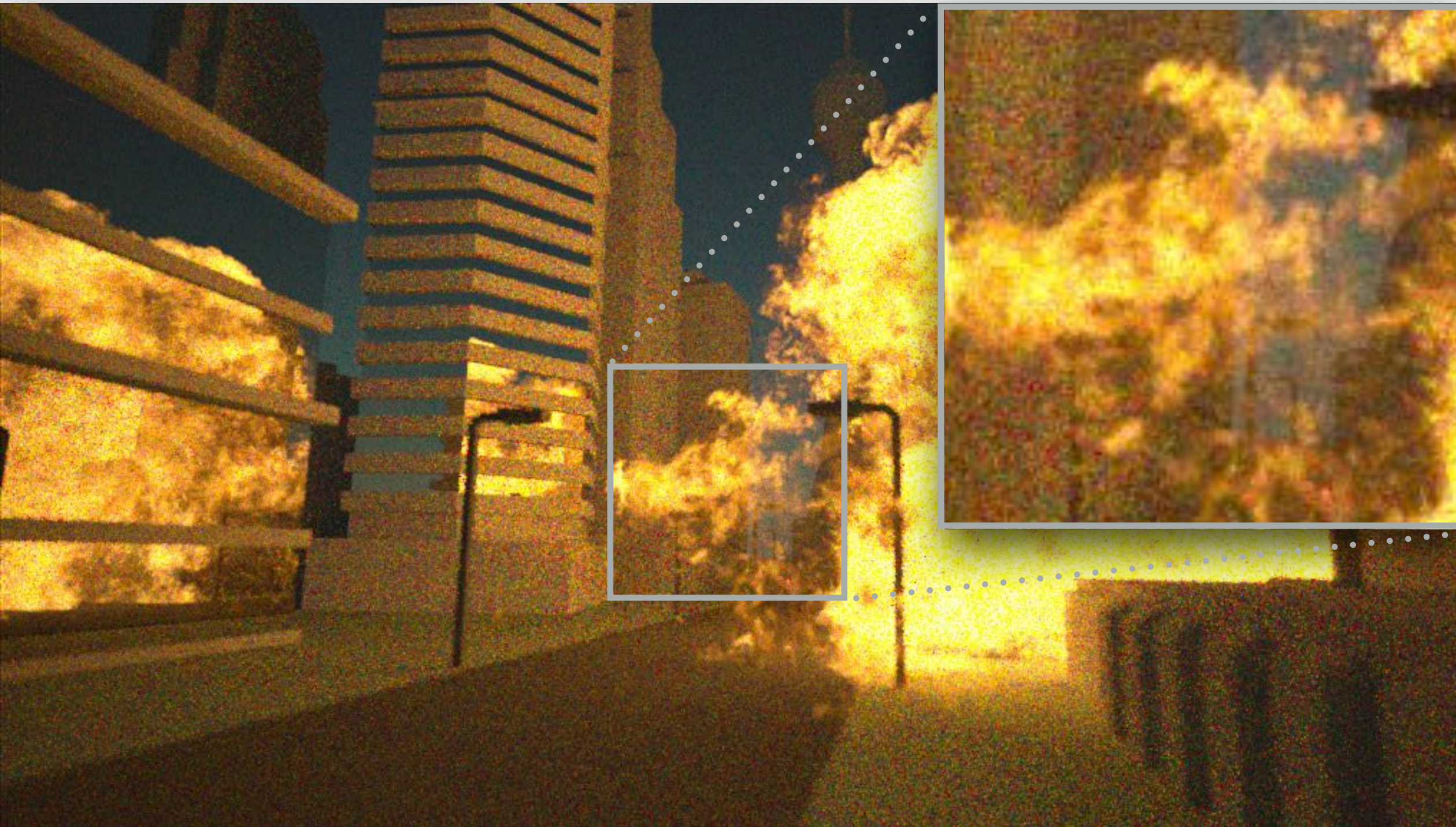
NEE - RMSE 0.983 - 43spp

Results

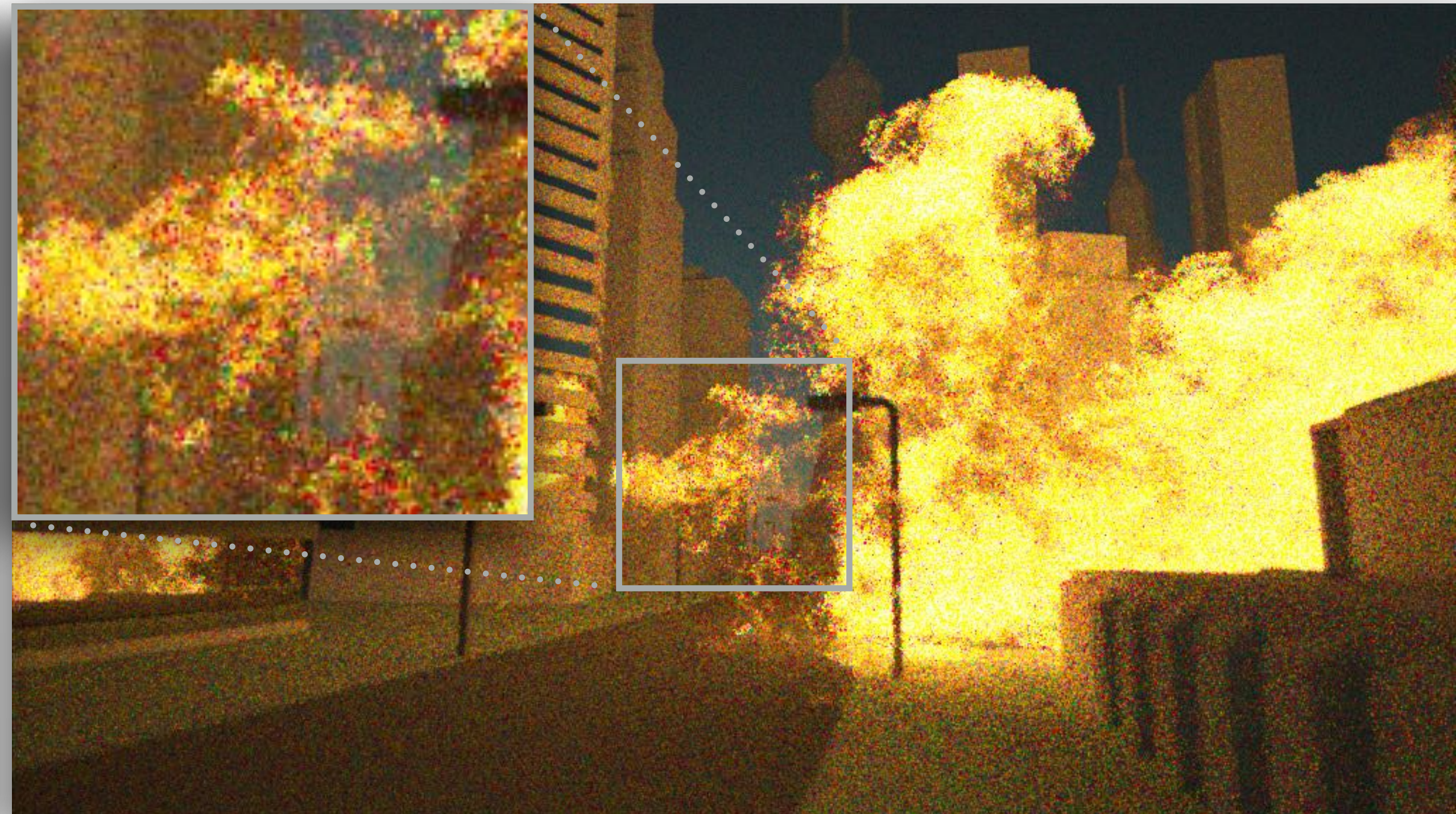
- Explosion (thin) - equal time - 10min



Density



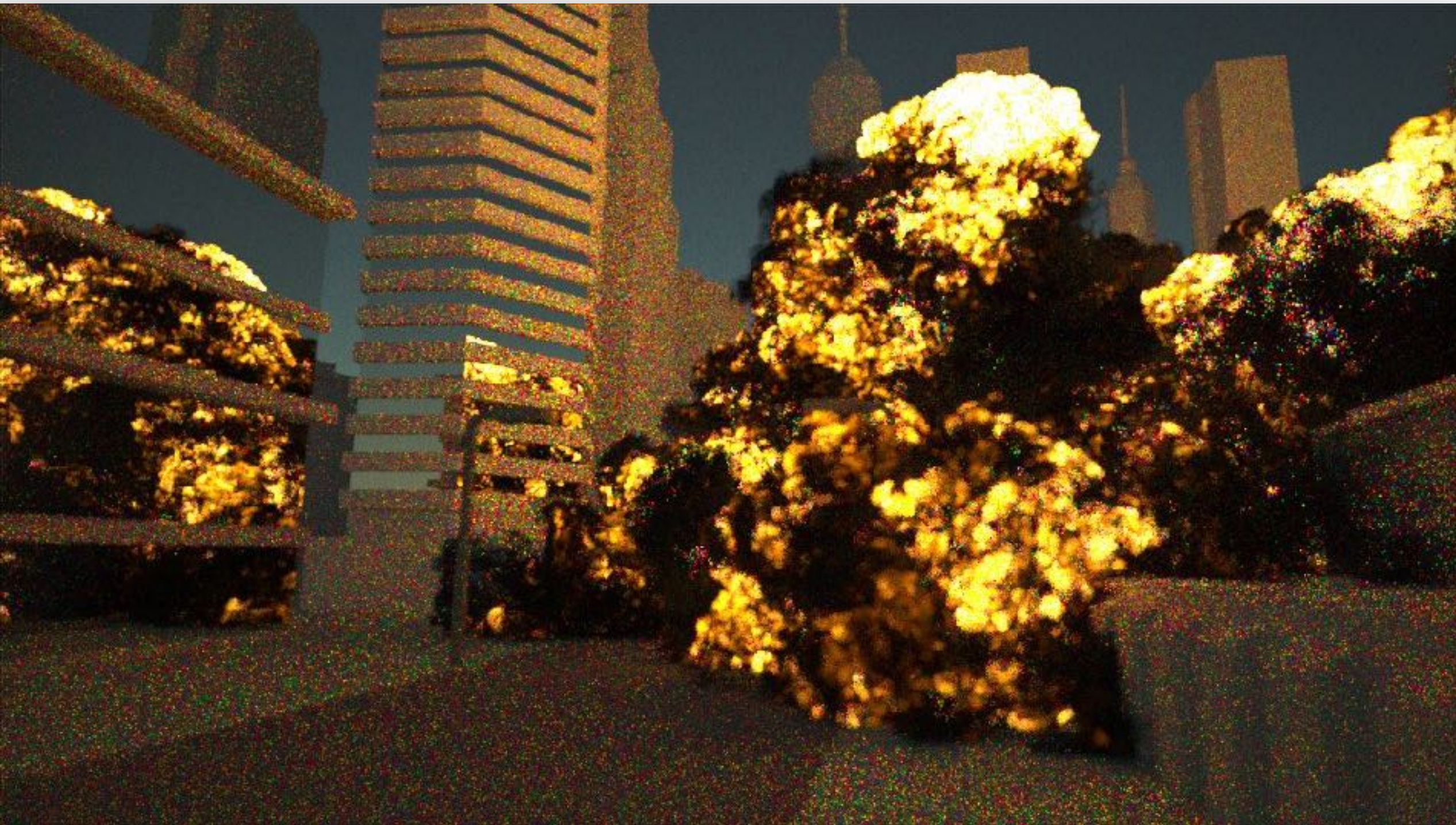
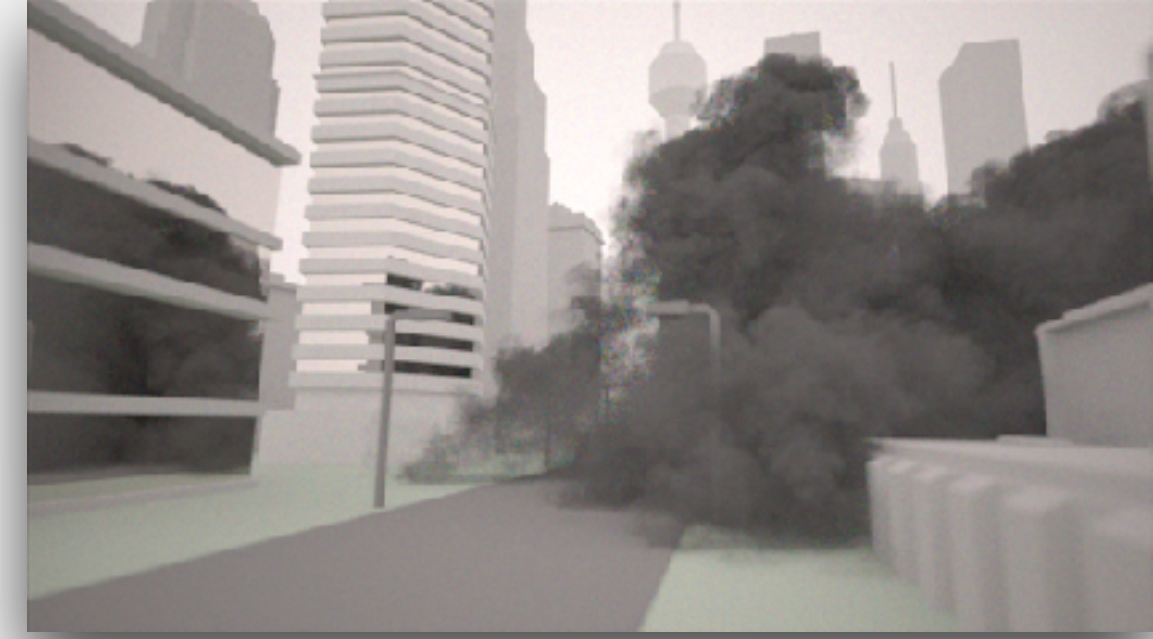
FNEE - RMSE 0.748 - 48spp



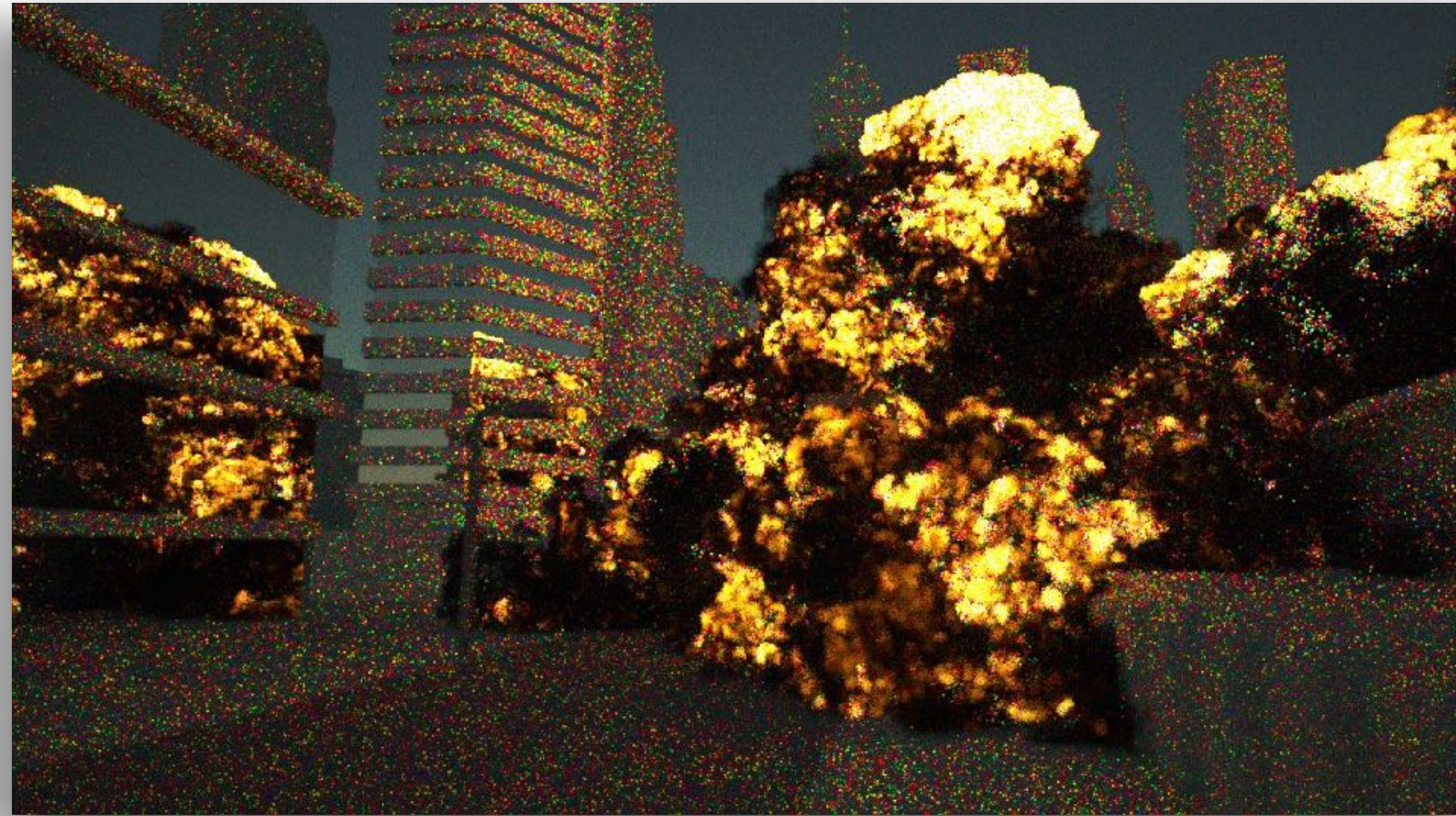
NEE - RMSE 0.983 - 43spp

Results

- Explosion (dense) - equal time - 30min



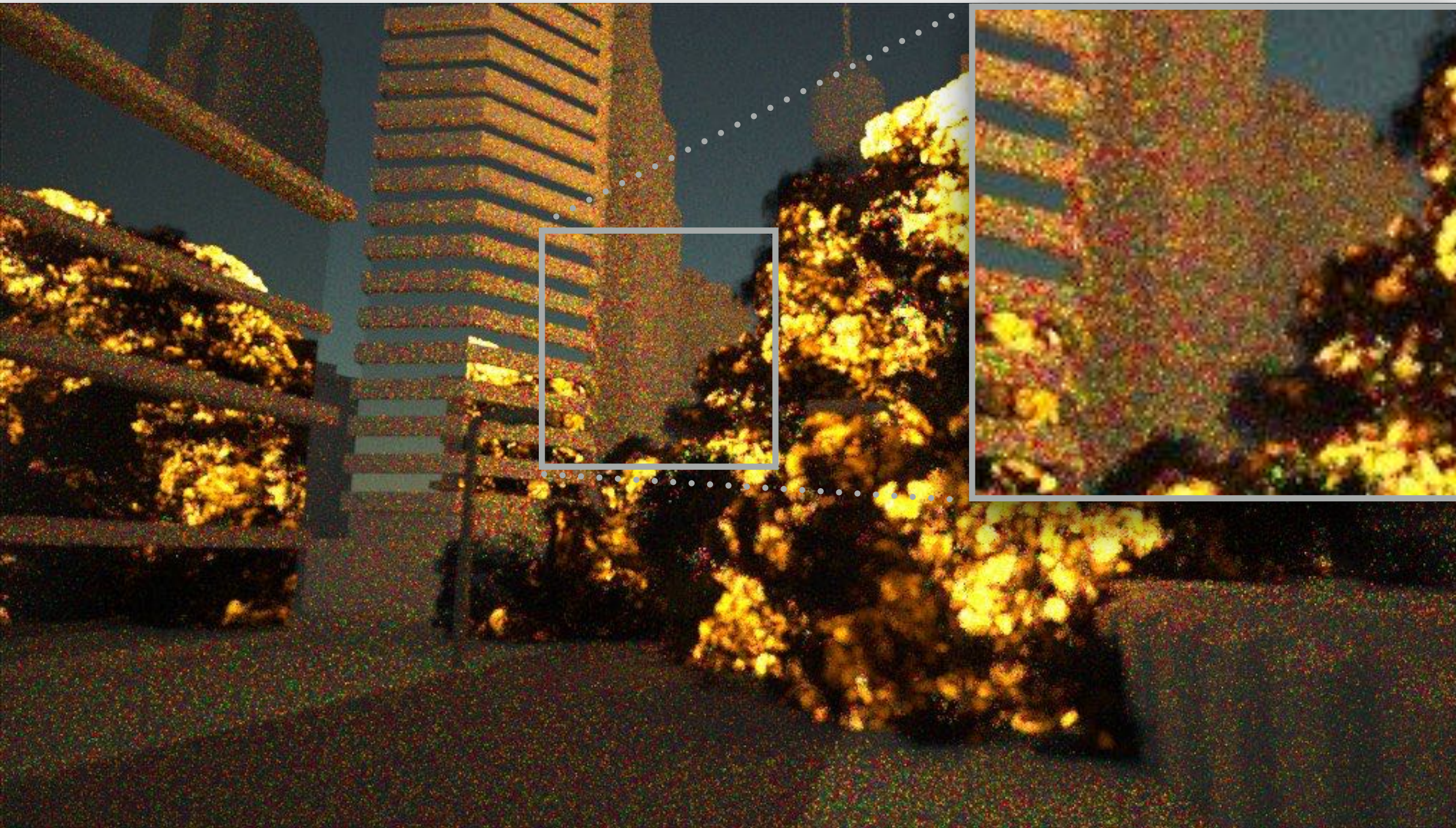
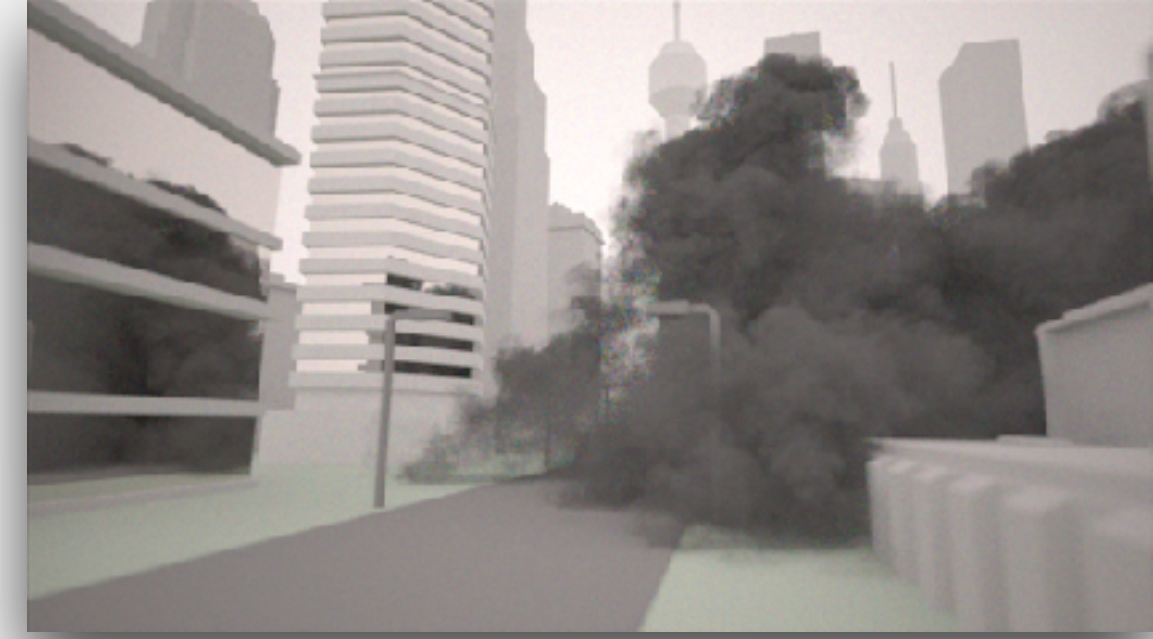
FNEE - RMSE 0.572 - 196spp



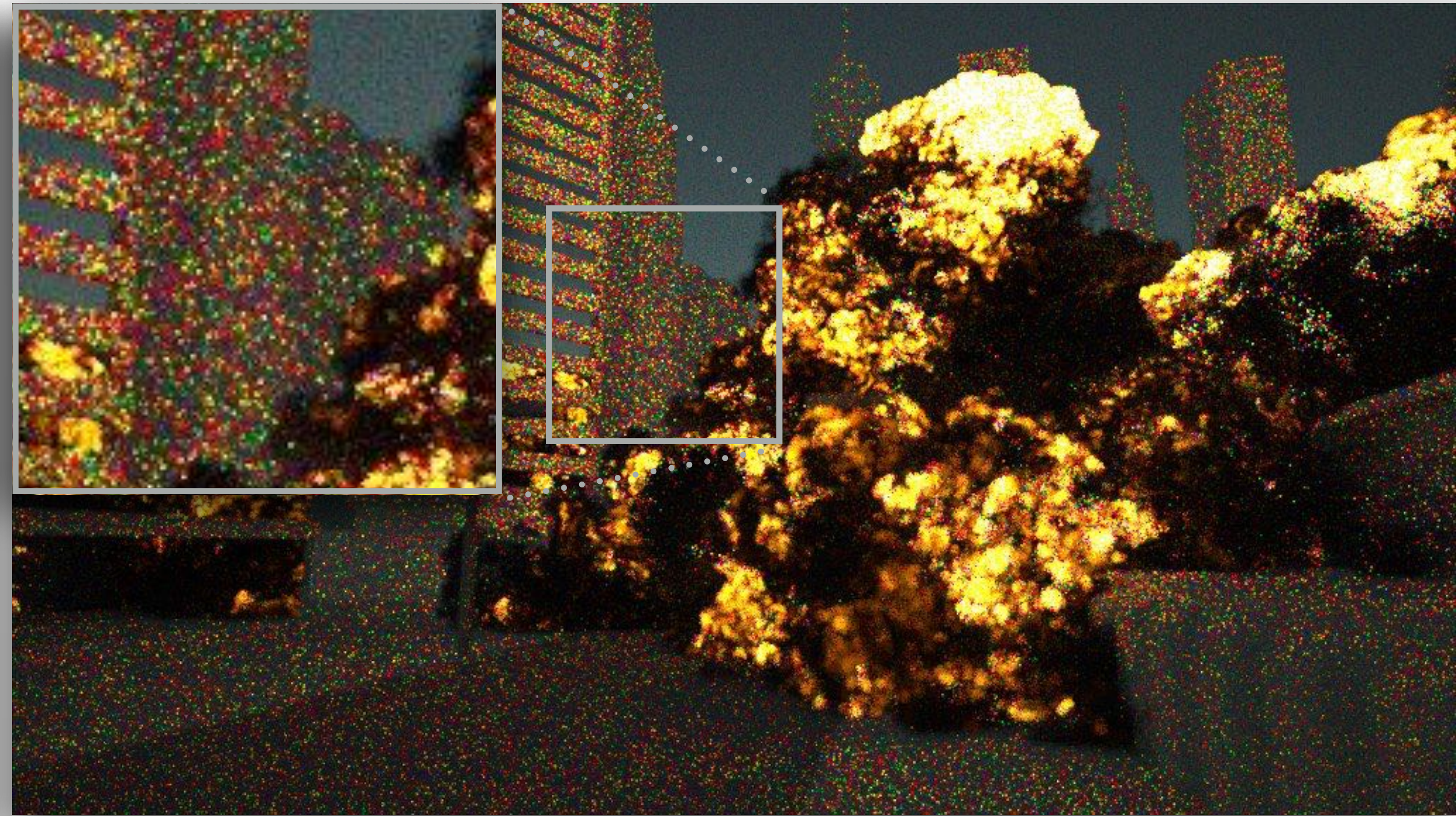
NEE - RMSE 0.892 - 73spp

Results

- Explosion (dense) - equal time - 30min



FNEE - RMSE 0.572 - 196spp



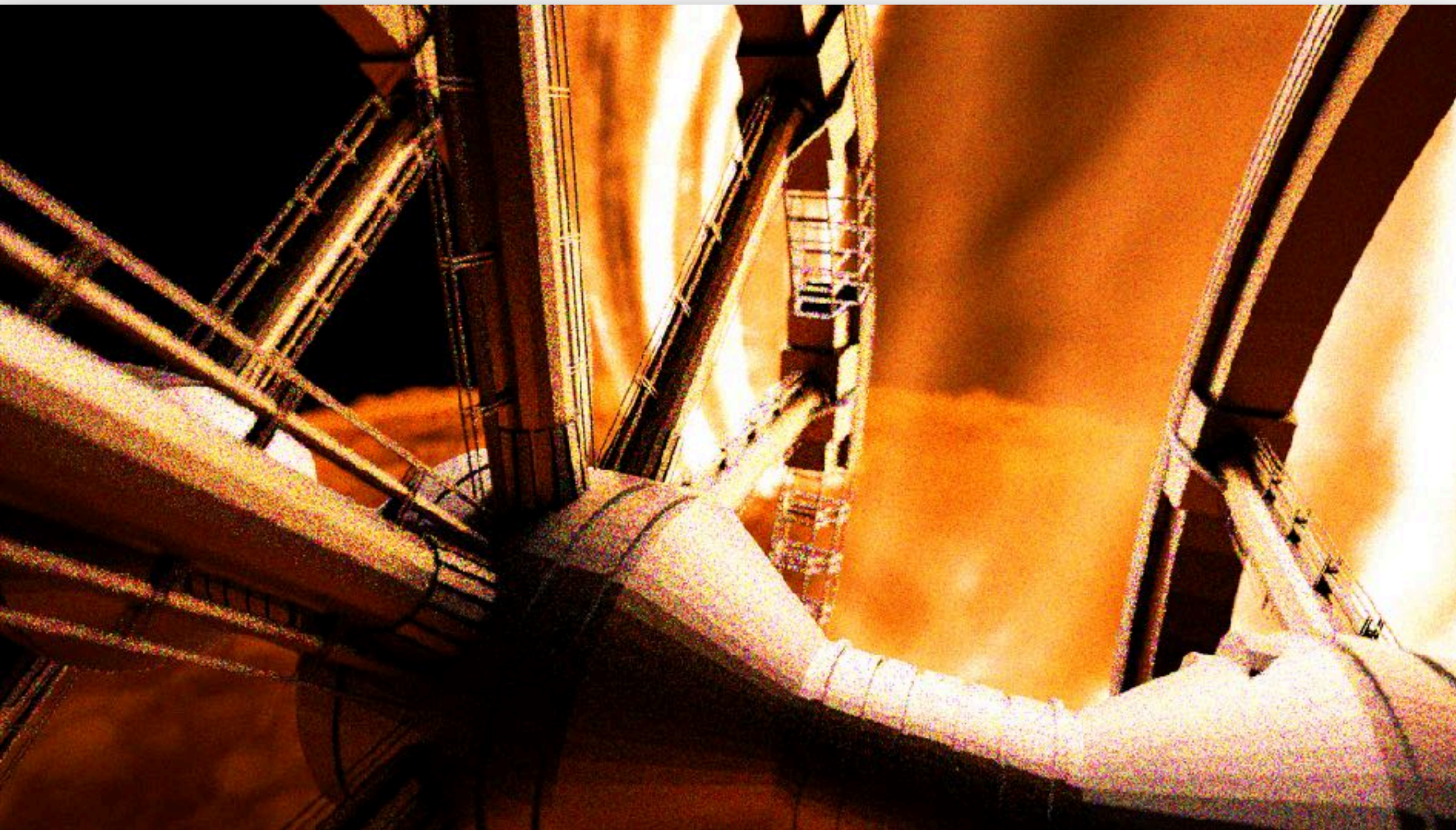
NEE - RMSE 0.892 - 73spp

Results

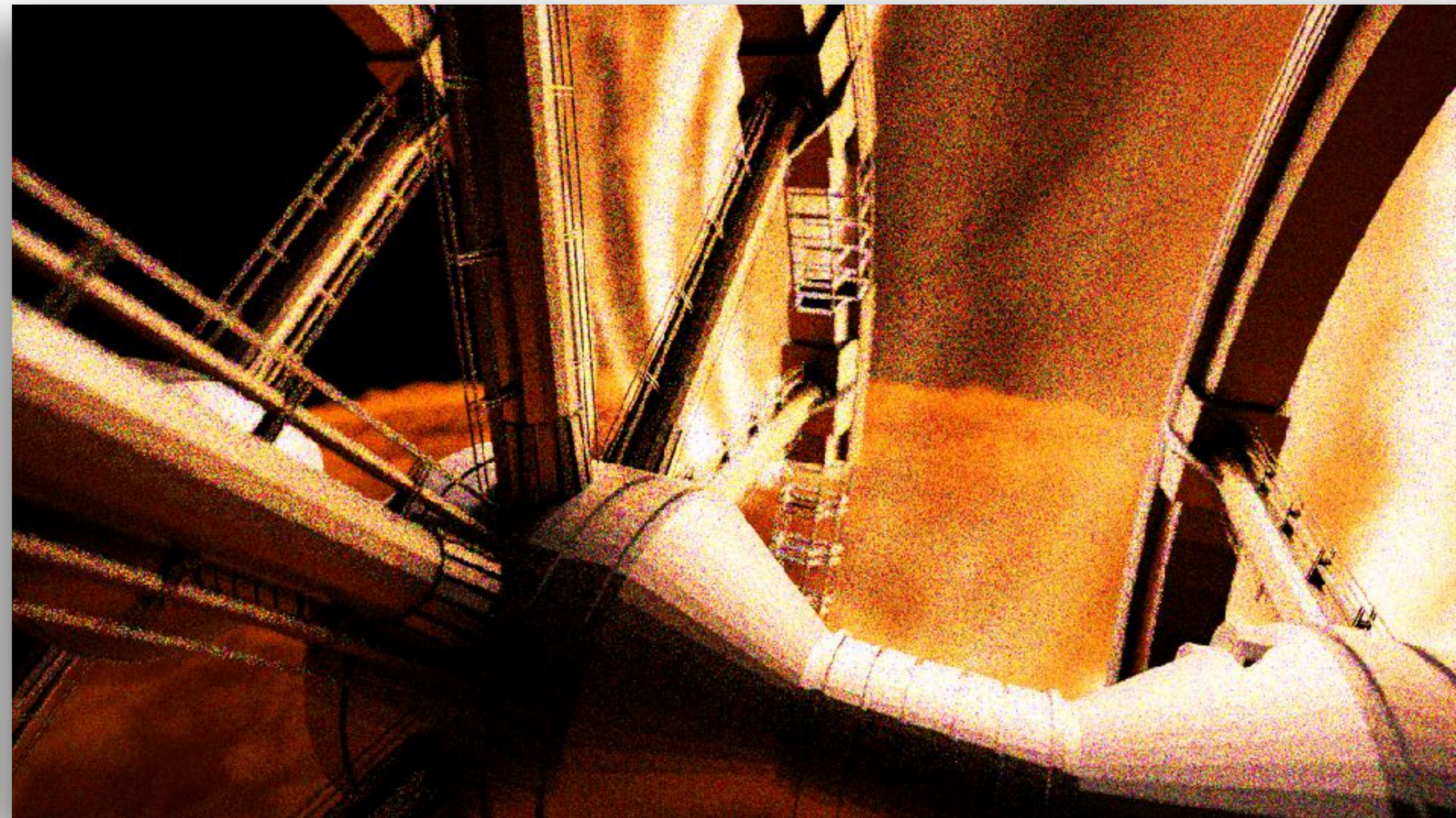
- Solar flare (30GB) - equal sample - 128spp



Overview



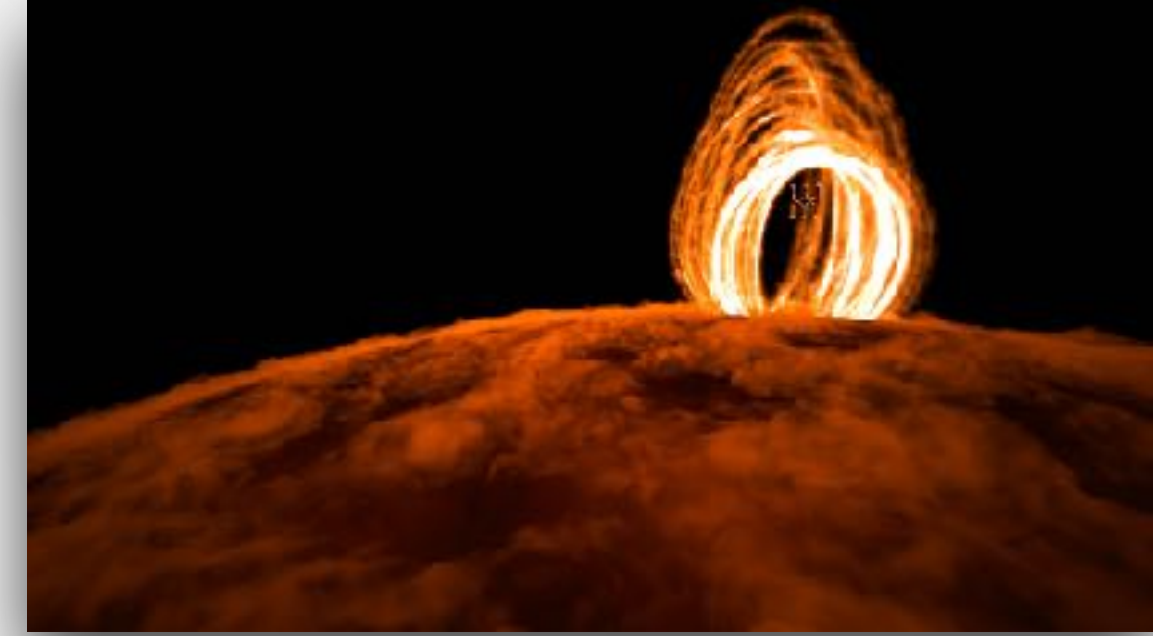
FNEE - RMSE 36.7 - 11.2 core hours



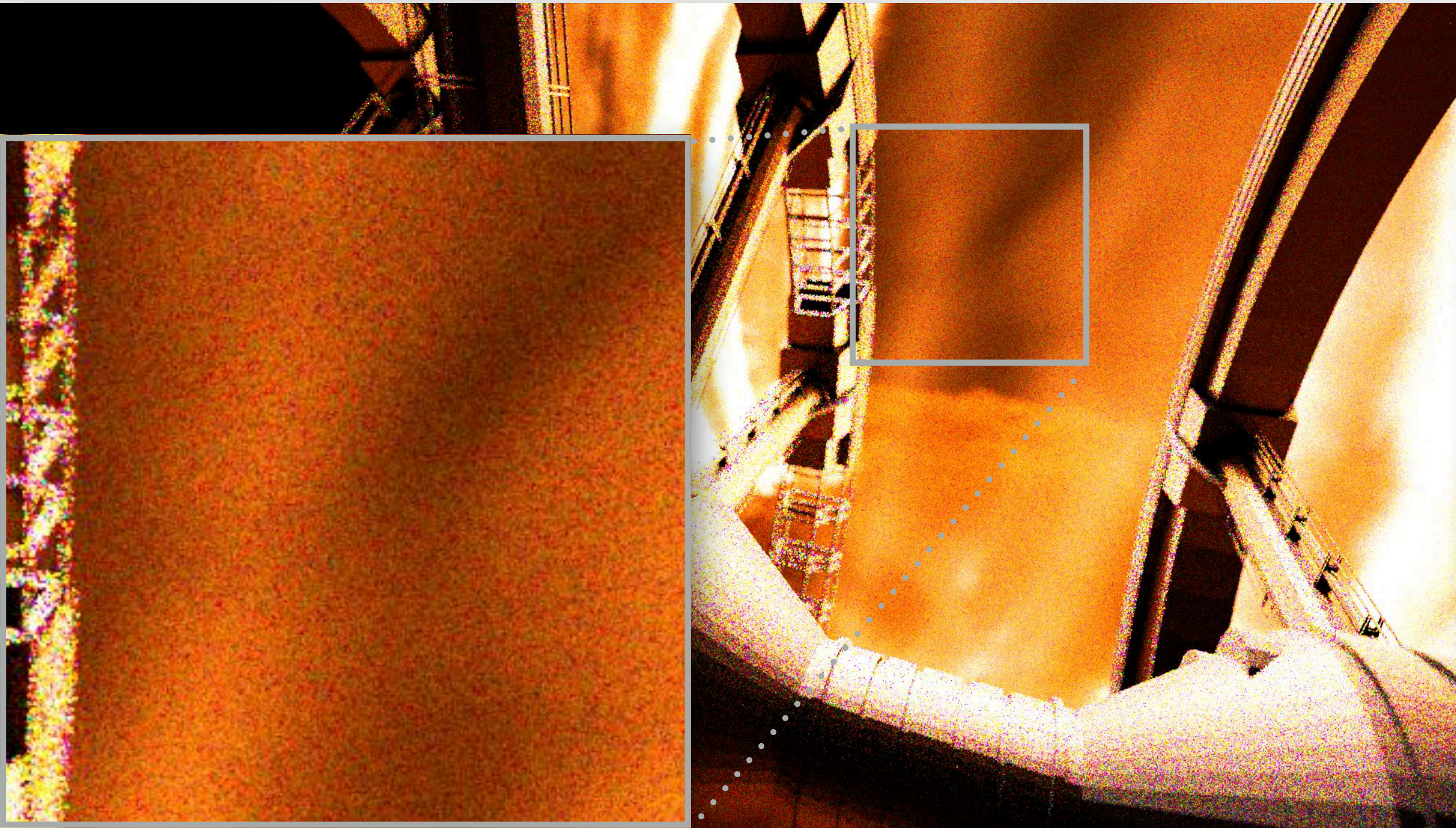
NEE - RMSE 52.6 - 7.5 core hours

Results

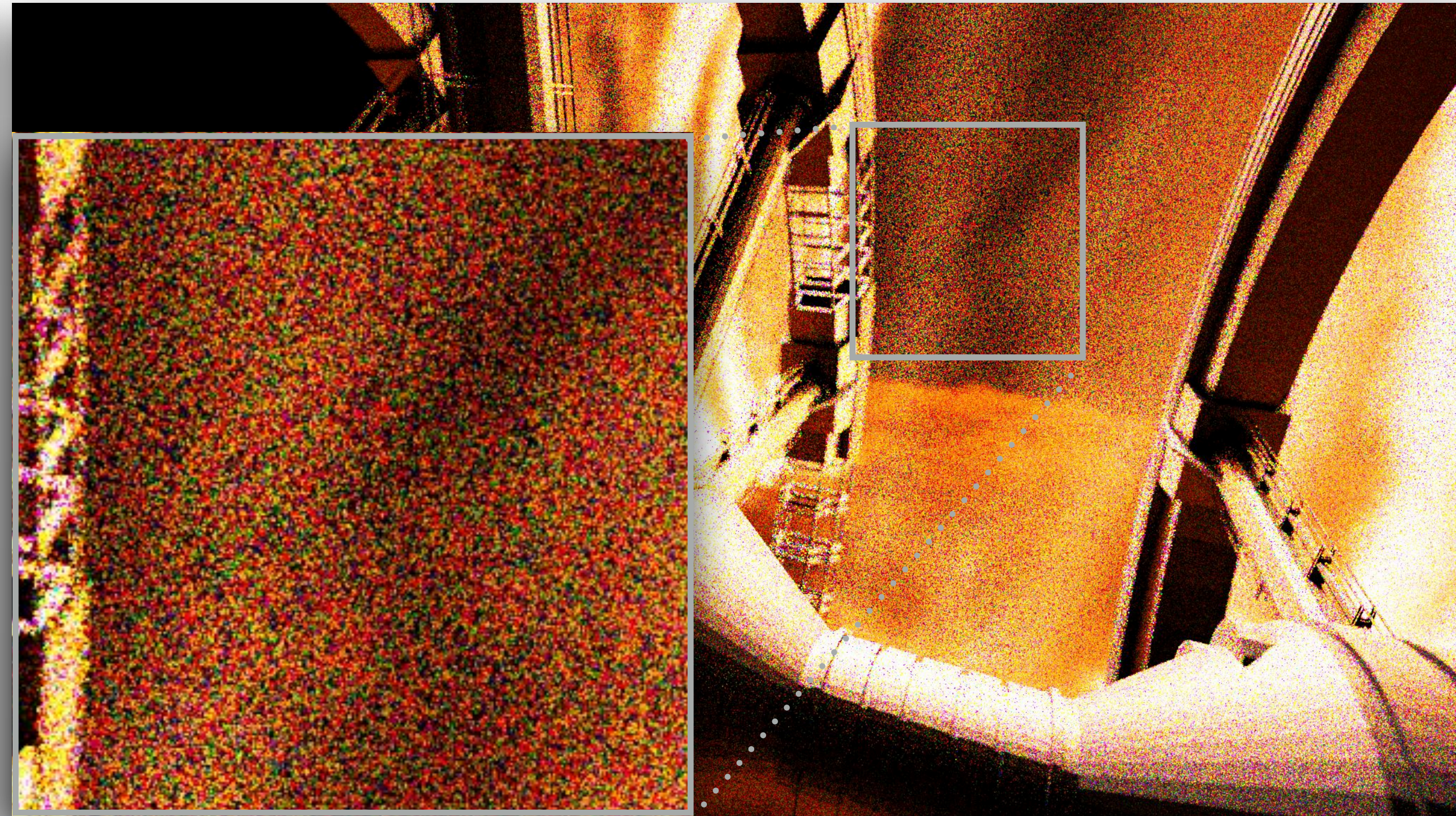
- Solar flare (30GB) - equal sample - 128spp



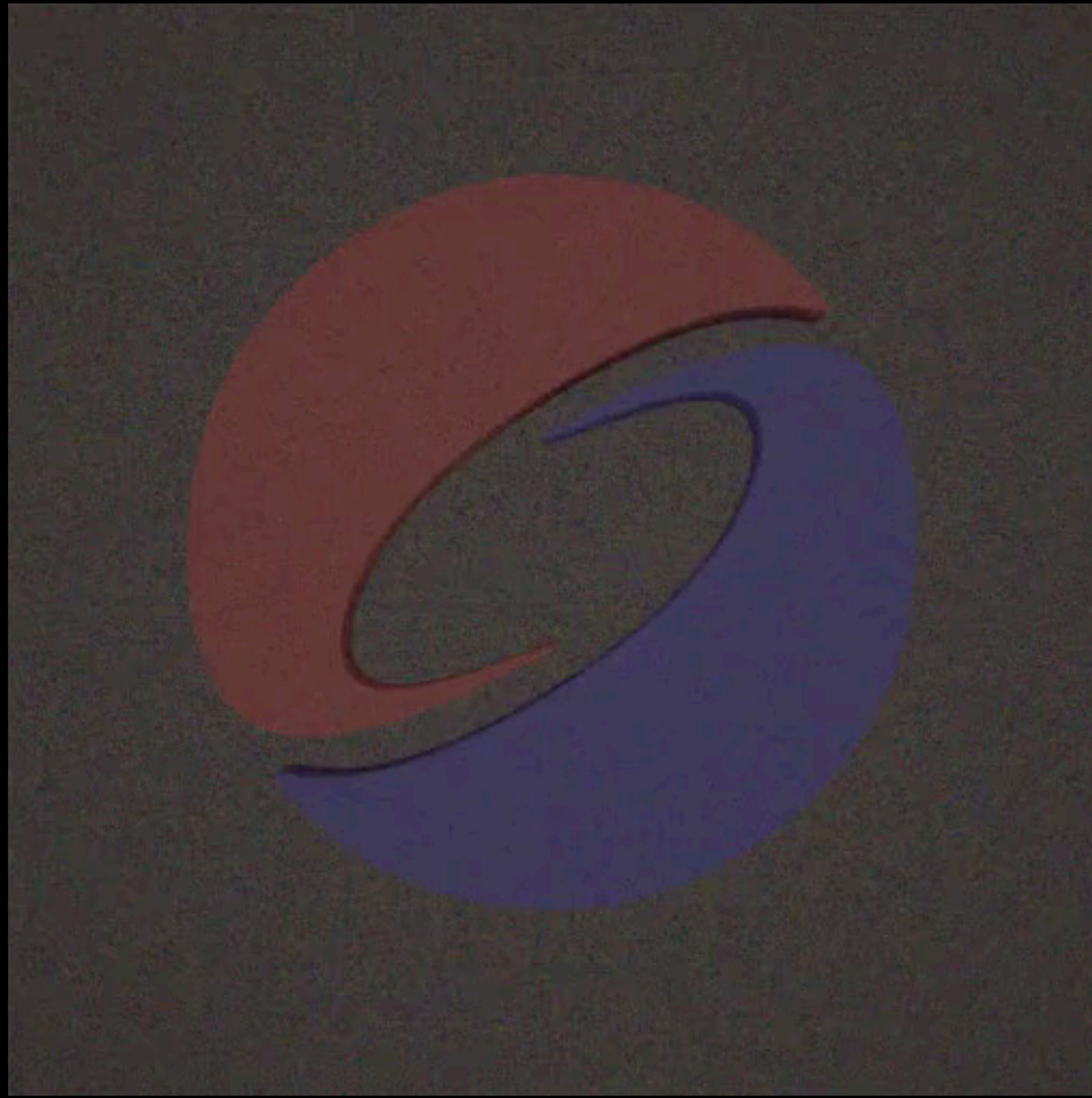
Overview



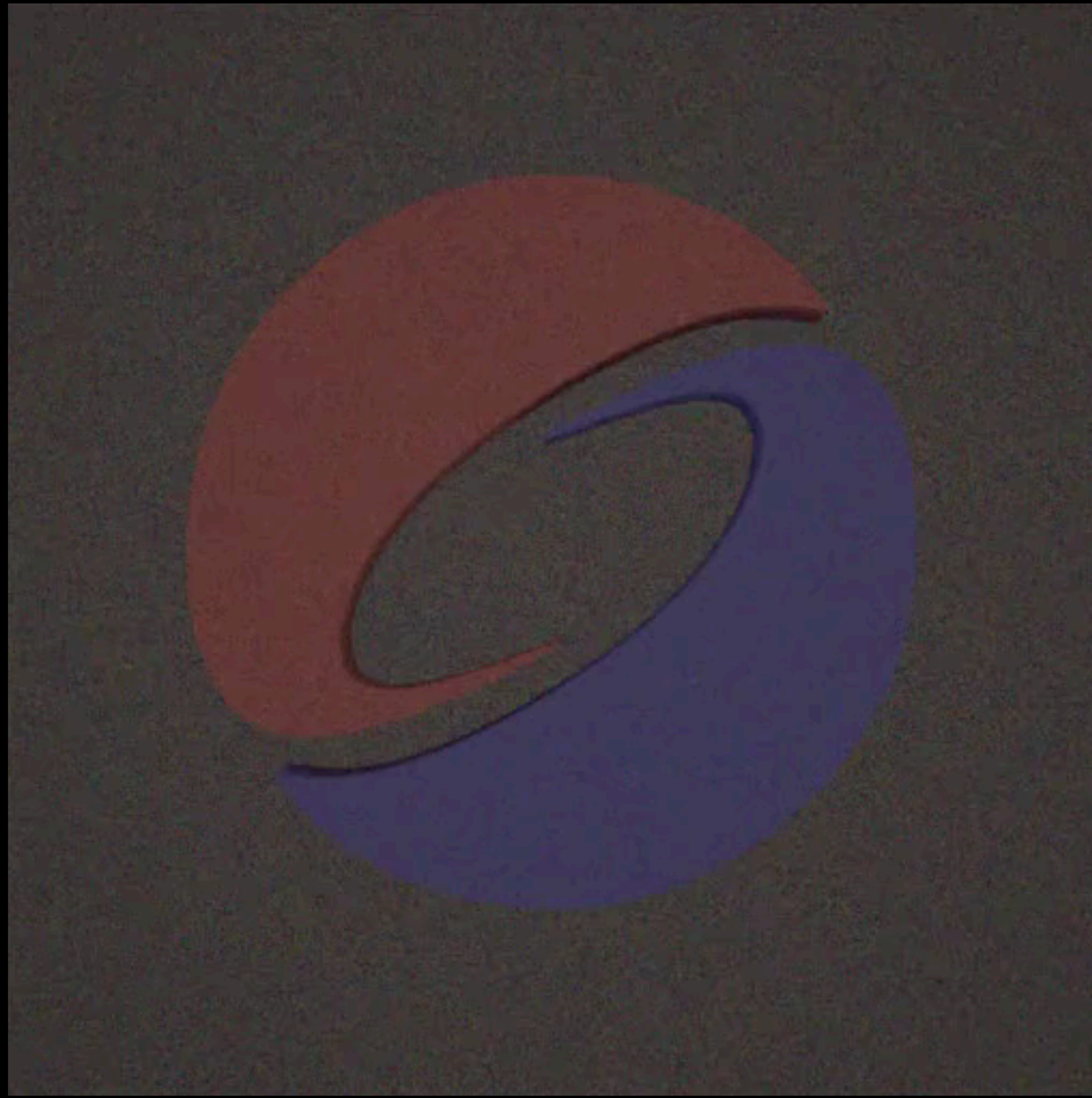
FNEE - RMSE 36.7 - 11.2 core hours



NEE - RMSE 52.6 - 7.5 core hours
RMSE 36.7 ~ 15 core hours

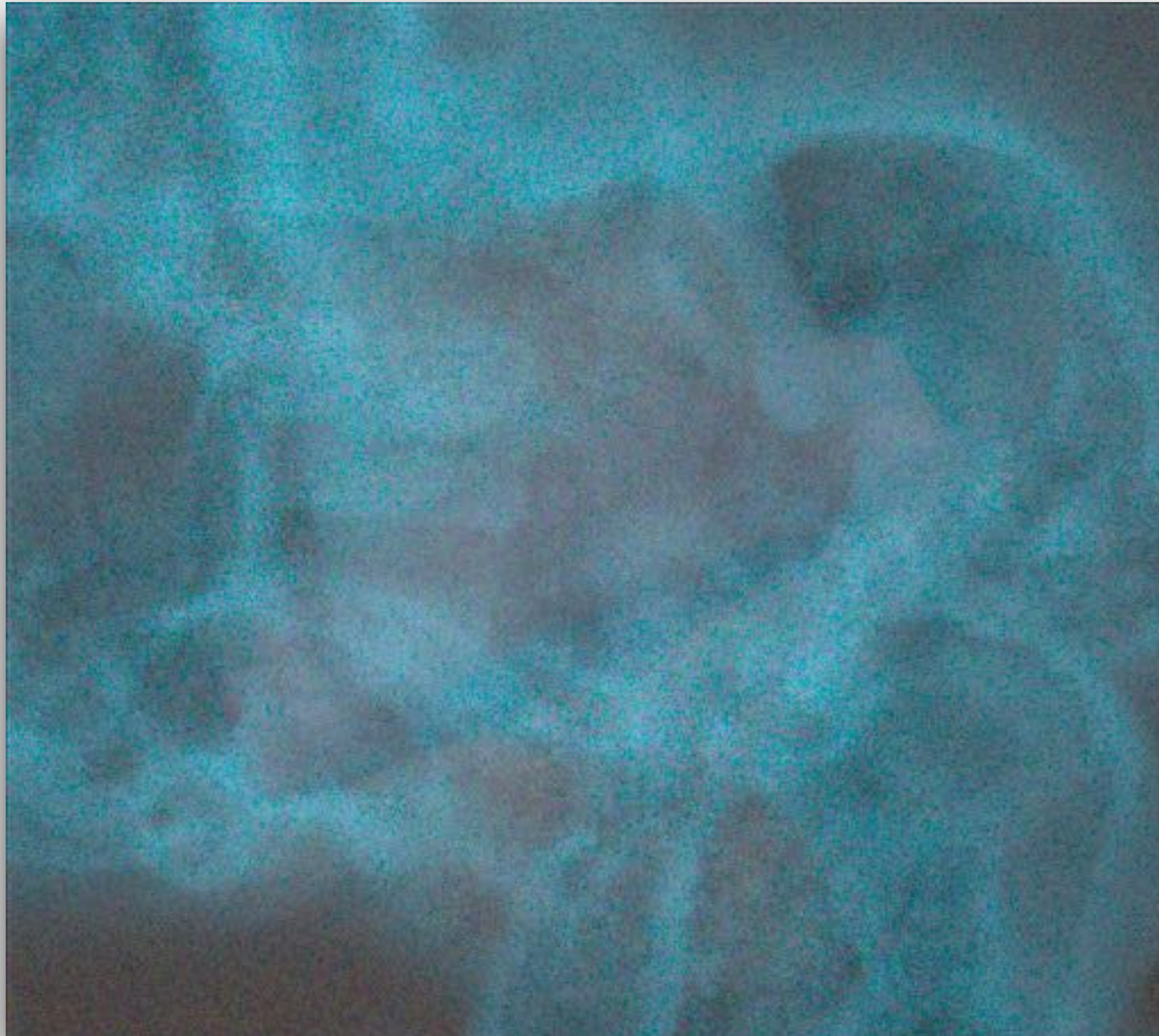


FNEE

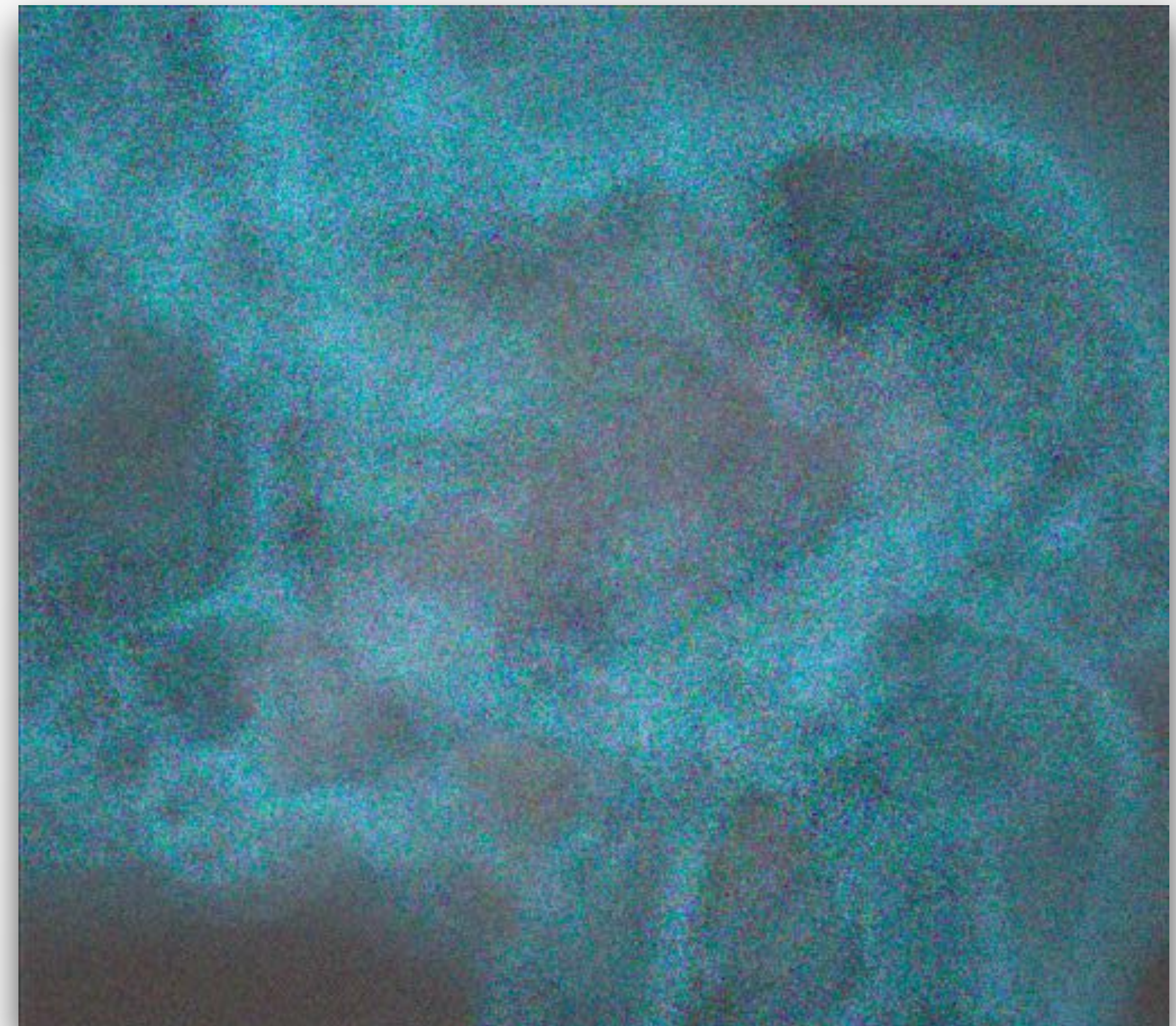


NEE

Results - Equal Time 10min



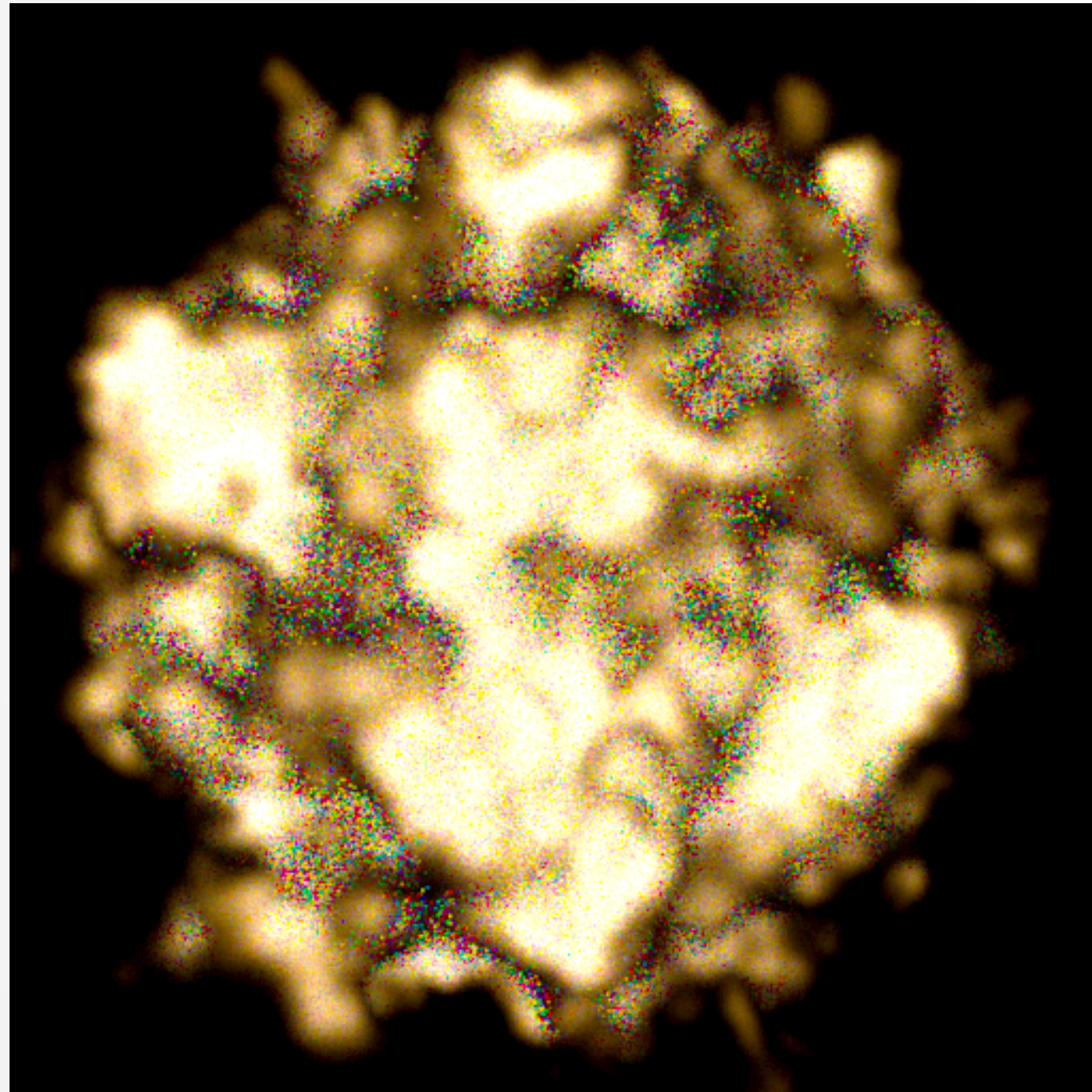
FNEE - RMSE 0.05 - 134spp



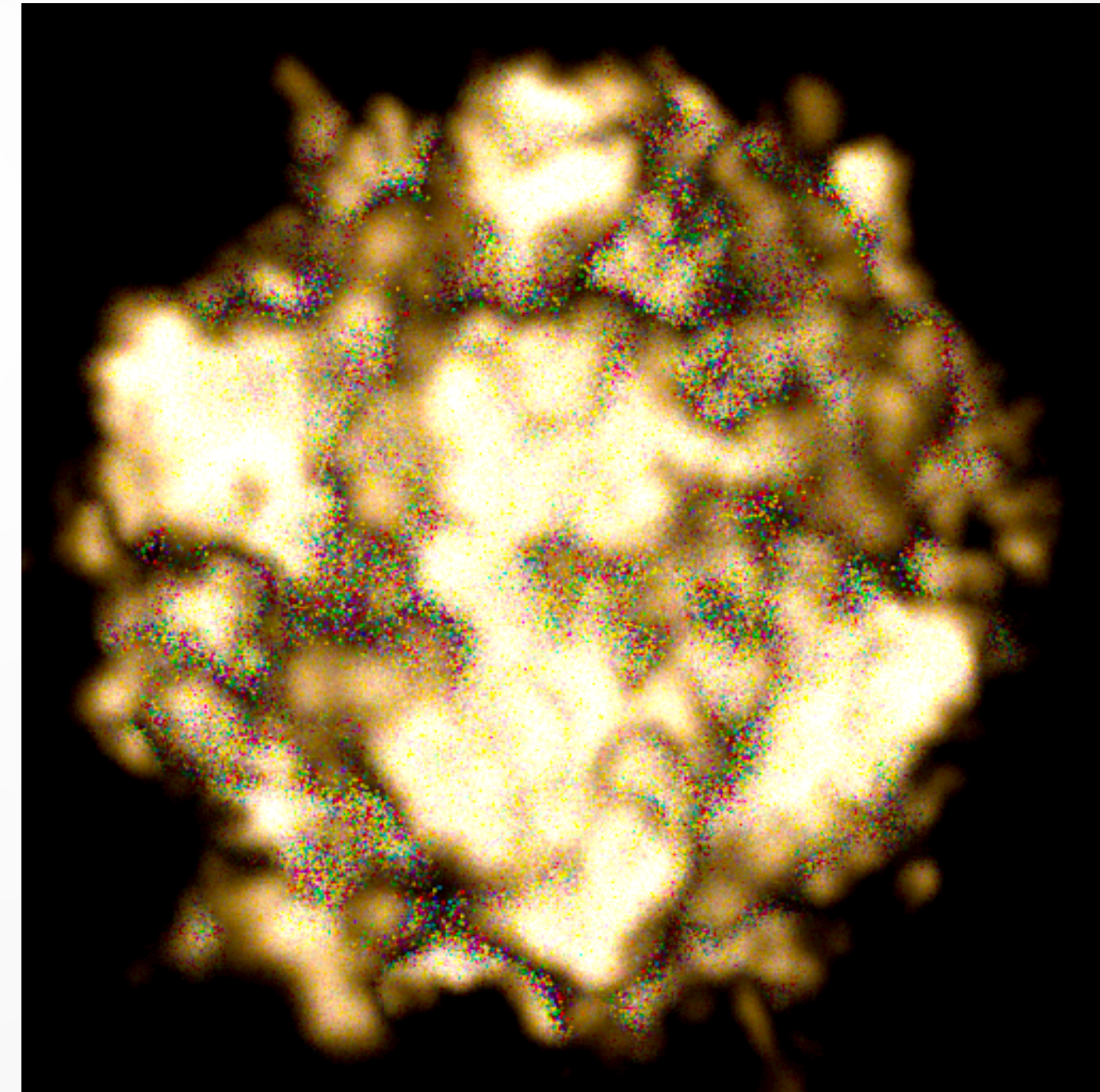
NEE - RMSE 0.11 - 174spp

Limitations and Future Work

- Line integration does not improve forward sampling for dense volumes



line integration



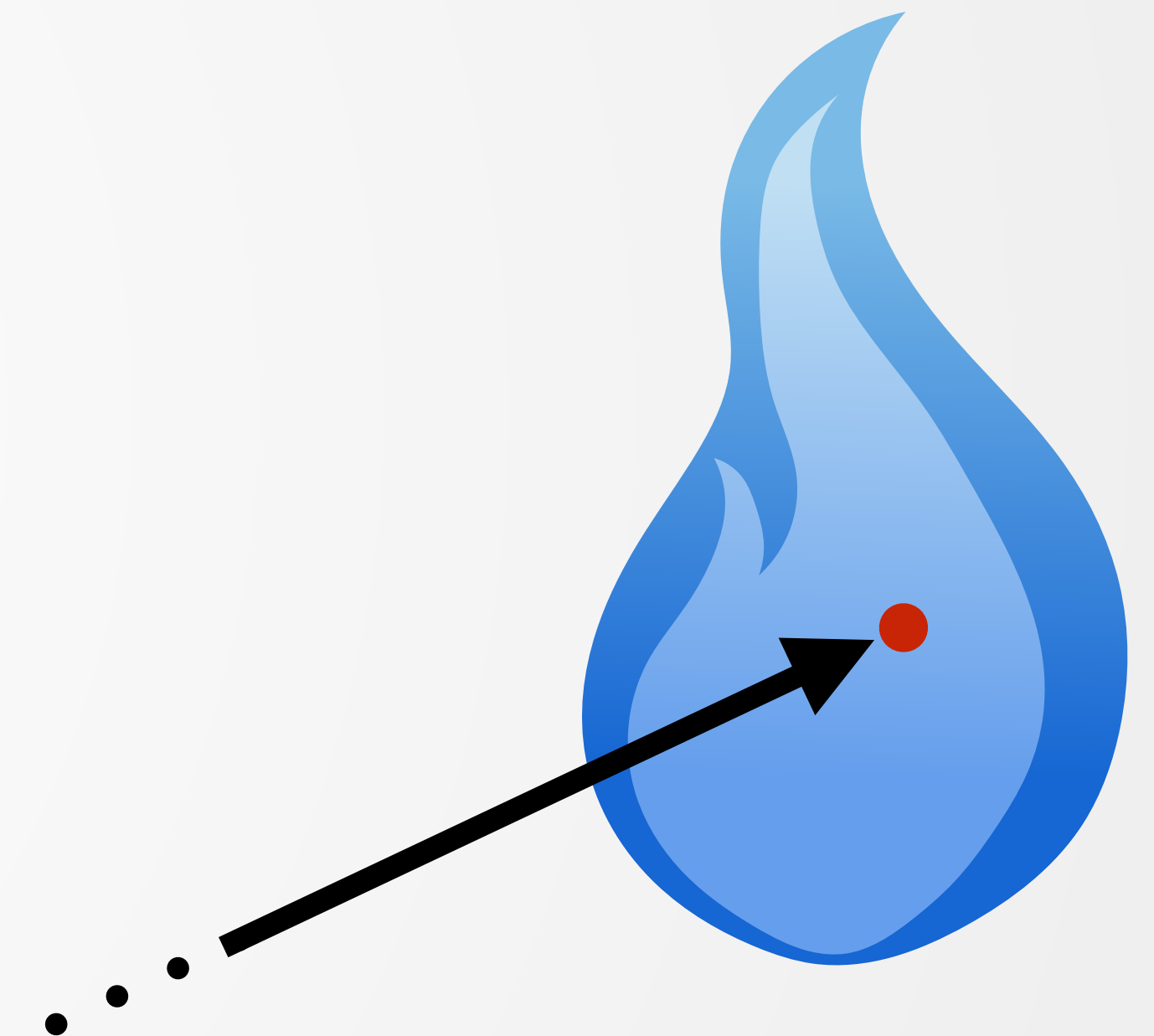
point integration

Limitations and Future Work

- Line integration does not improve forward sampling for dense volumes
- Extension to more rendering algorithms
- Combination with delta/residual tracking

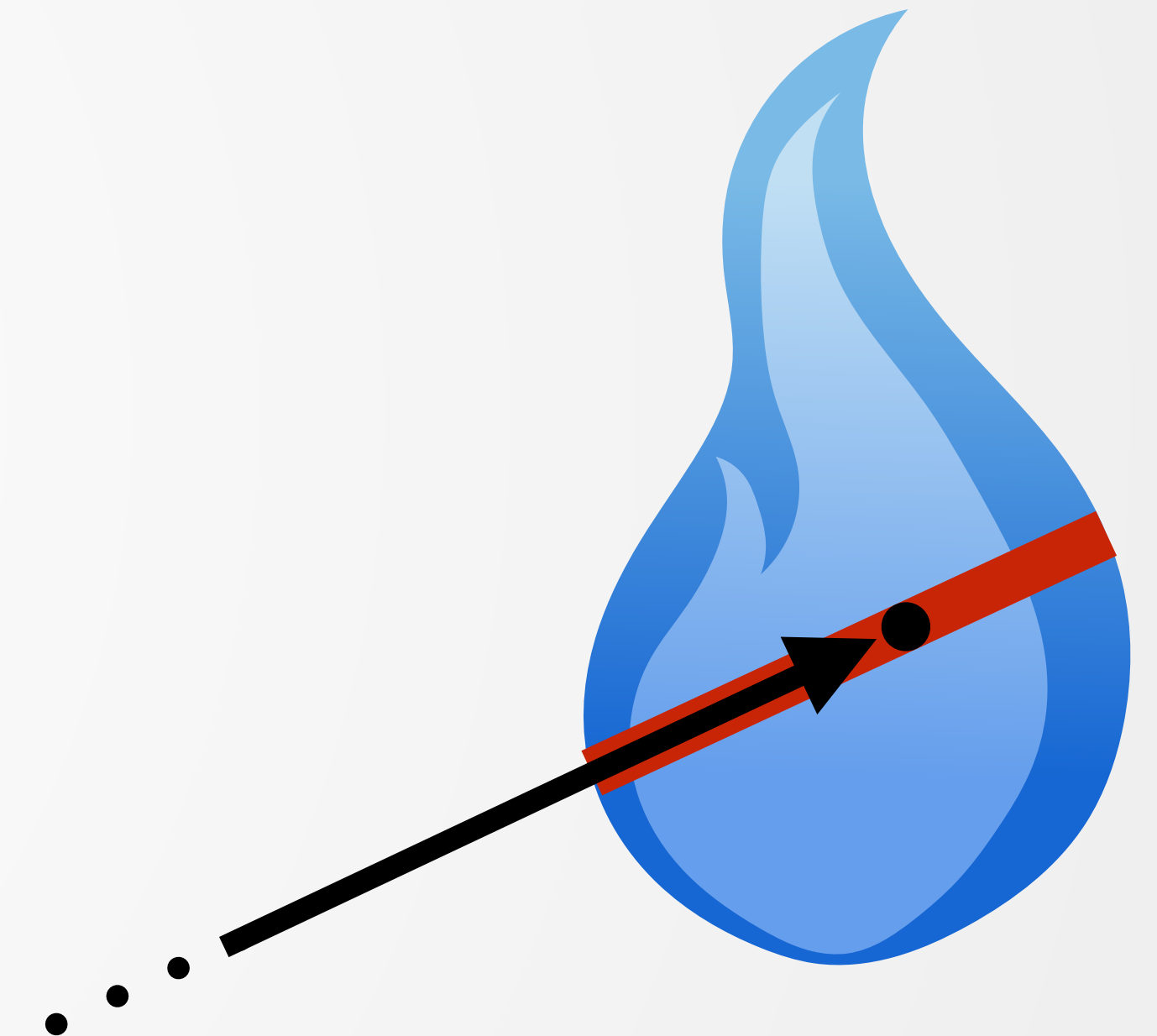
Conclusion

	dense	thin	MIS of forward & NEE
point integration	✓	✗	
deterministic			
line integration + NEE			
line integration + FNEE			



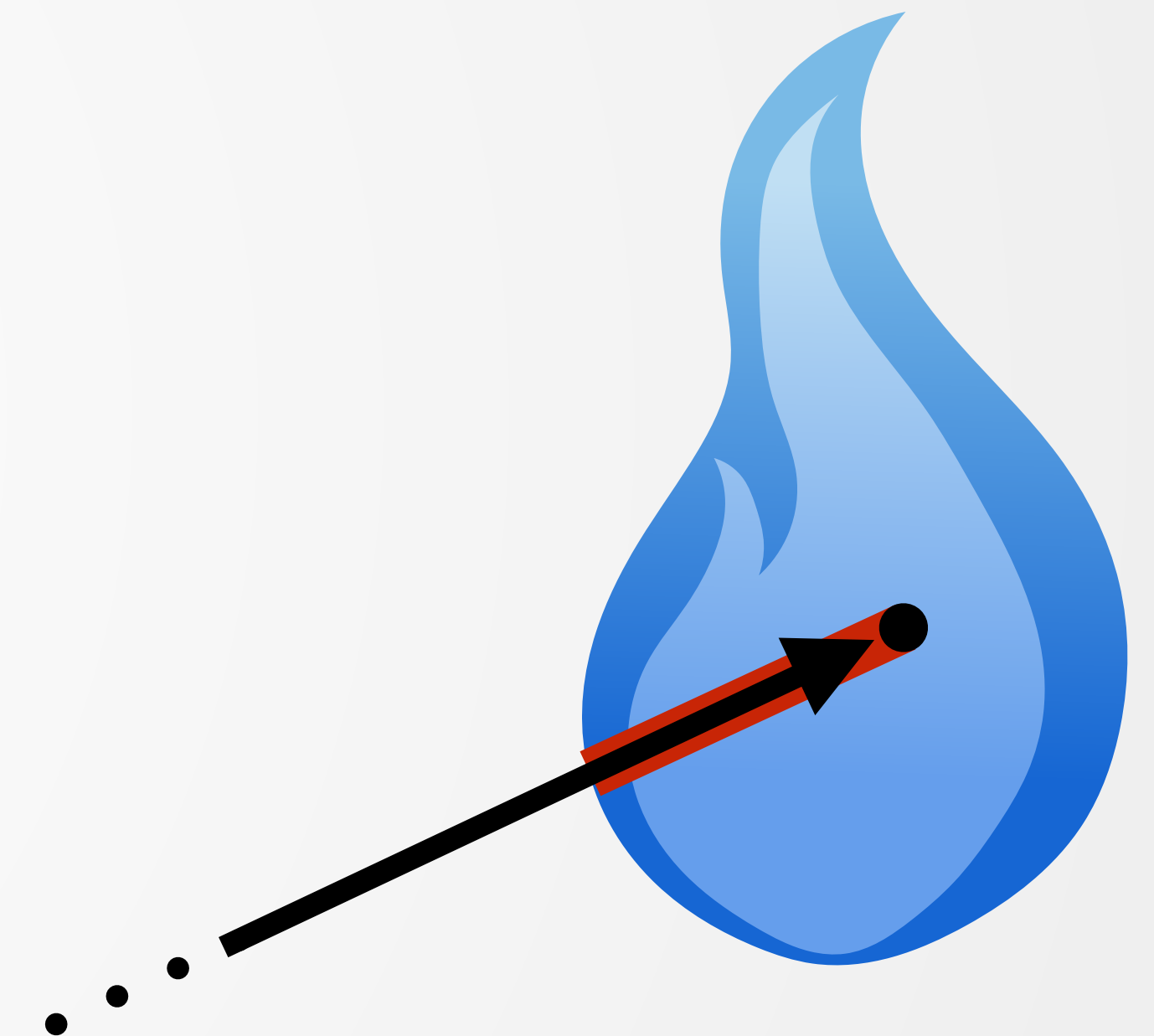
Conclusion

	dense	thin	MIS of forward & NEE
point integration	✓	✗	
deterministic	✗	✓	
line integration + NEE			
line integration + FNEE			



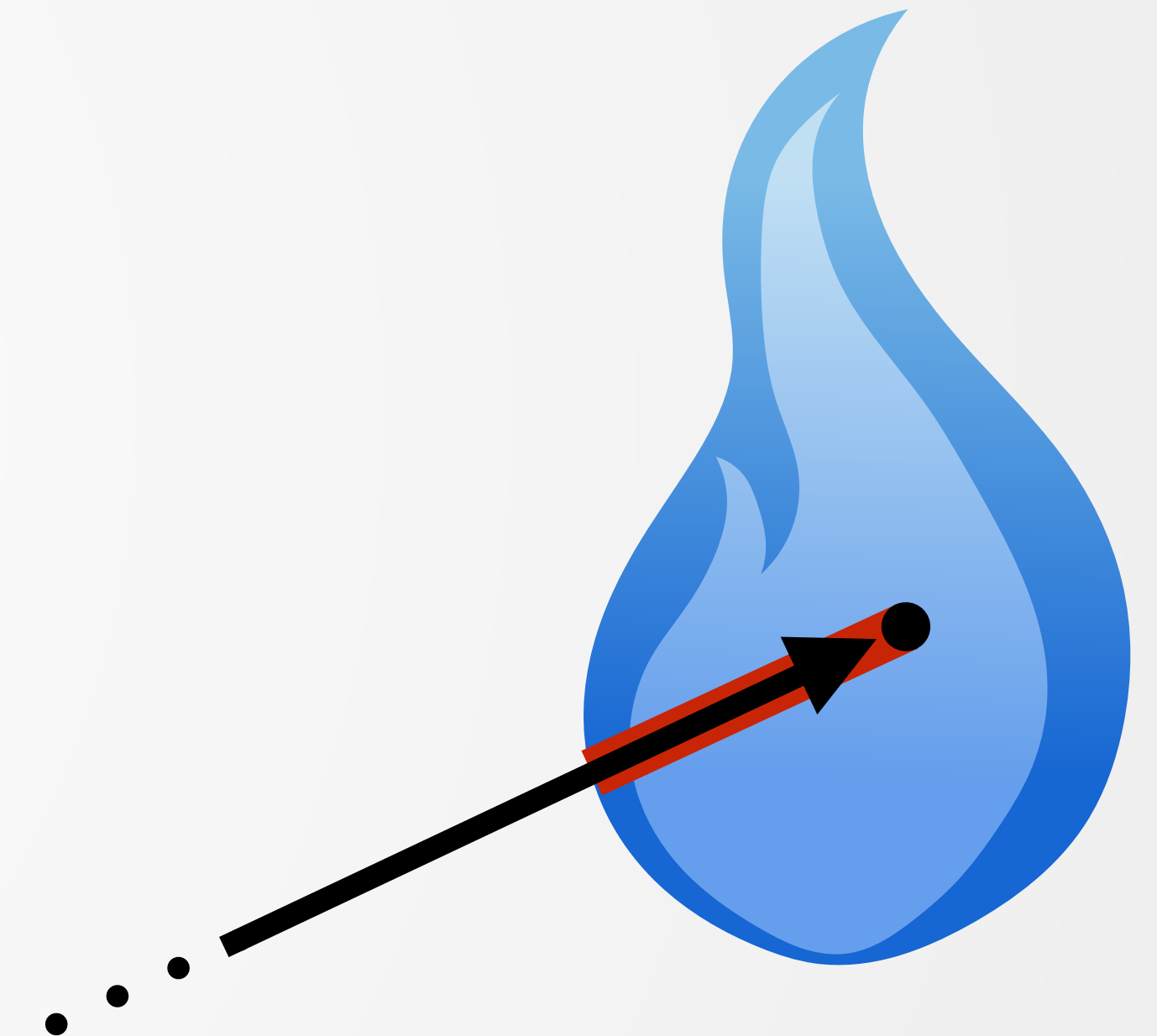
Conclusion

	dense	thin	MIS of forward & NEE
point integration	<input checked="" type="checkbox"/>	<input type="checkbox"/>	
deterministic	<input type="checkbox"/>	<input checked="" type="checkbox"/>	
line integration + NEE	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>	
line integration + FNEE			



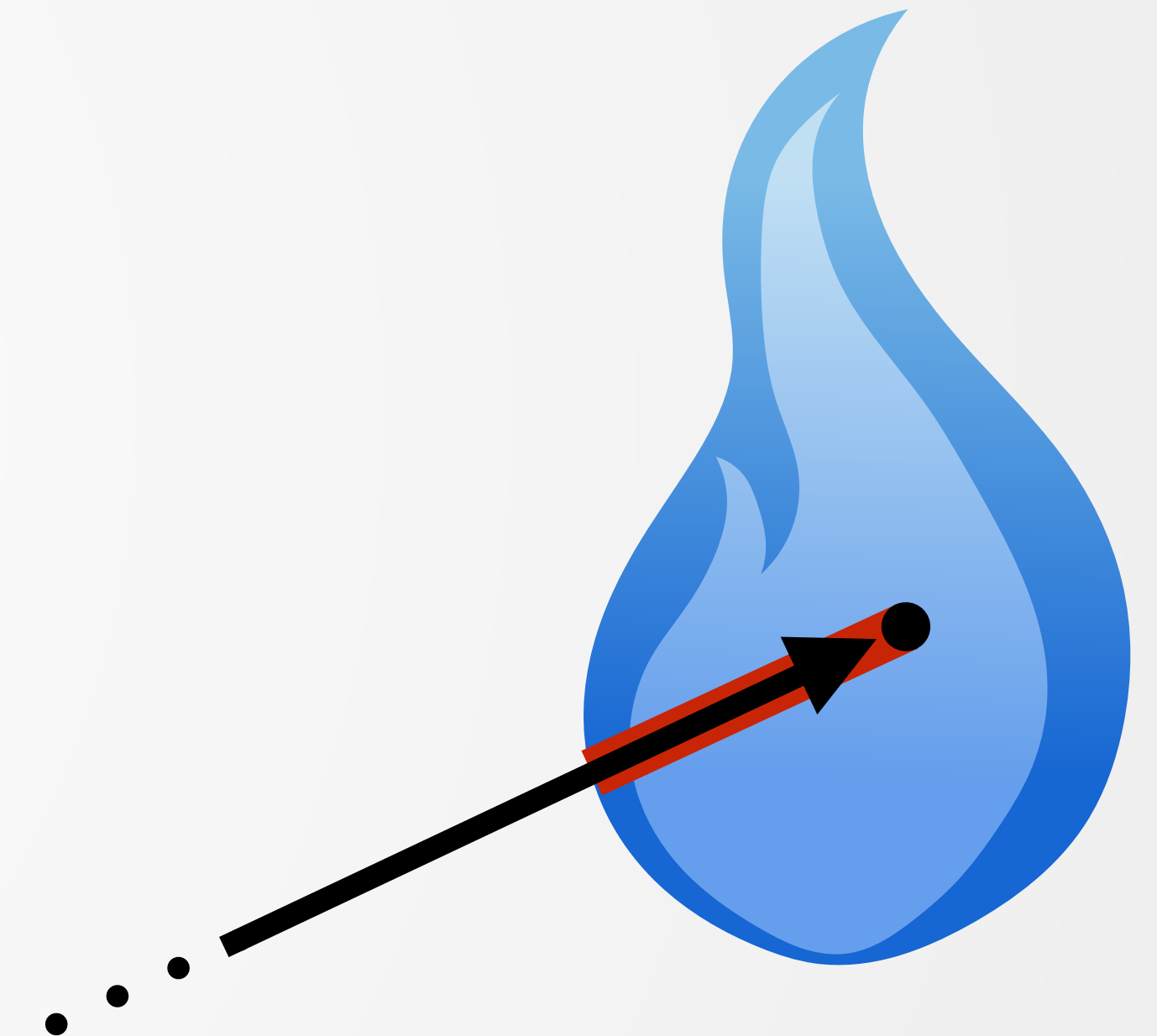
Conclusion

	dense	thin	MIS of forward & NEE
point integration	✓	✗	✓
deterministic	✗	✓	✗
line integration + NEE	✓	✓	✗
line integration + FNEE			



Conclusion

	dense	thin	MIS of forward & NEE
point integration	✓	✗	✓
deterministic	✗	✓	✗
line integration + NEE	✓	✓	✗
line integration + FNEE	✓	✓	✓



Acknowledgements

- Many thanks to Luca Fascione,
Tomas Davidovic and Marc Droske



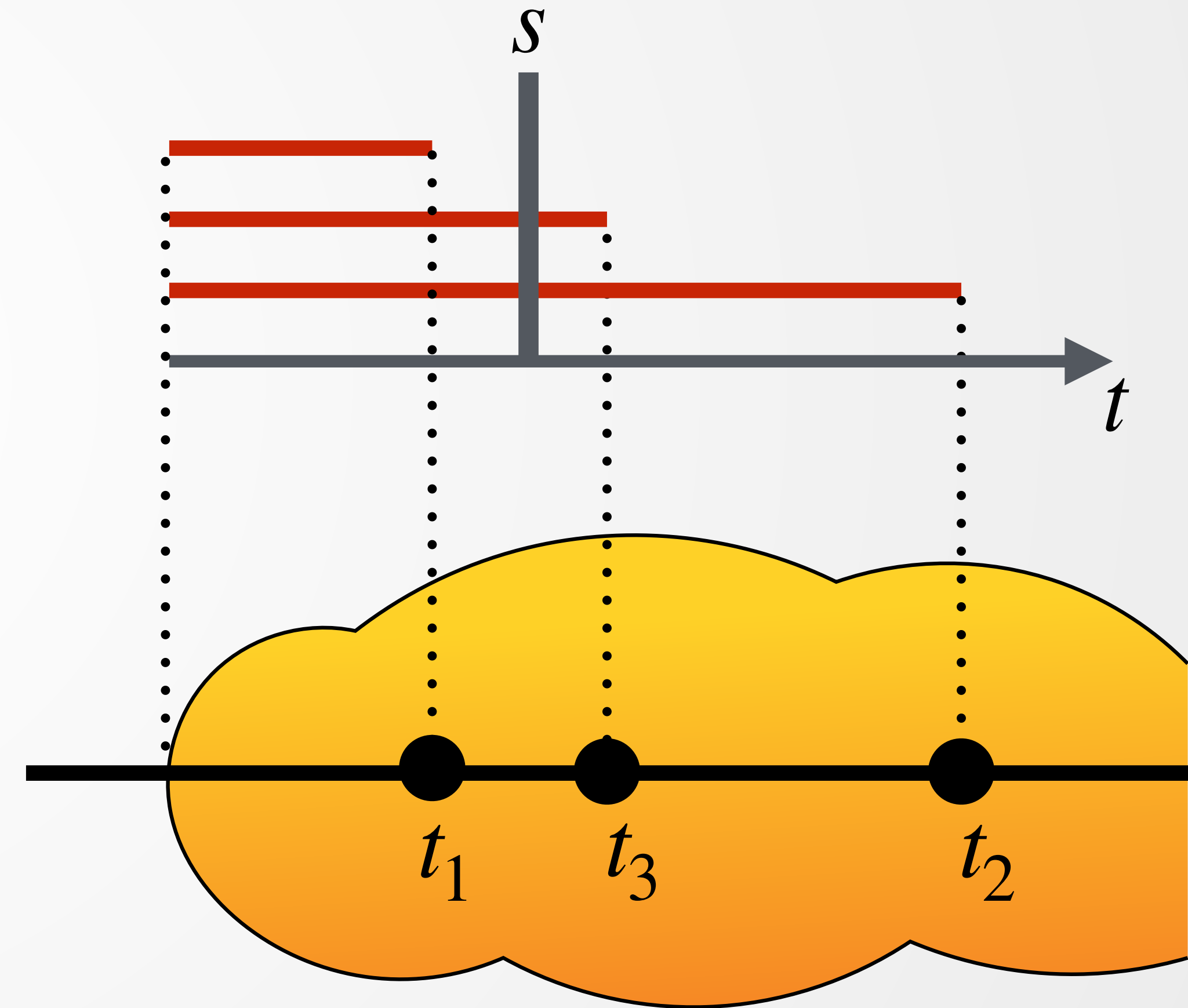
Thank You
for your Attention!

Backup / Trash

Weight Function

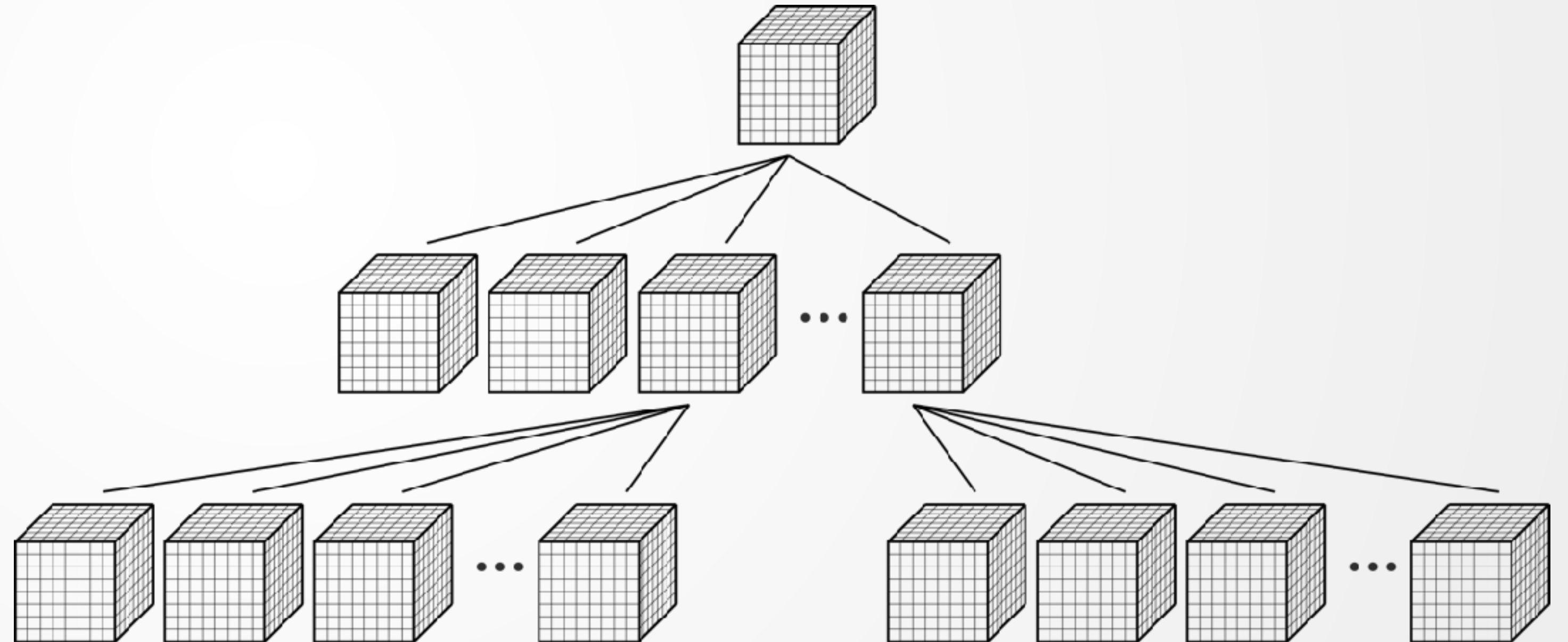
- If we use transmittance sampling

$$\int_0^\infty \tau(t) L_e(t) dt \approx \frac{1}{N} \sum_{i=1}^N \int_0^{t_i} L_e(s) ds$$



Volume Representation

- Multiresolution Grid
- Density and temperature per voxel
- FNEE always at 64^3

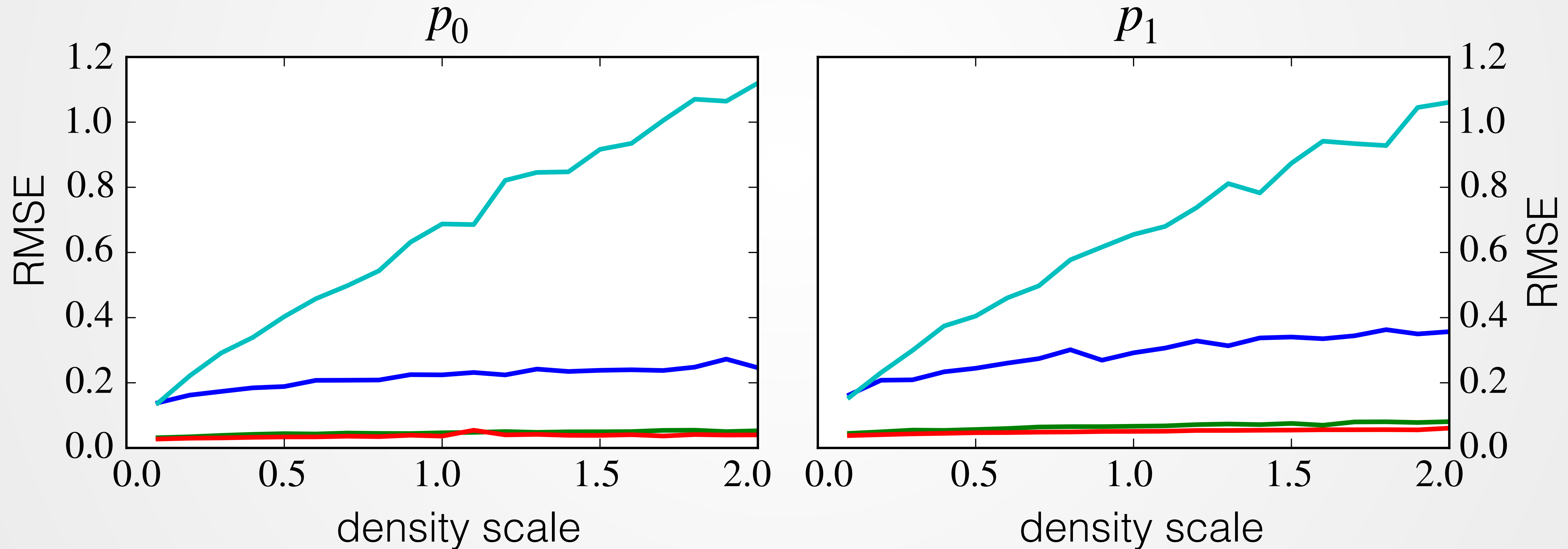


FNEE Test

- NEE
- FNEE 4096^3
- FNEE 512^3
- FNEE 64^3



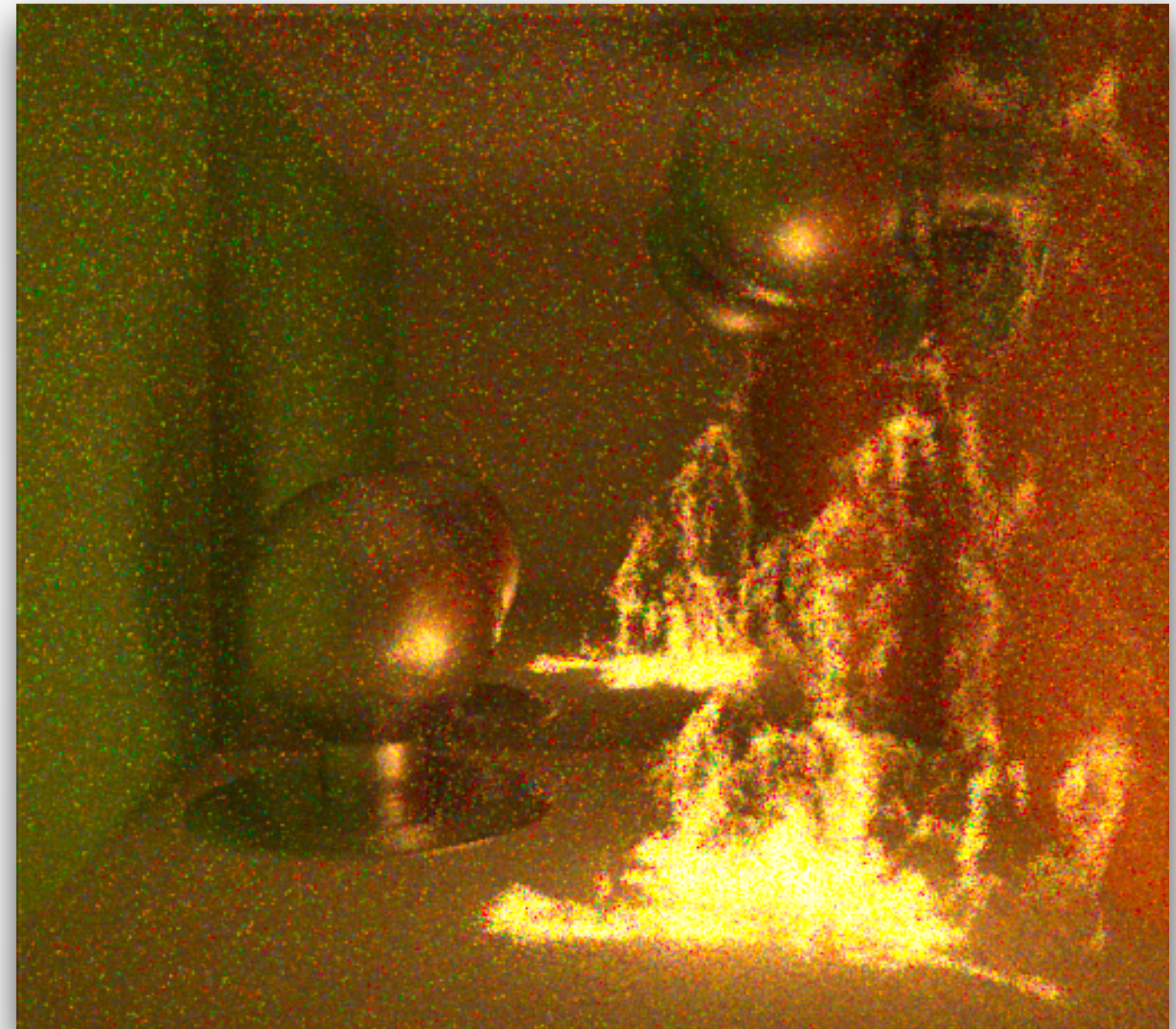
- Equal-time RMSE different densities



Results - Equal Time 15min



FNEE - RMSE 0.13 - 47spp



NEE - RMSE 0.21 - 70spp

Conclusion

- Line Integration robustly improves efficiency for thin emissive media
- FNEE allows MIS and samples transmittance which is beneficial for dense emissive media
- Together Line Integration and FNEE can efficiently render a very wide range of emissive heterogeneous media

